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STRUCTURAL BEHAVIOR OF PRESSURE-STABILIZED ARCHES

by
Earl C. Steeves

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UNITED STATES ARMY
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NATICK, MASSACHUSETTS 01760



Aero-Mechanical Engineering Laboratory

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correlations establish the usefulness of the theory was a design tool. ←

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PREFACE

This work was carried out as a part of an In-House Laboratory Independent Research project entitled, "Investigation of the Strength and Stability Characteristics of Pressurized Rib Structures." This work was initiated in response to the findings of a systems analysis which identified the pressurized rib concept as being the most promising structural alternative for meeting the Army requirement for lightweight highly mobile tentage. As is indicated by the references cited in this report, two previous reports describing a similar investigation of pressure-stabilized beams have been published. In the reference citation the organizations "US Army Natick Laboratories" and "US Army Natick Development Center" refer to the organization now called the "US Army Natick Research and Development Command". The author wishes to express his thanks to Colette Klarman, formerly of the Data Analysis Office, for her effort in writing the computer program for carrying out the solution of the equations developed in this report and for plotting the theoretical and experimental results.

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THE STRUCTURAL BEHAVIOR OF PRESSURE-STABILIZED ARCHES

INTRODUCTION

The use of pressure-stabilized structures for Army field shelters has been the subject of considerable attention over the past decade with emphasis on the single-wall and double-wall type of shelter, as indicated by references 1 and 2. A systems analysis of Army field shelter needs for the 1985 time frame revealed that the requirements for lightweight tentage of low package bulk and with minimum setup and disassembly times might be most effectively achieved with a tent having a frame of highly pressurized (compared with present air-supported tents) structural elements supporting a lightweight fabric barrier, as illustrated in Figure 1. As a result of the potential indicated by the systems analysis an investigation of the structural behavior of pressure-stabilized structural elements was begun with the objective being to develop a design capability which would permit the concept to be evaluated for use in Army tentage. The results of a theoretical and experimental study of the behavior of pressure-stabilized beams under load are presented in references 3 and 4. However, as is illustrated in Figure 1, pressure-stabilized arches will be used in this concept for tentage and thus design data for these structural elements are required. Such design data are presented in this report in the form of a theory for the deformation of pressure-stabilized arches together with experimental confirmation of the prediction made with this theory.

A review of previous work on the behavior of pressure-stabilized structural elements is given in references 1 and 2. The only additional work known to the author of interest relative to the behavior of arches is the theoretical study of the stability of pressure-stabilized rings given in reference 5. This work dealt entirely with the stability problem for the complete ring and these results were not used in the present work because it was believed that a more consistent theory would be obtained by adopting the ideas of superposition of small displacements on larger ones as was done for the pressure-stabilized beam problem in reference 3.

1. Dietz, A. E., R. B. Proffitt, R. S. Chabot, E. L. Moak, and C. J. Monego; Wind Tunnel Tests and Analyses for Ground-Mounted, Air-Supported Structures (revised); US Army Natick Laboratories Technical Report 70-7-GP; 1969.
2. Dietz, A. E., R. B. Proffitt, R. S. Chabot, and E. L. Moak; Design Manual for Ground-Mounted Air-Supported Structures (Single-and Double-Wall) (revised); US Army Natick Laboratories Technical Report 69-59-GP; 1969. A 76107
3. Steeves, Earl C.; A Linear Analysis of the Deformation of Pressure Stabilized Beams; US Army Natick Laboratories Technical Report 75-47-AMEL; 1975. 8 261 7
4. Steeves, Earl C.; Behavior of Pressure Stabilized Beams Under Load; US Army Natick Development Center Technical Report 75-82-AMEL; 1975. 1 024 - 1
5. Weeks, G. E.; Buckling of a Pressurized Toroidal Ring Under Uniform External Loading; NASA TN D-4124; 1967.

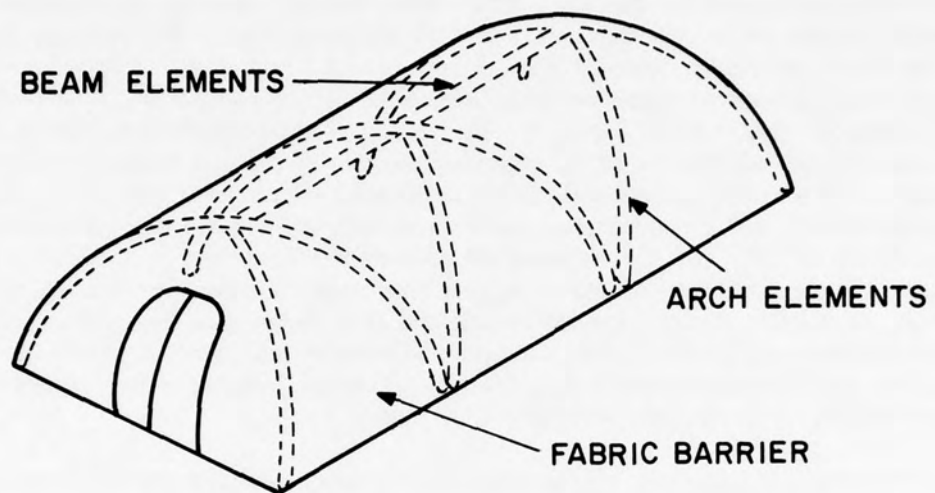


Figure 1. Tent Concept Using Pressure Stabilized Structural Elements

Included in this report is the derivation of the equations describing the behavior of pressure-stabilized arches under loads both in the plane of the arch and normal to the plane of the arch. The solution of the equations for the in-plane problem are presented along with a computer program to carry out this solution numerically. The experimental study is also described, including the loading tests on arches and the measurement of the elastic properties of the fabric from which the arches were made. The results of this experimental study are compared with the predictions of the theory.

THEORETICAL ANALYSIS

This section of the report is concerned with development of the theory to predict the behavior of pressure-stabilized arches under load. We begin with a derivation of the governing equations for deformation in the plane of the arch and normal to the plane of the arch. These sets of equations are uncoupled and the solution to the in-plane set is obtained here and a computer program to carry out the solution numerically is described.

Derivation of Governing Equations

Fundamental Principles

We consider a surface in the form of a circular torus with a circular cross-section, as shown on Figure 2. Points on the surface are located by specification of the coordinates θ_1 and θ_2 , and the differential arc element and radii of curvature on the surface are given by

$$ds^2 = [R + a\cos(\theta_1)]^2 d\theta_2^2 + a^2 d\theta_1^2 \quad (1a)$$

$$1/R_1 = 1/a \quad (1b)$$

$$1/R_2 = \cos(\theta_1)/[a\cos(\theta_1) + R] \quad (1c)$$

In equation (1), a is the cross-section radius and R is the radius of the torus centerline. Assuming that the membrane state of stress is present, the principle of minimum potential energy is written as

$$\delta \int_A (1/2)[N_{11}\epsilon_{11} + N_{22}\epsilon_{22} + 2N_{12}\epsilon_{12} - 2Pv_3] dA = 0 \quad (2)$$

Where N_{ij} , ϵ_{ij} , P , and V_3 are, respectively, the stress resultants, the surface strains, the inflation pressure, and the normal displacement. The surface strains can be expressed in terms of the displacements and their derivatives for the toroidal coordinates as:

$$\epsilon_{11} = (1/a)[v_{1,1} + v_3 + (1/2a)(-v_{3,1} + v_1)^2] \quad (2a)$$

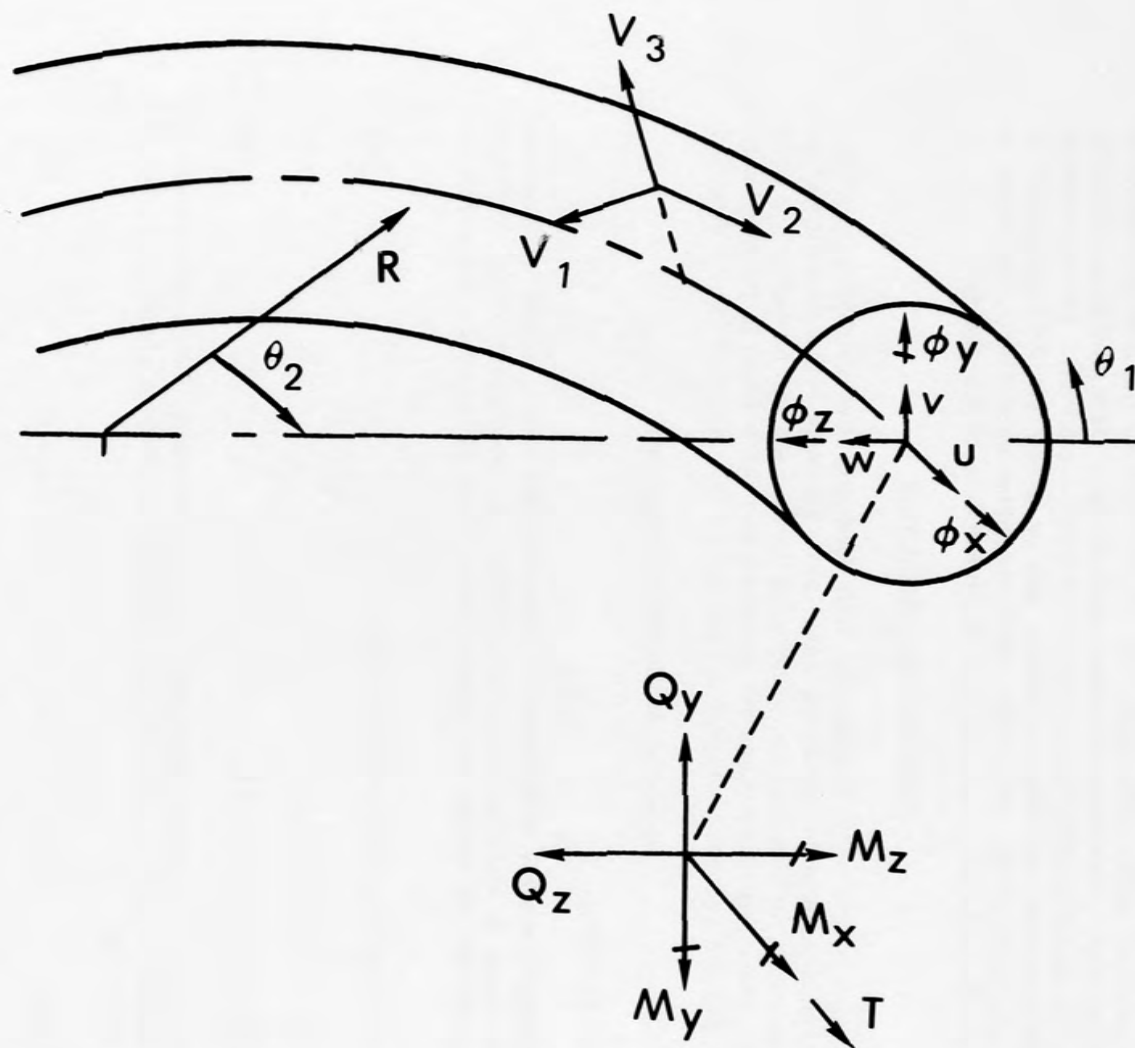


FIGURE 2. COORDINATES, DISPLACEMENT COMPONENTS AND INTERNAL FORCES

$$\epsilon_{22} = (1/\alpha_2)[v_{2,2} - v_1 \sin(\theta_1) + v_3 \cos(\theta_1) + (1/2\alpha_2)(-v_{3,2} + v_2 \cos(\theta_1))^2] \quad (2b)$$

$$\epsilon_{12} = (1/2\alpha_2)[(R/a + \cos(\theta_1))v_{2,1} + v_{1,2} + v_2 \sin(\theta_1) + (1/a)(-v_{3,1} + v_1)(-v_{3,2} + v_2 \cos(\theta_1))] \quad (2c)$$

In equations (2) $\alpha_2 = (R/a + \cos(\theta_1))$. To complete the basis for the theory we specify an orthotropic law relating the stress resultants and the surface strains as

$$N_{11} = C_{11}\epsilon_{11} + C_{12}\epsilon_{22} \quad (3a)$$

$$N_{22} = C_{12}\epsilon_{11} + C_{22}\epsilon_{22} \quad (3b)$$

$$N_{12} = 2C_{33}\epsilon_{12} \quad (3c)$$

It has been assumed in writing equations (3) that the lines of orthotropic symmetry are parallel to the coordinate lines.

Energy Principle for Deformation about Pressurized State

The derivation now proceeds identically with that for pressure-stabilized beams in reference 3 by assuming that the displacements v_i can be expressed as the sum of displacements w_i due to pressurization and u_i due to applied load as

$$v_i = w_i + u_i \quad (4)$$

Substitution of this displacement assumption into the strain-displacement relation (2) yields

$$\epsilon_{ij} = \epsilon_{ij}^{\circ} + \epsilon'_{ij} + \epsilon''_{ij} \quad (5)$$

$$i = 1, 2$$

$$j = 1, 2$$

These supplementary strain measures are defined in terms of the displacements w_i and u_i as

$$\begin{aligned} \epsilon_{11}^{\circ} &= (1/a)[w_{1,1} + w_3 + (1/2a)(-w_{3,1} + w_1)^2] \\ \epsilon'_{11} &= (1/a)[u_{1,1} + u_3 + (1/a)(-w_{3,1} + w_1)(-u_{3,1} + u_1)] \\ \epsilon''_{11} &= (1/2a^2)(-u_{3,1} + u_1)^2 \\ \epsilon_{22}^{\circ} &= (1/\alpha_2)[w_{2,2} - w_1 \sin(\theta_1) + w_3 \cos(\theta_1) + (1/2\alpha_2)(-w_{3,2} + w_2 \cos(\theta_1))^2] \end{aligned} \quad (6)$$

$$\begin{aligned}
\epsilon'_{22} &= (1/\alpha_2)[u_{2,2} - u_1 \sin(\theta_1) + u_3 \cos(\theta_1) + \\
&\quad (1/\alpha_2)(-w_{3,2} + w_2 \cos(\theta_1))(-u_{3,2} + u_2 \cos(\theta_1))] \\
\epsilon''_{22} &= (1/2\alpha_2^2)[-u_{3,2} + u_2 \cos(\theta_1)]^2 \\
\epsilon^\circ_{12} &= (1/2\alpha_2)[(R/a + \cos(\theta_1))w_{2,1} + w_{1,2} + w_2 \sin(\theta_1) + \\
&\quad (1/a)(-w_{3,1} + w_1)(-w_{3,2} + w_2 \cos(\theta_1))] \\
\epsilon'_{12} &= (1/2\alpha_2)[(R/a + \cos(\theta_1))u_{2,1} + u_{1,2} + u_2 \sin(\theta_1) + \\
&\quad (1/a)(-w_{3,1} + w_1)(-u_{3,2} + u_2 \cos(\theta_1)) + \\
&\quad (1/a)(-u_{3,1} + u_1)(-w_{3,2} + w_2 \cos(\theta_1))] \\
\epsilon''_{12} &= (1/2\alpha_2)[-u_{3,1} + u_1] [-u_{3,2} + u_2 \cos(\theta_1)]
\end{aligned} \tag{6}$$

The ϵ°_{ij} are the complete nonlinear strain measures for the pressurized state expressed in terms of the displacements w_i . The ϵ'_{ij} are the linear strain measures in the displacements u_i due to applied load and also contain the terms coupling the pressurized state and that due to applied load. The ϵ''_{ij} are the nonlinear terms of the strains due to applied load and they can be interpreted as the products of the rotations of a surface line element about the i th and j th axes. Corresponding to these supplementary strain measures is a set of stress measures which represent the total stress components as

$$\begin{aligned}
N_{ij} &= N^\circ_{ij} + N'_{ij} + N''_{ij} \\
i &= 1, 2 \\
j &= 1, 2
\end{aligned} \tag{7}$$

Expressions for the stress measures N°_{ij} , N'_{ij} , and N''_{ij} in terms of the strain measures ϵ°_{ij} , ϵ'_{ij} , and ϵ''_{ij} are found by substitution of equation (5) into the stress strain law (3) which yields

$$\begin{aligned}
N^\circ_{11} &= C_{11}\epsilon^\circ_{11} + C_{12}\epsilon^\circ_{22} \\
N'_{11} &= C_{11}\epsilon'_{11} + C_{12}\epsilon'_{22} \\
N''_{11} &= C_{11}\epsilon''_{11} + C_{12}\epsilon''_{22} \\
N^\circ_{22} &= C_{12}\epsilon^\circ_{11} + C_{22}\epsilon^\circ_{22} \\
N'_{22} &= C_{12}\epsilon'_{11} + C_{22}\epsilon'_{22} \\
N''_{22} &= C_{12}\epsilon''_{11} + C_{22}\epsilon''_{22}
\end{aligned} \tag{8}$$

$$\begin{aligned}
N_{12}^{\circ} &= 2C_{33}\epsilon_{12}^{\circ} \\
N_{12}' &= 2C_{33}\epsilon_{12}' \\
N_{12}'' &= 2C_{33}\epsilon_{12}''
\end{aligned} \tag{8}$$

Substitution of equations (4), (5) and (7) into the energy principle (2) and retaining terms up to those quadratic in the displacement components u_i yields

$$\begin{aligned}
\delta \int_A 1/2 [& (\epsilon_{11}^{\circ} N_{11}^{\circ} + \epsilon_{22}^{\circ} N_{22}^{\circ} + 2\epsilon_{12}^{\circ} N_{12}^{\circ} - 2Pw_3) + 2(\epsilon_{11}' N_{11}^{\circ} + \epsilon_{22}' N_{22}^{\circ} + \\
& 2\epsilon_{12}' N_{12}^{\circ} - Pu_3) + (\epsilon_{11}' N_{11}' + \epsilon_{22}' N_{22}' + 2\epsilon_{12}' N_{12}' + 2\epsilon_{11}'' N_{11}^{\circ} + \\
& 2\epsilon_{22}'' N_{22}^{\circ} + 4\epsilon_{12}'' N_{12}^{\circ} - 2F_1 u_1 - 2F_2 u_2 - 2F_3 u_3)] dA = 0
\end{aligned} \tag{9}$$

In writing this relationship the work due to the applied forces F_i which do work only through the displacement components u_i ($i = 1, 3$) has been added, and the following identities which can be proven through the stress-strain law have been used

$$\begin{aligned}
\epsilon_{11}^{\circ} N_{11}' + \epsilon_{22}^{\circ} N_{22}' &= \epsilon_{11}' N_{11}^{\circ} + \epsilon_{22}' N_{22}^{\circ} \\
\epsilon_{12}^{\circ} N_{12}' &= \epsilon_{12}' N_{12}^{\circ} \\
\epsilon_{11}^{\circ} N_{11}'' + \epsilon_{22}^{\circ} N_{22}'' &= \epsilon_{11}'' N_{11}^{\circ} + \epsilon_{22}'' N_{22}^{\circ} \\
\epsilon_{12}^{\circ} N_{12}'' &= \epsilon_{12}'' N_{12}^{\circ}
\end{aligned} \tag{10}$$

To yield the governing equation for deformation about the pressurized state, which is described by the displacement components u_i , the variation in equation (9) must be interpreted so as to be carried out with respect to the components u_i . Since the expression inclosed in the first set of parenthesis in equation (9) is independent of the components u_i , its variation must vanish. Carrying out the variation of the expression in the second set of parenthesis and performing the required integration by parts, one finds that the coefficients of the variational displacements δu_i are the equilibrium equations governing the pressurized state which must vanish if the stress resultants N_{11}° , N_{22}° , and N_{12}° represent an equilibrium state. Taking these facts into account, the following is the energy principle for deformation about the pressurized state:

$$\begin{aligned}
\delta \int_A 1/2 (& \epsilon_{11}' N_{11}' + \epsilon_{22}' N_{22}' + 2\epsilon_{12}' N_{12}' + 2\epsilon_{11}'' N_{11}^{\circ} + 2\epsilon_{22}'' N_{22}^{\circ} + \\
& 4\epsilon_{12}'' N_{12}^{\circ} - 2F_1 u_1 - 2F_2 u_2 - 2F_3 u_3) dA = 0
\end{aligned} \tag{11}$$

Since the stresses N_{11}° , N_{22}° , and N_{12}° due to pressurization are considered known quantities like the elastic constants, this energy expression is quadratic in the displacements u_i and will yield a set of linear equations. Thus the displacement assumption (4) has provided a means for linearizing the problem.

Simplified Displacement Approximation

As indicated, we have been able to linearize the problem while including the effect of pressurization but we still have a problem in two independent coordinates which will be described in terms of a set of linear partial differential equations. The present objective is to simplify the mathematical form by introducing a displacement approximation which specifies the form of the displacement components with respect to the meridional coordinate, θ_1 . This displacement approximation describes the deformation in terms of rigid body motions of the cross-section; that is, the cross-section retains its shape during deformation. The approximation is the one used in beam theory. Here, however, transverse shear deformation is included. This approximation is stated mathematically by expressing the displacement components u_i in terms of the three displacements of the cross-section U , V , W and the rotations of the cross-section about three mutually perpendicular axes, ϕ_x , ϕ_y , and ϕ_z as:

$$u_1 = a\phi_x + W\sin(\theta_1) + V\cos(\theta_1) \quad (12a)$$

$$u_2 = U - \phi_y\cos(\theta_1) - \phi_z\sin(\theta_1) \quad (12b)$$

$$u_3 = V\sin(\theta_1) - W\cos(\theta_1) \quad (12c)$$

These cross-section displacements which are functions of θ_2 only are shown graphically in Figure 2. These displacement approximations can be used to formulate one-dimensional strain measures, stress resultants, and a one-dimensional energy principle.

The one-dimensional strain measures are obtained by substituting equations (12) into equations (6) yielding

$$\begin{aligned} \epsilon'_{11} &= 0 \\ \epsilon''_{11} &= \phi_x^2/2 \quad (13) \\ \epsilon'_{22} &= (1/\alpha_2)[U' - W] - \phi_y\cos(\theta_1) - (\phi_z' + \phi_x)\sin(\theta_1) \\ \epsilon''_{22} &= (1/2\alpha_2^2)[(U + W')\cos(\theta_1) - V'\sin(\theta_1) - \phi_y\cos^2(\theta_1) - \phi_z\sin(\theta_1)\cos(\theta_1)]^2 \\ \epsilon'_{12} &= (1/2\alpha_2)[a(\phi_x' - \phi_z) + (W' + U + R\phi_y)\sin(\theta_1) + (V' - R\phi_z)\cos(\theta_1)] \\ \epsilon''_{12} &= (1/2\alpha_2)[\phi_x((U + W')\cos(\theta_1) - V'\sin(\theta_1) - \phi_y\cos^2(\theta_1) - \\ &\quad \phi_z\sin(\theta_1)\cos(\theta_1))] \end{aligned}$$

At this point we introduce two additional assumptions. The first of these assumes that the deformation is such that a uniaxial state of strain results which implies $\epsilon_{11} = 0$. This is consistent with the displacement approximation (12) to the first order and requires

that we neglect the second order term ϕ_x^2 and set $\epsilon''_{11} = 0$. The second of these additional assumptions is that the shear strain can be adequately represented by a linear expression in the displacements and their derivatives. This assumption implies that $\epsilon'_{12} = 0$. This assumption can be further justified by noting that in the energy expression (11) ϵ''_{12} is a coefficient of N_{12}^0 which is the shear stress component for the pressurized state. Since this stress component vanishes for internal pressure loading, the nonlinear term being neglected in the shear strain would make no contribution to the energy.

The one-dimensional energy principle is obtained by incorporating the above assumptions in the energy principle (11) and rewriting it as a quadratic in the strain measures as:

$$\delta \int_A 1/2 [C_{22}(\epsilon'_{22})^2 + 4C_{33}(\epsilon'_{12})^2 + 2N_{22}^0 \epsilon''_{22} - 2(F_1 u_1 + F_2 u_2 + F_3 u_3)] dA = 0 \quad (14)$$

With the substitution of equations (12) and (13) into this expression and integrating with respect to θ_1 from 0 to 2π the one-dimensional energy principle is obtained as

$$\begin{aligned} \delta \int_{\theta_2} \pi/2 [& \frac{C_{22}}{R^2} [2(U' - W)^2 + Z_2 (\frac{a}{R})^2 (U' - W + R\phi'_y)^2 + a^2 Z_3 (\phi'_z + \phi_x)^2] + \\ & \frac{C_{33}}{R^2} [2a^2 (\phi'_x - \phi_z)^2 + Z_2 (\frac{a}{R})^2 (a(\phi'_x - \phi_z) - \frac{R}{a} (V' - R\phi_z))^2 + \\ & Z_3 (W' + U + R\phi_y)^2] + \frac{N_{22}^0}{R^2} [(U + W')^2 + Z_2 (\frac{a}{R})^2 (U + W' + R\phi_y)^2 + \\ & (V')^2 + Z_4 (\frac{a}{R})^2 (V' - R\phi_z)^2] - 2[Uf_2 + Wf_1 + Vf_3 + \\ & a\phi_x f_4 - a\phi_y f_5 - a\phi_z f_6]] aR d\theta_2 = 0 \end{aligned} \quad (15)$$

The details of this development are presented in Appendix A.

As derived in Appendix B, expressions for the one-dimensional stress resultants and moments in terms of the cross-section displacements and rotations are

$$t = \pi C_{22} \frac{a}{R} [(2 + (\frac{a}{R})^2 Z_2)(U' - W) + (\frac{a}{R})^2 Z_2 R\phi'_y] \quad (16a)$$

$$\begin{aligned} q_y = \pi C_{33} \frac{a}{R} Z_2 [(V' - R\phi_z) - R(\frac{a}{R})^2 (\phi'_x - \phi_z)] - \\ \pi N_{22}^0 \frac{a}{R} [-Z_3 V' + (\frac{a}{R})^2 R Z_4 \phi_z] \end{aligned} \quad (16b)$$

$$q_z = \pi C_{33} Z_3 \frac{a}{R} [W' + U + R\phi_y] + \pi N_{22}^0 \frac{a}{R} [Z_2 (U + W') + (\frac{a}{R})^2 ZR\phi_y] \quad (16c)$$

$$m_x = \pi C_{33} a (\frac{a}{R})^2 [R(2 + (\frac{a}{R})^2 Z_2)(\phi'_x - \phi_z) - Z_2 (V' - R\phi_z)] \quad (16d)$$

$$m_y = -\pi C_{22} Z_2 a (\frac{a}{R})^2 [U' - W + R\phi'_y] \quad (16e)$$

$$m_z = -\pi C_{22} Z_3 a R (\frac{a}{R})^2 (\phi'_z + \phi_x) \quad (16f)$$

The energy principle (15) can be expressed in terms of these stress resultants and moments by carrying out the variation and substituting equations (16) to give

$$\begin{aligned} & \left[\frac{1}{R} \delta(U' - W) - \frac{1}{R} m_y \phi'_y - \frac{1}{R} m_z (\phi'_z + \phi_x) + \right. \\ & \left. \frac{1}{R} m_x (\phi'_x - \phi_z) + \frac{1}{R} q_y \delta(V' - R\phi_z) + \frac{\pi}{R} N_{22}^0 \frac{a}{R} V' \delta(R\phi_z) \right. \\ & \left. + \frac{1}{R} q_z \delta(U + W' - R\phi_y) - \frac{\pi}{R} N_{22}^0 \frac{a}{R} (U + W') \delta(R\phi_y) \right. \\ & \left. - \pi a (f_2 \delta U + f_1 \delta W + f_3 \delta V + af_4 \delta \phi_x \right. \\ & \left. - af_5 \delta \phi_y - af_6 \delta \phi_z) \right] R d\theta_2 = 0 \end{aligned} \quad (17)$$

Observation of the expression leads to the following definition of the one-dimensional strain measures

$$e = \frac{1}{R} (U' - W) \quad (18a)$$

$$\kappa_y = \frac{1}{R} \phi'_y \quad (18b)$$

$$\kappa_z = \frac{1}{R} (\phi'_z + \phi_x) \quad (18c)$$

$$\kappa_x = \frac{1}{R} (\phi'_x - \phi_z) \quad (18d)$$

$$\gamma_z = \frac{1}{R} (U + W' - R\phi_y) \quad (18e)$$

$$\gamma_y = \frac{1}{R} (V' - R\phi_z) \quad (18f)$$

This completes the derivation of the one-dimensional theory. The governing equations in terms of the cross-section displacements and rotations can be obtained directly from equation (15) by application of the calculus of variations. Here the alternate procedure of obtaining the equilibrium equation in terms of the stress resultants and moments will be used. The governing equations in terms of the displacements and rotation are then obtained by use of the stress-displacement relations (16).

Governing Differential Equations

The equilibrium equations in terms of the stress resultants and moments are obtained from equation (17) by integrating by parts where possible to yield

$$\begin{aligned}
 & \int_{-\alpha}^{\alpha} \left\{ \left[\frac{1}{R} (-t' + q_z) - \pi a f_2 \right] \delta U - \left[\frac{1}{R} (t + q'_z) + \pi a f_1 \right] \delta W + \right. \\
 & \quad \left[\frac{1}{R} m'_y + q_z - \frac{\pi a}{R} N_{22}^0 (U + W') + \pi a^2 f_5 \right] \delta \phi_y - \left[\frac{1}{R} q'_y + \pi a f_3 \right] \delta V + \\
 & \quad \left[\frac{1}{R} (m'_z - m_x) - q_y + \frac{\pi a}{R} N_{22}^0 V' + \pi a^2 f_6 \right] \delta \phi_z - \\
 & \quad \left. \left[\frac{1}{R} (m_z + m'_x) + \pi a^2 f_4 \right] \delta \phi_x \right\} R d\theta_2 + \\
 & \quad (t \delta U - m_y \delta \phi_y - m_z \delta \phi_z + m_x \delta \phi_x + q_y \delta V + q_z \delta W) \Big|_{-\alpha}^{\alpha} = 0
 \end{aligned} \tag{19}$$

Since the variational displacements are independent, satisfaction of the above equality requires that

$$\frac{1}{R} (-t' + q_z) - \pi a f_2 = 0 \tag{20a}$$

$$-\frac{1}{R} (t + q'_z) - \pi a f_1 = 0 \tag{20b}$$

$$\frac{1}{R} m'_y + q_z - \frac{\pi a}{R} N_{22}^0 (U + W') + \pi a^2 f_5 = 0 \tag{20c}$$

$$-\frac{1}{R} q'_y - \pi a f_3 = 0 \tag{20d}$$

$$\frac{1}{R} (m'_z - m_x) - q_y + \frac{\pi a}{R} N_{22}^0 V' + \pi a^2 f_6 = 0 \tag{20e}$$

$$-\frac{1}{R} (m_z + m'_x) - \pi a^2 f_4 = 0 \tag{20f}$$

over the region $-\alpha < \theta_2 < \alpha$. On the boundaries $\theta_2 = -\alpha$ and $\theta_2 = \alpha$ one of each of the following pairs of parameters must be specified

$$\begin{aligned}
 & t \quad \text{or} \quad U \\
 & m_y \quad \text{or} \quad \phi_y \\
 & q_z \quad \text{or} \quad W \\
 & m_z \quad \text{or} \quad \phi_z \\
 & m_x \quad \text{or} \quad \phi_x \\
 & q_y \quad \text{or} \quad V
 \end{aligned} \tag{21}$$

To complete the development, we substitute the stress-displacement relations (16) into the equilibrium equations to give the following governing equations for the displacements and rotations

$$\begin{aligned}
 & -C_{22} \frac{a}{R^2} (2 + (\frac{a}{R})^2 Z_2) U'' + \frac{a}{R^2} (C_{33} Z_3 + N_{22}^0 Z_2) U \\
 & - (\frac{a}{R})^3 C_{22} Z_2 \phi_y'' + \frac{a}{R} (C_{33} Z_3 + (\frac{a}{R})^2 N_{22}^0 Z_2) \phi_y \\
 & + \frac{a}{R^2} [C_{22} (2 + (\frac{a}{R})^2 Z_2) + C_{33} Z_3 + N_{22}^0 Z_2] W' - a f_2 = 0
 \end{aligned} \tag{22a}$$

$$\begin{aligned}
 & -\frac{a}{R^2} (C_{33} Z_3 + N_{22}^0 Z_2) W'' + C_{22} \frac{a}{R^2} (2 + (\frac{a}{R})^2 Z_2) W \\
 & - \frac{a}{R^2} [C_{22} (2 + (\frac{a}{R})^2 Z_2) + C_{33} Z_3 + N_{22}^0 Z_2] U' \\
 & - \frac{a}{R} [(\frac{a}{R})^2 C_{22} Z_2 + C_{33} Z_3 + (\frac{a}{R})^2 N_{22}^0 Z_2] \phi_y' - a f_1 = 0
 \end{aligned} \tag{22b}$$

$$\begin{aligned}
 & -(\frac{a}{R})^2 a C_{22} Z_2 \phi_y'' + (C_{33} Z_3 + (\frac{a}{R})^2 N_{22}^0 Z_2) a \phi_y \\
 & - (\frac{a}{R})^3 C_{22} Z_2 U'' + \frac{a}{R} (C_{33} Z_3 + (\frac{a}{R})^2 N_{22}^0 Z_2) U \\
 & + \frac{a}{R} [(\frac{a}{R})^2 C_{22} Z_2 + C_{33} Z_3 + (\frac{a}{R})^2 N_{22}^0 Z_2] W' + a^2 f_5 = 0
 \end{aligned} \tag{22c}$$

$$-\frac{a}{R^2} (C_{33}Z_2 + N_{22}^0 Z_3) V'' + \left(\frac{a}{R}\right)^3 C_{33} Z_2 \phi_X'' \quad (22d)$$

$$+ \frac{a}{R} [C_{33}Z_2 (1 - (\frac{a}{R})^2) + (\frac{a}{R})^2 N_{22}^0 Z_4] \phi_Z' - a f_3 = 0$$

$$-\left(\frac{a}{R}\right)^2 a C_{22} Z_3 \phi_Z'' + [C_{33}(2(\frac{a}{R})^2 + (1 - (\frac{a}{R})^2)^2 Z_2) + (\frac{a}{R})^2 N_{22}^0 Z_4] a \phi_Z' - [(\frac{a}{R})^2 C_{22} Z_3 + C_{33}(\frac{a}{R})^2 (2 - Z_2 + (\frac{a}{R})^2 Z_2)] a \phi_X' \quad (22e)$$

$$-\frac{a}{R} [C_{33}Z_2 (1 - (\frac{a}{R})^2) - N_{22}^0 (1 - Z_3)] V' + a^2 f_6 = 0$$

$$-\left(\frac{a}{R}\right)^2 a C_{33} (2 + (\frac{a}{R})^2 Z_2) \phi_X'' + \left(\frac{a}{R}\right)^2 a C_{22} Z_3 \phi_X' + \left(\frac{a}{R}\right)^2 [C_{22} Z_3 + C_{33} (2 - Z_2 + (\frac{a}{R})^2 Z_2)] a \phi_Z' \quad (22f)$$

$$+ \left(\frac{a}{R}\right)^3 C_{33} Z_2 V'' - a^2 f_4 = 0$$

This gives a set of six linear second order differential equations with constant coefficients in the six cross-section displacement parameters. The first three of these equations describing the deformation in the plane of the arch are uncoupled from the last three which describe the deformation out of the plane of the arch. This completes the development of the theory for the structural behavior of pressure-stabilized arches. The theory is put in nondimensional form in Appendix C. Although the motivation for this derivation was to establish equations to describe or predict the behavior of pressure-stabilized arches under applied static loads, these equations also represent a theory for the elastic stability of arches. That is, if the applied loads, f_i , $i=1, 6$, are set equal to zero and homogenous boundary conditions are used, we have a set of homogenous equations for the determination of the values of N_{22}^0 giving nontrivial solution functions for the displacement parameters. These values of N_{22}^0 are the buckling stresses, and the solution functions are buckling mode shapes.

Discontinuity Conditions for Green's Function:

One additional item that will be required is a derivation of the discontinuity conditions required for obtaining a Green's function solution. The Green's function for structural problems can be interpreted as the deformation at a general point θ_2 due to a unit load applied at $\bar{\theta}_2$. The discontinuity conditions involve this unit load and internal stress resultants and moments. To derive these conditions we consider an arch having an angular span of 2α with the origin of the coordinate θ_2 positioned at the center of the span

as shown in Figure 3. The load applied at $\theta_2 = \bar{\theta}_2$ has some distribution with respect to the coordinate θ_1 as shown in Figure 3 and requires three components, $G_1(\theta_1)$, $G_2(\theta_1)$, and $G_3(\theta_1)$, for complete specification. The arch is divided into two regions, one on either side of the applied load or mathematically $-\alpha \leq \theta_2 < \bar{\theta}_2$ and $\bar{\theta}_2 < \theta_2 \leq \alpha$. To obtain the needed conditions the energy principle (11) is rewritten integrating over each of the regions separately and including the potential energy of the forces applied at $\theta_2 = \bar{\theta}_2$

$$\begin{aligned} & \delta \int_{-\alpha}^{\bar{\theta}_2} \int_0^{2\pi} E(\theta_1, \theta_2) (1 + a/R \cos(\theta_1)) R d\theta_1 d\theta_2 + \\ & \delta \int_{\bar{\theta}_2}^{\alpha} \int_0^{2\pi} E(\theta_1, \theta_2) (1 + a/R \cos(\theta_1)) R d\theta_1 d\theta_2 - \\ & \delta \int_0^{2\pi} [G_1(\theta_1) u_1(\theta_1, \bar{\theta}_2) + G_2(\theta_1) u_2(\theta_1, \bar{\theta}_2) + G_3(\theta_1) u_3(\theta_1, \bar{\theta}_2)] a d\theta_1 = 0 \end{aligned} \quad (23)$$

where $E(\theta_1, \theta_2)$ is the energy density function and the displacement components in the third integral are evaluated at $\theta_2 = \bar{\theta}_2$. The simplified displacement approximations are substituted as done previously and the integration with respect to θ_1 carried out to give

$$\begin{aligned} & \delta \int_{-\alpha}^{\bar{\theta}_2} E(\theta_2) a R d\theta_2 + \delta \int_{\bar{\theta}_2}^{\alpha} E(\theta_2) a R d\theta_2 - \\ & \delta \left\{ \pi a [g_2 U(\bar{\theta}_2) + g_1 W(\bar{\theta}_2) + g_3 V(\bar{\theta}_2) + \right. \\ & \left. g_4 a \theta_x(\bar{\theta}_2) - g_5 a \phi_y(\bar{\theta}_2) - g_6 a \phi_z(\bar{\theta}_2)] \right\} = 0 \end{aligned} \quad (24)$$

where

$$g_1 = \frac{1}{\pi} \int_0^{2\pi} (G_1(\theta_1) \sin(\theta_1) - G_3(\theta_1) \cos(\theta_1)) d\theta_1 \quad (25a)$$

$$g_1 = \frac{1}{\pi} \int_0^{2\pi} G_2(\theta_1) d\theta_1 \quad (25b)$$

$$g_3 = \frac{1}{\pi} \int_0^{2\pi} (G_1(\theta_1) \cos(\theta_1) + G_3(\theta_1) \sin(\theta_1)) d\theta_1 \quad (25c)$$

$$g_4 = \frac{1}{\pi} \int_0^{2\pi} G_1(\theta_1) d\theta_1 \quad (25d)$$

$$g_5 = \frac{1}{\pi} \int_0^{2\pi} G_2(\theta_1) \cos(\theta_1) d\theta_1 \quad (25e)$$

$$g_6 = \frac{1}{\pi} \int_0^{2\pi} G_2(\theta_1) \sin(\theta_1) d\theta_1 \quad (25f)$$

Over the region $-\alpha \leq \theta_2 \leq \bar{\theta}_2$, the energy density is expressed in terms of the displacement parameters $U_1, W_1, V_1, \phi_{x1}, \phi_{y1}$, and ϕ_{z1} and over the region $\bar{\theta}_2 < \theta_2 \leq \alpha$ in terms of $U_2, W_2, V_2, \phi_{x2}, \phi_{y2}$ and ϕ_{z2} . If the variation in (24) is carried out, the result expressed in terms of stress resultants and moments, and the integration by parts performed, a set of six governing equations identical in form to (22) are obtained from each of the two regions being considered. What is of interest here are the boundary terms and the applied force at $\bar{\theta}_2$. This boundary term which must vanish is

$$\begin{aligned}
 & t_1 \delta U_1 - m_{y1} \delta \phi_{y1} - m_{z1} \delta \phi_{z1} + m_{x1} \delta \phi_{x1} + q_{y1} \delta V_1 + q_{z1} \delta W_1 \Big|_{-\alpha}^{\bar{\theta}_2} + \\
 & t_2 \delta U_2 - m_{y2} \delta \phi_{y2} - m_{z2} \delta \phi_{z2} + m_{x2} \delta \phi_{x2} + q_{y2} \delta V_2 + q_{z2} \delta W_2 \Big|_{\bar{\theta}_2}^{\alpha} \\
 & -a\pi [g_2 \delta U_1(\bar{\theta}_2) + g_1 \delta W_1(\bar{\theta}_2) + g_3 \delta V_1(\bar{\theta}_2) + g_4 a \delta \phi_{x1}(\bar{\theta}_2) \\
 & -g_5 a \delta \phi_{y1}(\bar{\theta}_2) - g_6 a \delta \phi_{z1}(\bar{\theta}_2)] = 0
 \end{aligned} \tag{26}$$

In writing (26) subscript 1 refers to a variable defined on the region $-\alpha \leq \theta_2 \leq \bar{\theta}_2$ and subscript 2 to a variable defined on $\bar{\theta}_2 < \theta_2 \leq \alpha$. The boundary terms at $\theta_2 = \pm \alpha$ give the boundary conditions at the ends of the arch which are, not unexpectedly, identical with those derived previously. The remaining boundary terms will yield the conditions that must hold at the applied load, but it is first necessary to state the conditions of continuity of deformation between the two regions. These conditions are simply

$$\begin{aligned}
 U_1(\bar{\theta}_2) &= U_2(\bar{\theta}_2) \\
 W_1(\bar{\theta}_2) &= W_2(\bar{\theta}_2) \\
 V_1(\bar{\theta}_2) &= V_2(\bar{\theta}_2) \\
 \phi_{x1}(\bar{\theta}_2) &= \phi_{x2}(\bar{\theta}_2) \\
 \phi_{y1}(\bar{\theta}_2) &= \phi_{y2}(\bar{\theta}_2) \\
 \phi_{z1}(\bar{\theta}_2) &= \phi_{z2}(\bar{\theta}_2)
 \end{aligned} \tag{27}$$

Thus the variations of these parameters must be equal and the boundary terms at $\bar{\theta}_2$ become

$$\begin{aligned}
 & [t_1 - t_2 - \pi a g_2] \delta U_1(\bar{\theta}_2) + [-m_{y1} + m_{y2} + \pi a^2 g_5] \delta \phi_{y1}(\bar{\theta}_2) \\
 & [q_{z1} - q_{z2} - \pi a g_1] \delta W_1(\bar{\theta}_2) + [-m_{z1} + m_{z2} + \pi a^2 g_6] \delta \phi_{z1}(\bar{\theta}_2) \\
 & [m_{x1} - m_{x2} - \pi a^2 g_4] \delta \phi_{x1}(\bar{\theta}_2) + [q_{y1} - q_{y2} - \pi a g_3] \delta V_1(\bar{\theta}_2) = 0
 \end{aligned} \tag{28}$$

Each of the terms must vanish independently giving the discontinuity conditions as

$$t_1(\bar{\theta}_2) - t_2(\bar{\theta}_2) = \pi a g_2 \tag{29a}$$

$$m_{y1}(\bar{\theta}_2) - m_{y2}(\bar{\theta}_2) = \pi a^2 g_5 \tag{29b}$$

$$q_{z1}(\bar{\theta}_2) - q_{z2}(\bar{\theta}_2) = \pi a g_1 \tag{29c}$$

$$m_{z1}(\bar{\theta}_2) - m_{z2}(\bar{\theta}_2) = \pi a^2 g_6 \tag{29d}$$

$$m_{x1}(\bar{\theta}_2) - m_{x2}(\bar{\theta}_2) = \pi a^2 g_4 \tag{29e}$$

$$q_{y1}(\bar{\theta}_2) - q_{y2}(\bar{\theta}_2) = \pi a g_3 \tag{29f}$$

These are the required conditions and they are expressed in nondimensional form in Appendix C.

Solution of the Governing Equations

Having derived a set of governing equations in the previous section we turn now to the solution of these equations. In what follows only the inplane deformation will be considered with solutions obtained in the form of a Green's Function and for an arch with a uniform normal load. The Green's Function provides a means for obtaining solutions for quite general loading by integration.

Homogenous Solution

The equations to be solved are (22a), (22b), and (22c) which are given in nondimensional form in Appendix C as (C22), (C23) and (C24). These are rewritten here in more compact form to aid in writing the solutions.

$$-H_1 U'' + H_2 U - H_3 \phi_Y'' + H_4 \phi_Y + (H_1 + H_2)W' = 0 \quad (30a)$$

$$-H_2 W'' + H_1 W - (H_3 + H_4)\phi_Y' - (H_1 + H_2)U' = 0 \quad (30b)$$

$$-\rho H_3 \phi_Y'' + \rho H_4 \phi_Y - H_3 U'' + H_4 U + (H_3 + H_4)W' = 0 \quad (30c)$$

where

$$H_1 = 2d/\rho + dZ_2/\rho^3 \quad (31a)$$

$$H_2 = cZ_3/\rho + nZ_2/\rho \quad (31b)$$

$$H_3 = dZ_2/\rho^2 \quad (31c)$$

$$H_4 = cZ_3 + nZ/\rho^2 \quad (31d)$$

Since the homogenous solution is sought, the force parameters are set equal to zero. The equations have constant coefficients, so the solution is

$$U = Ae^{\omega\theta_2} \quad (32a)$$

$$\phi_Y = Be^{\omega\theta_2} \quad (32b)$$

$$W = Ce^{\omega\theta_2} \quad (32c)$$

Substitution of this solution into (30) yields the following set of homogenous equations for A, B, and C:

$$\begin{bmatrix} H_2 - H_1\omega^2 & H_4 - H_3\omega^2 & (H_1 + H_2)\omega \\ H_4 - H_3\omega^2 & \rho(H_4 - H_3\omega^2) & (H_3 + H_4)\omega \\ -(H_1 + H_2)\omega & -(H_3 + H_4)\omega & H_1 - H_2\omega^2 \end{bmatrix} \begin{Bmatrix} A \\ B \\ C \end{Bmatrix} = 0 \quad (33)$$

Existence of a nontrivial solution requires that ω be a solution of

$$\begin{aligned} & H_1 H_4 (H_4 - \rho H_2) + \omega^2 [H_2 H_3 (\rho H_1 - H_3) + 2H_1 H_4 (H_4 - \rho H_2)] + \\ & \omega^4 [H_1 H_4 (H_4 - \rho H_2) + 2H_2 H_3 (\rho H_1 - H_3)] + \\ & \omega^6 [H_2 H_3 (\rho H_1 - H_3)] = 0 \end{aligned} \quad (34)$$

This is a sixth order equation in ω or a cubic equation in ω^2 which can be written in factored form as

$$(\omega^2 + 1)(\omega^2 + 1)[H_2 H_3 (\rho H_1 - H_3)\omega^2 + H_1 H_4 (H_4 - \rho H_2)] = 0 \quad (35)$$

for which the roots are $(-i, -i, i, i, \lambda, -\lambda)$ where

$$\lambda^2 = \frac{H_1 H_4 (\rho H_2 - H_4)}{H_2 H_3 (\rho H_1 - H_3)} = \frac{n\rho^2 (2 + Z_2/\rho^2)(cZ_3 + nZ/\rho^2)}{2Z_2 d (cZ_3 + nZ_2)} \quad (36)$$

Thus λ^2 is always positive and the homogenous solution, taking account of the repeated roots, is

$$U = A_1 \cosh(\lambda\theta_2) + A_2 \sinh(\lambda\theta_2) + A_3 \sin(\theta_2) + A_4 \cos(\theta_2) + A_5 \theta_2 \sin(\theta_2) + A_6 \theta_2 \cos(\theta_2) \quad (37a)$$

$$\phi_y = B_1 \cosh(\lambda\theta_2) + B_2 \sinh(\lambda\theta_2) + B_3 \sin(\theta_2) + B_4 \cos(\theta_2) + B_5 \theta_2 \sin(\theta_2) + B_6 \theta_2 \cos(\theta_2) \quad (37b)$$

$$W = C_1 \cosh(\lambda\theta_2) + C_2 \sinh(\lambda\theta_2) + C_3 \sin(\theta_2) + C_4 \cos(\theta_2) + C_5 \theta_2 \sin(\theta_2) + C_6 \theta_2 \cos(\theta_2) \quad (37c)$$

The satisfaction of (27) implies a relationship among the constants A_i , B_i , and C_i such that two sets can be expressed in terms of the third. Here A_i and B_i are expressed in terms of C_i as

$$\begin{aligned} A_1 &= \beta_1 C_2 \\ A_2 &= \beta_1 C_1 \\ A_3 &= \beta_3 C_4 + \beta_5 C_5 \\ A_4 &= -\beta_3 C_3 + \beta_5 C_6 \\ A_5 &= \beta_3 C_6 \\ A_6 &= -\beta_3 C_5 \end{aligned} \quad (38)$$

$$\begin{aligned}
B_1 &= \beta_2 C_2 \\
B_2 &= \beta_2 C_1 \\
B_3 &= \beta_4 C_4 + \beta_6 C_5 \\
B_4 &= -\beta_4 C_3 + \beta_6 C_6 \\
B_5 &= \beta_4 C_6 \\
B_6 &= -\beta_4 C_5
\end{aligned} \tag{39}$$

Expressions for the determination of the β_i are given in Appendix D. With these relations among the constants the solution is

$$\begin{aligned}
U = & C_1 \beta_1 \sinh(\lambda \theta_2) + C_2 \beta_1 \cosh(\lambda \theta_2) - C_3 \beta_3 \cos(\theta_2) + C_4 \beta_3 \sin(\theta_2) + \\
& C_5 (\beta_5 \sin(\theta_2) - \beta_3 \theta_2 \cos(\theta_2)) + C_6 (\beta_5 \cos(\theta_2) + \beta_3 \theta_2 \sin(\theta_2))
\end{aligned} \tag{40a}$$

$$\begin{aligned}
\phi_y = & C_1 \beta_2 \sinh(\lambda \theta_2) + C_2 \beta_2 \cosh(\lambda \theta_2) - C_3 \beta_4 \cos(\theta_2) + C_4 \beta_4 \sin(\theta_2) + \\
& C_5 (\beta_6 \sin(\theta_2) - \beta_4 \theta_2 \cos(\theta_2)) + C_6 (\beta_6 \cos(\theta_2) + \beta_4 \theta_2 \sin(\theta_2))
\end{aligned} \tag{40b}$$

$$\begin{aligned}
W = & C_1 \cosh(\lambda \theta_2) + C_2 \sinh(\lambda \theta_2) + C_3 \sin(\theta_2) + C_4 \cos(\theta_2) \\
& C_5 \theta_2 \sin(\theta_2) + C_6 \theta_2 \cos(\theta_2)
\end{aligned} \tag{40c}$$

This is the homogenous solution containing six unknown constants to be determined by the boundary conditions for a given set of applied loads.

Green's Function

Instead of attempting to find particular solutions for a variety of loading situations, a Green's function is obtained which will provide a solution for general load through integration. As stated above, the Green's Function has for structural problems the interpretation of the deflection at a general point θ_2 due to a unit load applied at $\bar{\theta}_2$. As in the derivation of the discontinuity conditions we consider a beam having an angular span of 2α with the origin located at midspan, as shown in Figure 3. Over the region $-\alpha \leq \theta_2 \leq \bar{\theta}_2$ a solution U_1 , ϕ_{y1} , and W_1 is defined in terms of integration constants C_i , $i = 1, 6$ and over the region $\bar{\theta}_2 < \theta_2 \leq \alpha$ a solution U_2 , ϕ_{y2} , and W_2 is defined in terms of integration constants C_i , $i = 7, 12$. Thus the complete solution is defined by 12 constants and 12 conditions must be specified for their determination. Six of these come from the boundary conditions, three on each end. The other six come from the three conditions of continuity of displacements and the three discontinuity conditions on the internal stress resultants and moments. If both ends are simply supported these conditions are

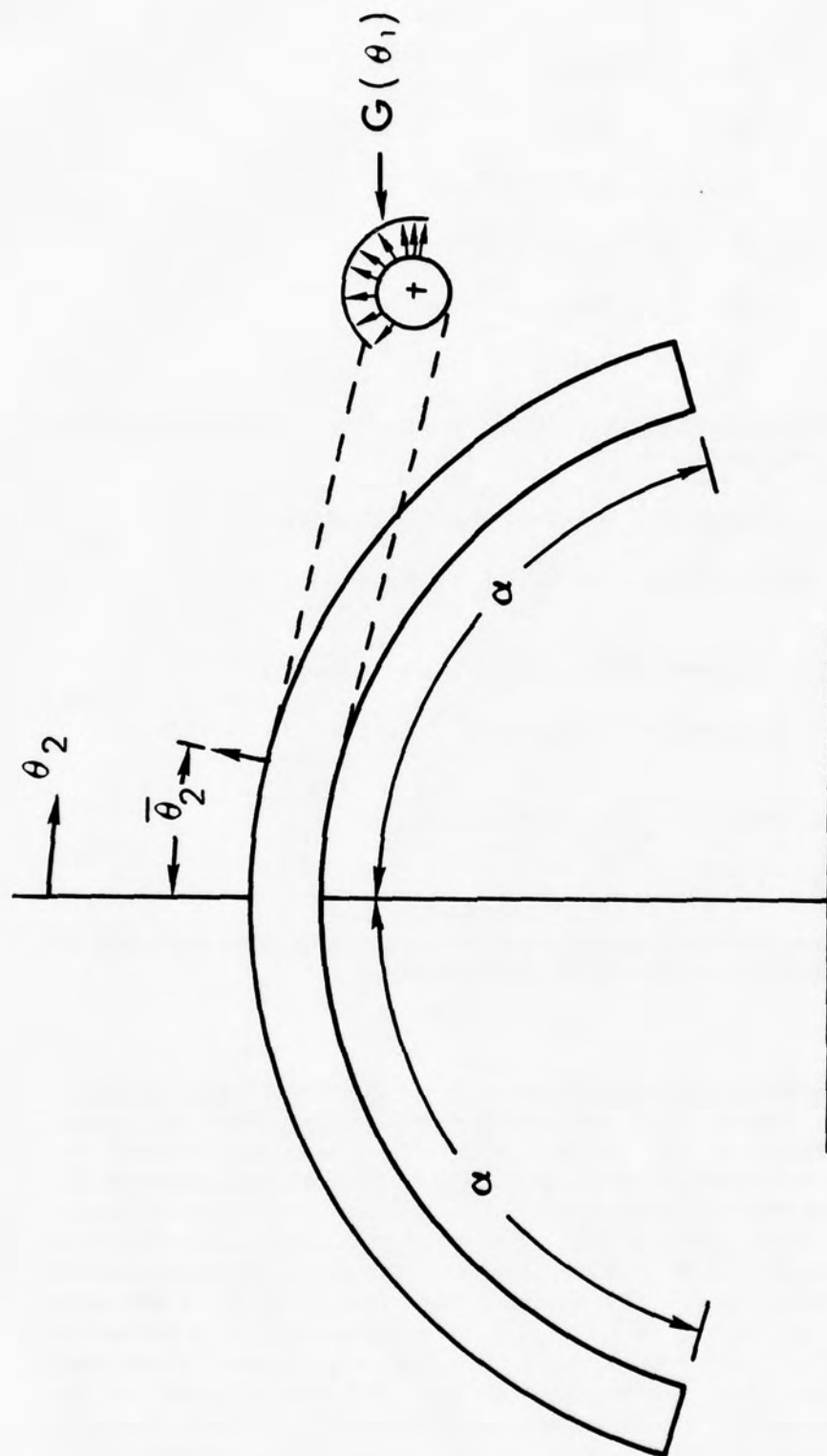


FIGURE 3. ILLUSTRATION OF THE LINE LOAD USED IN OBTAINING THE GREEN'S FUNCTION

$$U_1(-\alpha) = 0$$

$$M_{Y_1}(-\alpha) = 0$$

$$W_1(-\alpha) = 0$$

$$U_2(\alpha) = 0$$

$$M_{Y_2}(\alpha) = 0$$

$$W_2(\alpha) = 0$$

$$U_1(\bar{\theta}_2) - U_2(\bar{\theta}_2) = 0$$

$$\phi_{Y_1}(\bar{\theta}_2) - \phi_{Y_2}(\bar{\theta}_2) = 0$$

$$W_1(\bar{\theta}_2) - W_2(\bar{\theta}_2) = 0$$

$$T_1(\bar{\theta}_2) - T_2(\bar{\theta}_2) = \pi \bar{q}_2$$

$$M_{Y_1}(\bar{\theta}_2) - M_{Y_2}(\bar{\theta}_2) = \pi \bar{q}_s$$

$$Q_{Z_1}(\bar{\theta}_2) - Q_{Z_2}(\bar{\theta}_2) = -\pi \bar{q}_1$$

(41)

and if both ends are fixed, the conditions $M_{Y_1}(-\alpha) = 0$ and $M_{Y_2}(\alpha) = 0$ are respectively replaced by $\phi_{Y_1}(-\alpha) = 0$ and $\phi_{Y_2}(\alpha) = 0$. Other boundary conditions at $\pm\alpha$ are also possible. These conditions give a system of 12 linear equations for the constants C_i , $i = 1, 12$. The expressions for the coefficients of this system of equations are given in Appendix E.

Because only inplane deformation of the arch is being considered, the applied forces G_1 , G_2 , and G_3 must be symmetric about the plane of the arch. Two loading situations are of particular interest, normal load and vertical load. For normal loading, the components G_1 and G_2 vanish, therefore the nondimensional generalized forces \bar{q}_2 and \bar{q}_s vanish and the load is described in terms of \bar{q}_1 , and for a unit load \bar{q}_1 is set equal to unity. A vertical load is defined to be parallel to the line $\theta_2 = 0$. For a vertical load distribution $G(\theta_1)$ located at $\bar{\theta}_2$, the force components are

$$G_1 = -G(\theta_1)\sin(\theta_1)\cos(\bar{\theta}_2)$$

$$G_2 = -G(\theta_1)\sin(\bar{\theta}_2)$$

$$G_3 = G(\theta_1)\cos(\theta_1)\cos(\bar{\theta}_2)$$

(42)

and the generalized forces are found by carrying out the integrals in the definition (25). For example, if we have two concentrated forces of magnitude $G/2$ located at $\theta_1 = \pm \hat{\theta}_1$, then

$$G(\theta_1) = (G/2)[\delta(\theta_1 + \hat{\theta}_1) + \delta(\theta_1 - \hat{\theta}_1)] \quad (43)$$

where δ here denotes the Dirac delta function. Substituting (43) and (42) into (25) and carrying out the integrals using the integral property of the delta function yields

$$\bar{g}_1 = -g \cos(\bar{\theta}_2)$$

$$\bar{g}_2 = -g \sin(\bar{\theta}_2)$$

$$\bar{g}_3 = -g \sin(\bar{\theta}_2) \cos(\hat{\theta}_1)$$

for a unit load, $g = G/\pi C_{22}$ is set equal to unity.

Uniformly Distributed Normal Load

The solution for a uniform normal load could be obtained by integration of the Green's function derived in the previous section. However, since a particular solution of the nonhomogenous equations for this loading condition is easily found it was decided to give the solution explicitly as the sum of this particular solution and the homogenous solution. For this loading condition we deal with the forces F_1 , F_2 , and F_3 , with F_1 and F_2 vanishing. F_3 is independent of θ_2 and has a variation in θ_1 which is symmetrical about $\theta_1 = 0$ and is either constant or zero to give a distribution similar to that shown in Figure 4. Such a distribution will cause all the nondimensional force parameters to vanish except F_1 which will be a constant. Thus we need a particular solution of 30a, 30b, and 30c with F_1 appearing as a constant nonhomogenous term in (30b). The required particular solution is

$$\begin{aligned} U &= 0 \\ \phi_Y &= 0 \\ W &= \bar{f}_1 / H_1 \end{aligned} \quad (44)$$

The complete solution is the sum of this particular solution and the symmetric part of the homogenous solution

$$U = C_1 \beta_1 \sinh(\lambda \theta_2) + C_4 \beta_3 \sin(\theta_2) + C_5 (\beta_5 \sin(\theta_2) - \beta_3 \theta_2 \cos(\theta_2)) \quad (45a)$$

$$\phi_Y = C_1 \beta_2 \sinh(\lambda \theta_2) + C_4 \beta_4 \sin(\theta_2) + C_5 (\beta_6 \sin(\theta_2) - \beta_4 \theta_2 \cos(\theta_2)) \quad (45b)$$

$$W = C_1 \cosh(\lambda \theta_2) + C_4 \cos(\theta_2) + C_5 \theta_2 \sin(\theta_2) + \rho f_1 / d(2 + Z_2 / \rho^2) \quad (45c)$$

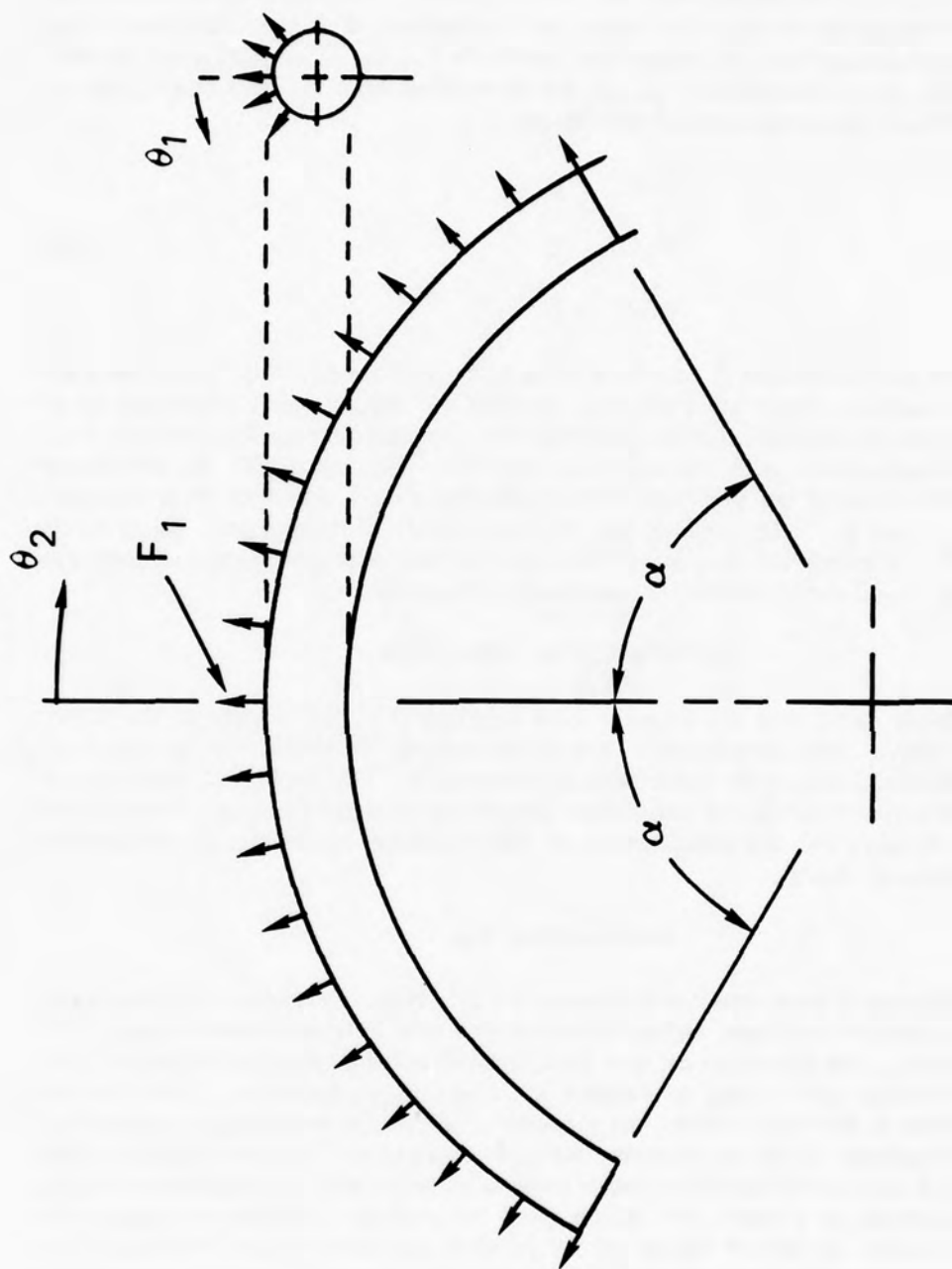


FIGURE 4. ILLUSTRATION OF UNIFORM NORMAL LOAD DISTRIBUTION

Only the symmetric part of the solution is included because the loading is symmetric about $\theta_2 = 0$, thus the deformation will be symmetric. Here symmetric deformation is used to characterize the situation where the displacement W is symmetric and U and ϕ_y are antisymmetric, thus the integration constants C_2, C_3, C_6 are set equal to zero. The remaining three constants C_1, C_4, C_5 are determined from the boundary conditions which for simply supported end conditions are

$$\begin{aligned} U(\alpha) &= 0 \\ M_y(\alpha) &= 0 \\ W(\alpha) &= 0 \end{aligned} \tag{46}$$

and for fixed end conditions $M_y(\alpha) = 0$ is replaced by $\phi_y(\alpha) = 0$. In both of these cases symmetric boundary conditions have been assumed. If the boundary conditions to be applied to each of the two ends are different, the complete homogenous solution must be used in conjunction with the particular solution. Equations (46) for the simply supported arch or with the substitution for fixed ends gives a system of three equations for C_1, C_4 , and C_5 . Expressions for the coefficients of this system are given in Appendix E. A computer program to carry out the computations associated with this solution and the Green's function is described in Appendix F.

EXPERIMENTAL ANALYSIS

To provide some data on which to base a judgment of the validity of the theory developed above, the deformation and load-carrying capability of a series of pressure-stabilized arches were determined experimentally. The elastic and shear moduli of the fabric used in making the arches were also measured experimentally. These moduli are needed to carry out the computations of the theoretical predictions for comparison with experimental results.

Arch Loading Tests

The objective of these tests was to measure the deformation behavior and load-carrying capacity of pressure stabilized arches of several sizes and inflation pressure levels. The flexibility, that is, the deflection per unit load, is taken as the measure of the deformation, and the wrinkling load is used to measure the load-carrying capability. The wrinkling load is defined as the load at which the maximum compressive stress due to applied load is equal in magnitude to the tensile stress due to pressurization. Thus any further increase in load would cause wrinkling of the fabric because it cannot support compressive stresses. The arches consist of a fabric skin which gives the structural strength to support the pressure, a bladder to prevent leakage of the inflation gas and end caps. The fabric skin was woven with beta fiberglass yarn using a three-dimensional weaving technique that results in a fabric having the natural contour of a torus. That is, when the arch is inflated it has the shape of a torus and no forces are required to maintain it in that shape. This

weaving process, which is described in references 6 and 7, produces a fabric in which the circumferential or fill yarn count is higher at the inner radius of the arch than at the outer radius. This nonuniformity of yarn count and the resulting natural contour or shape causes some difficulty in the determination of the fabric stiffness properties as will be discussed subsequently. The fabric used was a plain weave with an average yarn count in both warp and fill of 512/m using 133 Tex fiberglass yarns. Arches having cross-section radii of 0.038, 0.051, 0.076, and 0.089 m, all having an inner arch radius of 0.914 m, were woven and tested. The arch radius to cross-section radius ratios for these arches are then respectively 25, 19, 13, and 11.3.

A polyethylene film bladder was used to provide retention of the inflation gas. These bladders, made from 4-mil-thick film, were shaped to conform to the arch shape by cutting two segments of a circular annulus and joining them together by heat-sealing at the inner and outer radii. These bladders were made with the cross-section about 10% larger than that of the corresponding fabric. In doing this the strength requirements of the bladder were not a consideration. However, because of the oversizing of the bladders it was possible for folds to form in them, and when pressurized, the folds were flattened out resulting in cracks that caused leakage. This is believed to be a bladder material problem that could be cured by choosing a material with greater crack resistance.

The ends of the arches were closed and restrained with end cap assemblies shown in Figure 5. A schematic of this assembly is shown in Figure 6. As is shown, the fiberglass fabric and polyethylene bladder go through the inside of and wrap around the sealing ring. This arch-sealing ring combination is seated in the end cap on the rubber gasket. The arch and sealing ring are captured by the retaining ring which is bolted to the end cap to hold the assembly together and apply pressure to seal the arch for inflation. Inflation is accomplished through the port shown in Figure 6. As is seen in Figure 5, the end cap assembly was bolted to a steel plate so that it could not rotate. Thus the end restraint simulated fixed or clamped ends. Each arch had two end caps placed so that the arches had an angular span of π radians.

6. Koppelman, Edward and Arthur R. Campman; Woven Fabrics and Method of Weaving; US Patent No. 2998030; Aug 29, 1961.
7. Koppelman, Edward and Arthur R. Campman; Method of and Apparatus for Weaving Shaped Fabrics and Articles Woven Thereby; US Patent No. 313671; May 12, 1964.

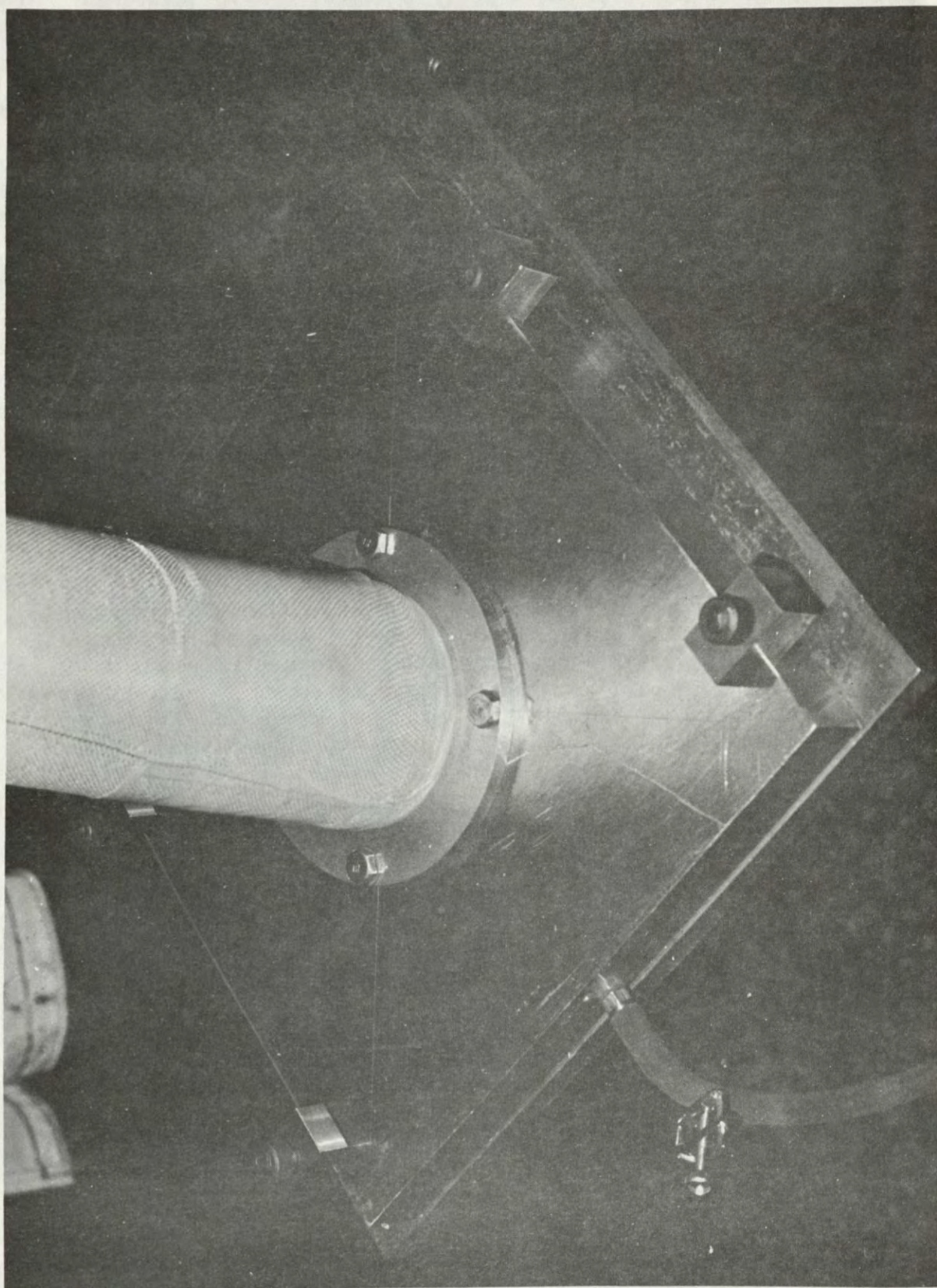


Figure 5. End Closure and Restraint for Fiberglass Arches.

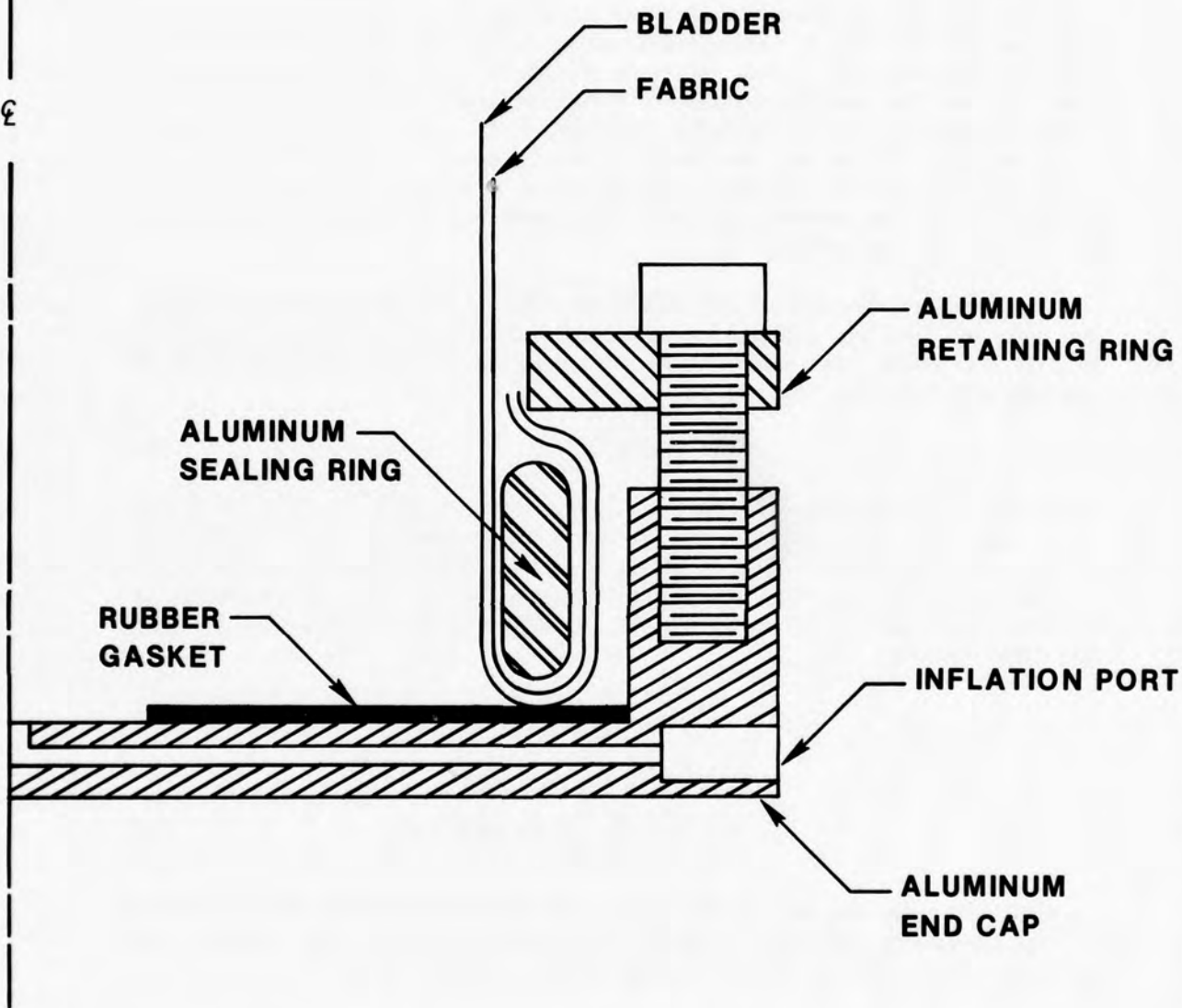


Figure 6. Schematic of the End Cap Assembly.

A schematic of the test apparatus is shown in Figure 7 and a photograph of the actual test apparatus is shown in Figure 8. The loading for all tests was a concentrated load at midspan. This load was applied using a 2.5-cm-wide strap wrapped around the arch. Tests were conducted with the load directed toward the arch center of curvature and away from the center of curvature. Wrinkling was, as expected, observed only when the load was directed toward the center of curvature, as this loading condition is the one which puts the arch in a compressive state of stress. The magnitude of the applied load was measured with a strain gage force transducer. The other measurement made was of the arch deflection at the point of the applied load. This was accomplished with a linear variable differential transformer positioned to measure the normal component of the deflection. The output from these transducers was amplified when required and recorded on a strip chart recorder, a sample of which is shown in Figure 9, for both the flexibility and the wrinkling load tests. Three tests were carried out for each pressure level with good repeatability.

To facilitate comparison of these experimental results with the theoretical prediction, the measured force and displacement were converted to the nondimensional parameters used in the theory. The measured normal component of displacement, W , is put in nondimensional form by the relation

$$W = W/a \quad (47)$$

where W is the nondimensional displacement and a is the cross-section radius. Conversion of the measured force F_a to the nondimensional force parameters \bar{g}_i , $i = 1, 6$ is illustrated in Figure 10. As shown in this figure, G_3 is the only nonvanishing component of the line load applied to the arch and this is in the negative direction. Thus the nondimensional force parameters of concern are $\bar{g}_1 = g_1/\bar{C}_{22}$ and $\bar{g}_2 = g_2/\bar{C}_{22}$. Using equations (25a) and (25c) we have

$$\bar{g}_1 = (1/\pi\bar{C}_{22}) \int_0^{2\pi} G_3(\theta_1) \cos(\theta_1) d\theta_1 \quad (48)$$

$$\bar{g}_3 = -(1/\pi\bar{C}_{22}) \int_0^{2\pi} G_3(\theta_1) \sin(\theta_1) d\theta_1 \quad (49)$$

where \bar{C}_{22} is a reference value of the elastic modulus and the negative direction of the load $G_3(\theta_1)$ has been accounted for. Since $G_3(\theta_1)$ is nonvanishing only over a portion of the periphery of the arch, the limits and integrals can be changed to give

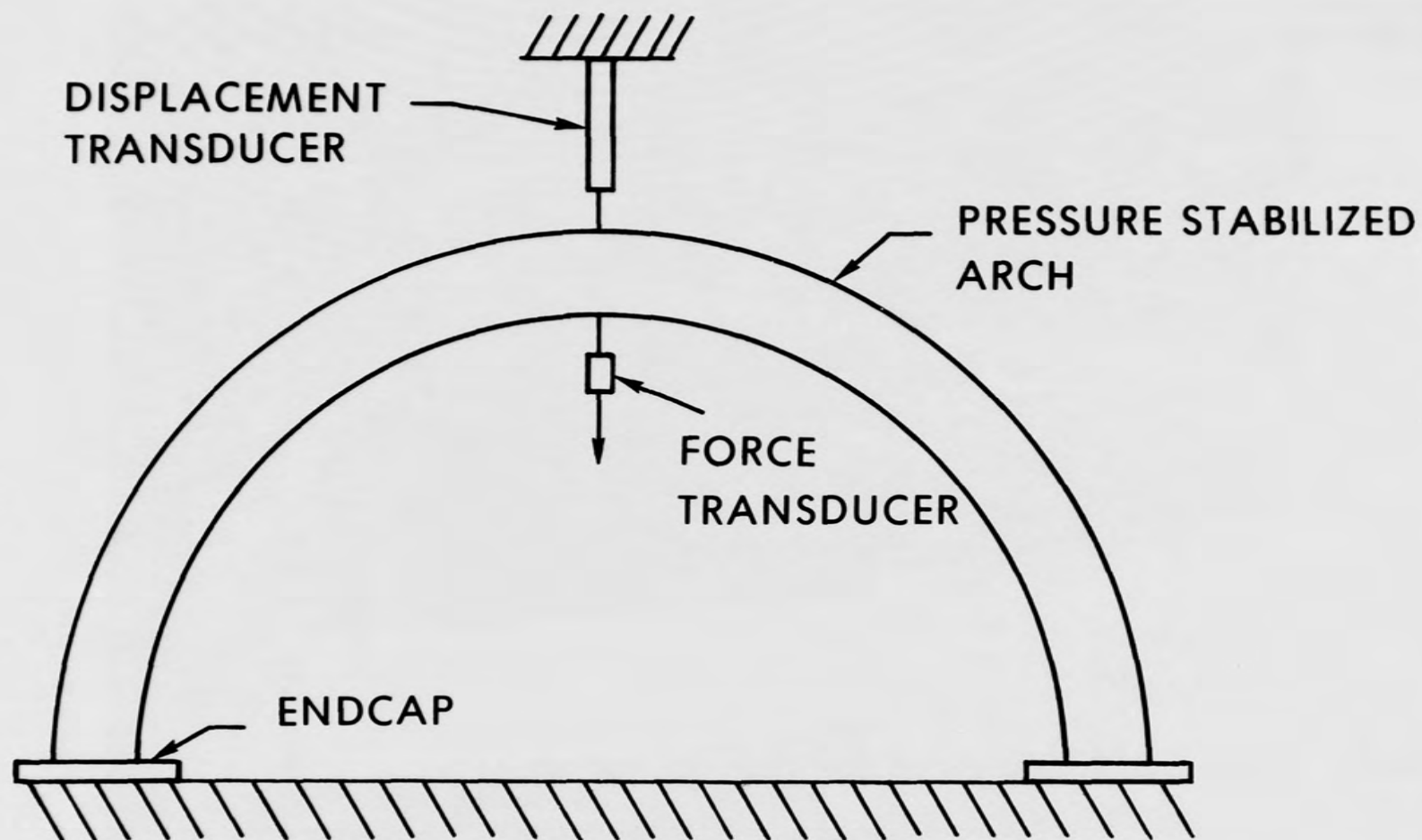


FIGURE 7. SCHEMATIC OF TEST APPARATUS

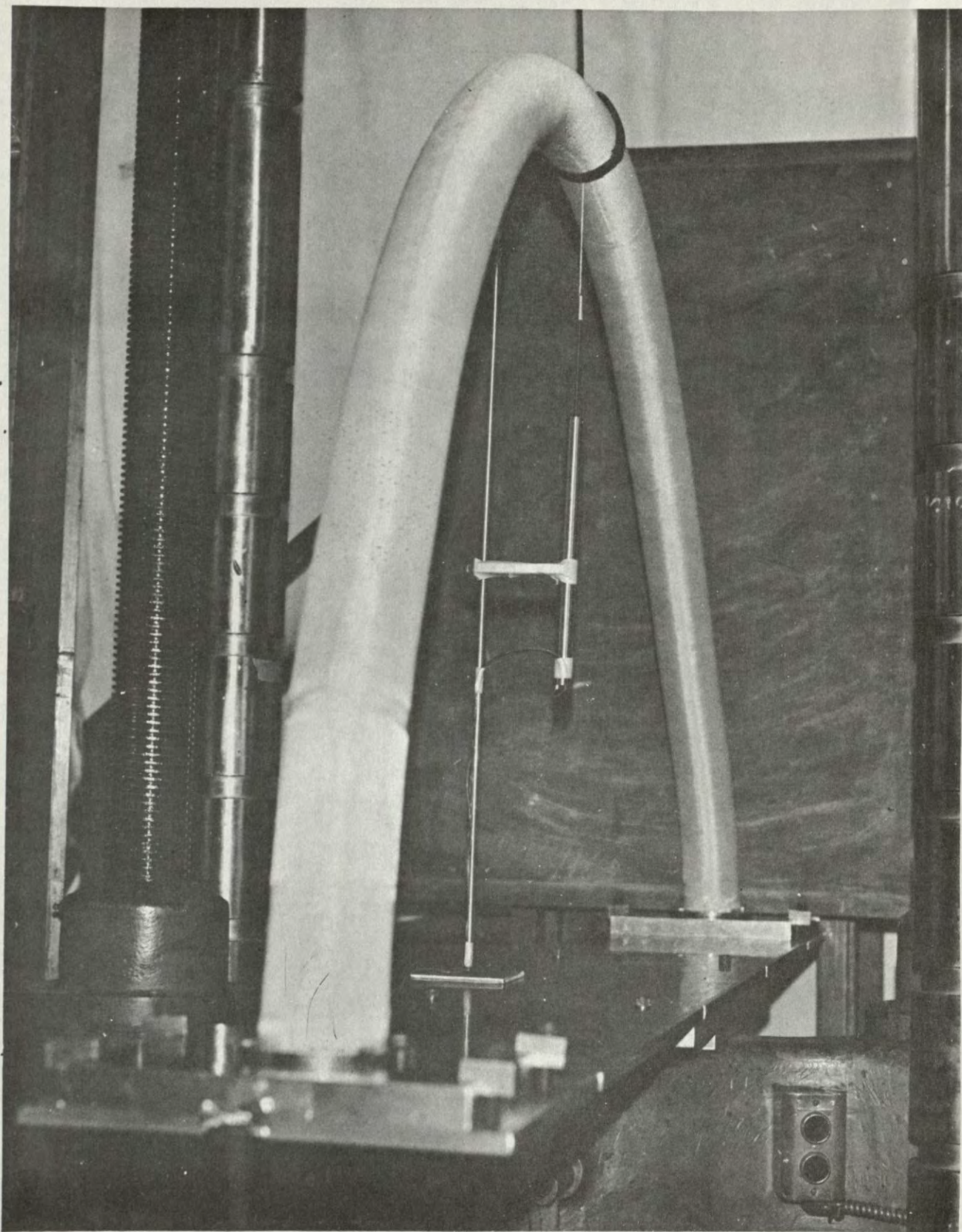
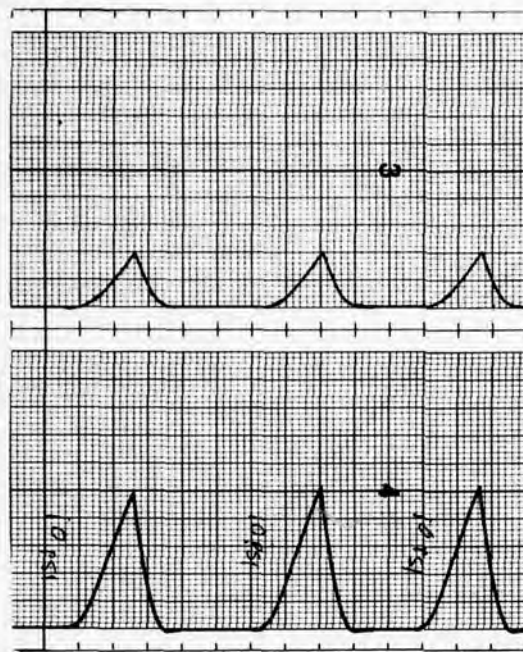


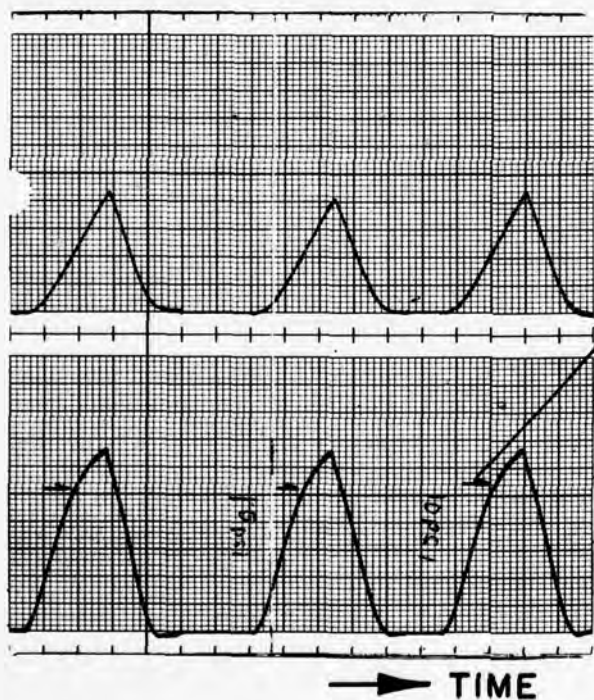
Figure 8. Arch Model in Test Apparatus.



FLEXIBILITY MEASUREMENT INWARD LOAD

↑ DISPLACEMENT
 $2.54 \times 10^{-3} \text{ m/DIV.}$

↑ FORCE
4.45 N/DIV.



WRINKLING LOAD MEASUREMENT

↑ DISPLACEMENT

DENOTES WRINKLING
LOAD MAGNITUDE

↑ FORCE
4.45 N/DIV.

FIBERGLASS ARCH
RADIUS : 0.965m
DIAMETER: 0.102m
PRESSURE: 69 kPa

Figure 9. Typical Recordings of the Force and Displacement From Arch Loading Tests.

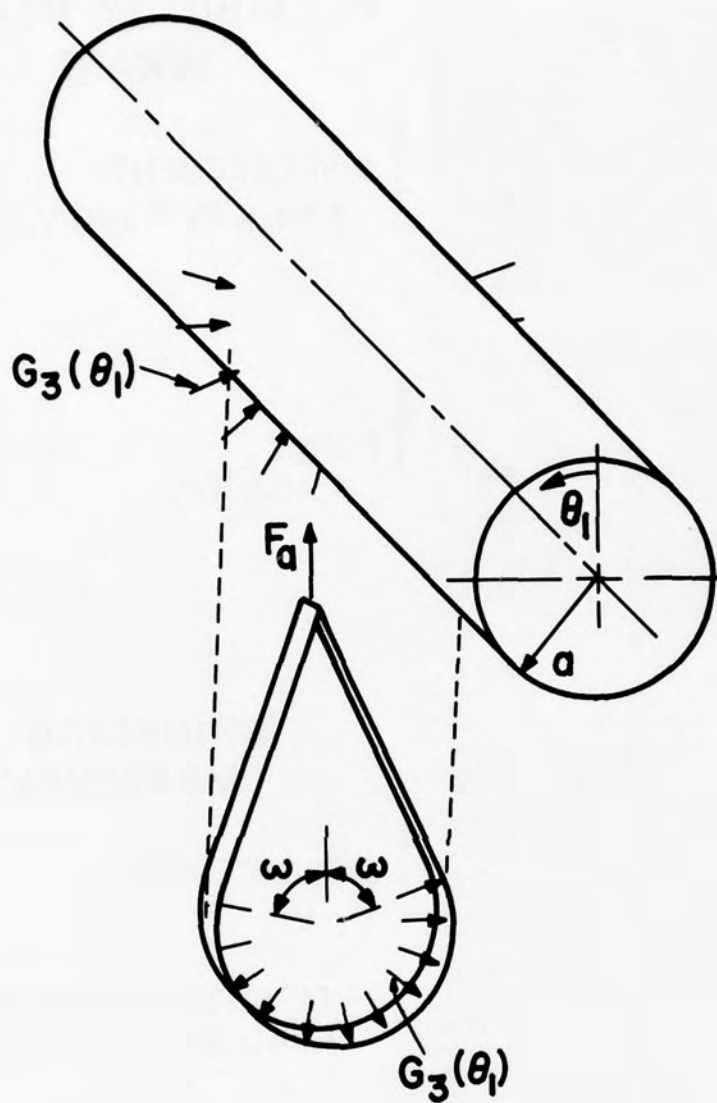


Figure 10. Arch Loading Technique

$$\bar{g}_1 = (1/\pi\bar{C}_{22}) \int_{\omega}^{2\pi-\omega} G_3(\theta_1) \cos(\theta_1) d\theta_1 \quad (50)$$

$$\bar{g}_3 = -(1/\pi\bar{C}_{22}) \int_{\omega}^{2\pi-\omega} G_3(\theta_1) \sin(\theta_1) d\theta_1 \quad (51)$$

Because of the symmetry of $G_3(\theta_1)$ about $\theta_1 = 0$, \bar{g}_3 vanishes and we need only be concerned with \bar{g}_1 . To obtain a relationship between \bar{g}_1 and F_a we observe that $G_3(\theta_1)$ also acts on the webbing used to apply the load and for equilibrium must have

$$F_a = \int_{\omega}^{2\pi-\omega} G_3(\theta_1) \cos(\theta_1) a d\theta_1 \quad (52)$$

Substitution of (52) into (50) gives

$$\bar{g}_1 = F_a / \pi a \bar{C}_{22}$$

the expression used to convert the measured applied load to the nondimensional force parameter. If the subscript w denotes wrinkling then the nondimensional wrinkling load is given in terms of the physical wrinkling load as

$$\bar{g}_{1w} = F_{aw} / \pi a \bar{C}_{22} \quad (53)$$

the magnitude of F_{aw} is determined experimentally by finding the value of F_a for which the loading curve becomes nonlinear. As can be seen from Figure 9, the transition from linear behavior to nonlinear behavior is smooth, making the evaluation of F_{aw} rather difficult. This difficulty is especially pronounced in comparison to the behavior of pressure-stabilized beams which, as reported in reference 4, exhibit a constant load jump in deflection as wrinkling begins. With such behavior it was quite easy to evaluate the wrinkling load from the loading curve.

The flexibility is the transverse displacement due to a unit load which in nondimensional form is:

$$\gamma = W/g_1 \quad (54)$$

Substituting the expressions for W and \bar{g}_1 gives the following expression for the nondimensional flexibility in terms of the measured force and displacement:

$$\gamma = \pi \bar{C}_{22} W / F_a \quad (55)$$

Determination of Material Stiffness Properties

In order to accomplish the objective of comparing the theory with experimental results obtained by the above described procedure, the elastic and shear moduli of the fabric used in the arches must be measured. These moduli are needed for the theoretical computation of the behavior of these fiberglass arches. These moduli or stiffnesses were determined from the results of tension and torsion tests. Although these tests are very similar to those commonly used, they were performed on specimens in their pressurized state of stress. Testing in this manner yields stiffnesses relative to a state of stress very close to that present in the arch loading tests, that is, uniaxial tension or shear superimposed on biaxial tension resulting from internal pressure. The moduli were measured using relatively small excursions from the pressurized state of stress, and the behavior was assumed to be linear over these excursions. Thus, for a given value of pressure, the elastic and shear moduli are constants. However, because of the nonlinear behavior of fabrics, these moduli were found to be dependent on the pressure level. This testing procedure had the additional advantage of yielding the moduli of the fabric skin-polyethylene film composite, and although the bladder is thought to make little contribution to the stiffness, any contribution is included. It should also be recalled that the arches were woven with a natural curved contour, and it was not possible to devise a simple test using curved specimens that would be suitable for measuring the elastic and shear moduli. We therefore obtained some straight woven fabric tubes having a cross-section radius of 0.038 m for use in determination of the moduli in tension and torsion tests. These straight tubes were woven with the same fiberglass yarns and plain weave design used in the contoured arches so the stiffness characteristic of the straight tubes should closely represent that of the arches.

Elastic Modulus

As indicated above, the elastic modulus was determined from the results of a tension test, as is shown schematically in Figure 11. After pressurizing the specimen the test is performed in the usual manner, applying an axial force F and measuring its magnitude along with the corresponding elongation, e . The theory requires the constant C_{22} relating the stress resultant, N_{22} , and the strain ϵ_{22} as

$$N_{22} = C_{22}\epsilon_{22}$$

Thus, C_{22} is the slope of the stress resultant-strain curve and can be computed from the force-elongation curve generated from the tension test by the expression

$$C_{22} = l_g \Delta F / 2\pi a \Delta e$$

where ΔF and Δe are respectively increments of applied force and specimen elongation. In the tests conducted, the specimen gage length, l_g , and the radius, a , were 0.343 m and 0.038 m, respectively. Typical force-elongation plots from these tests are shown in Figure 12.

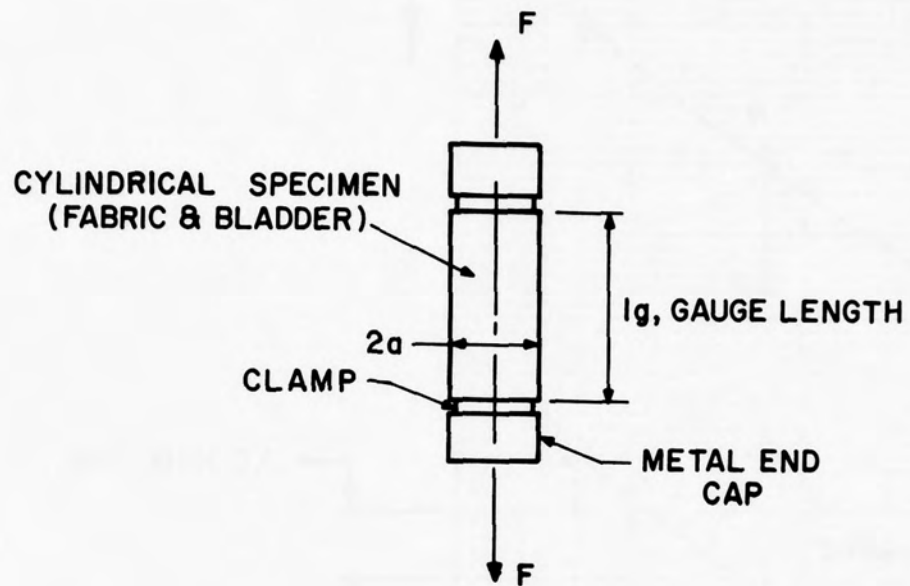
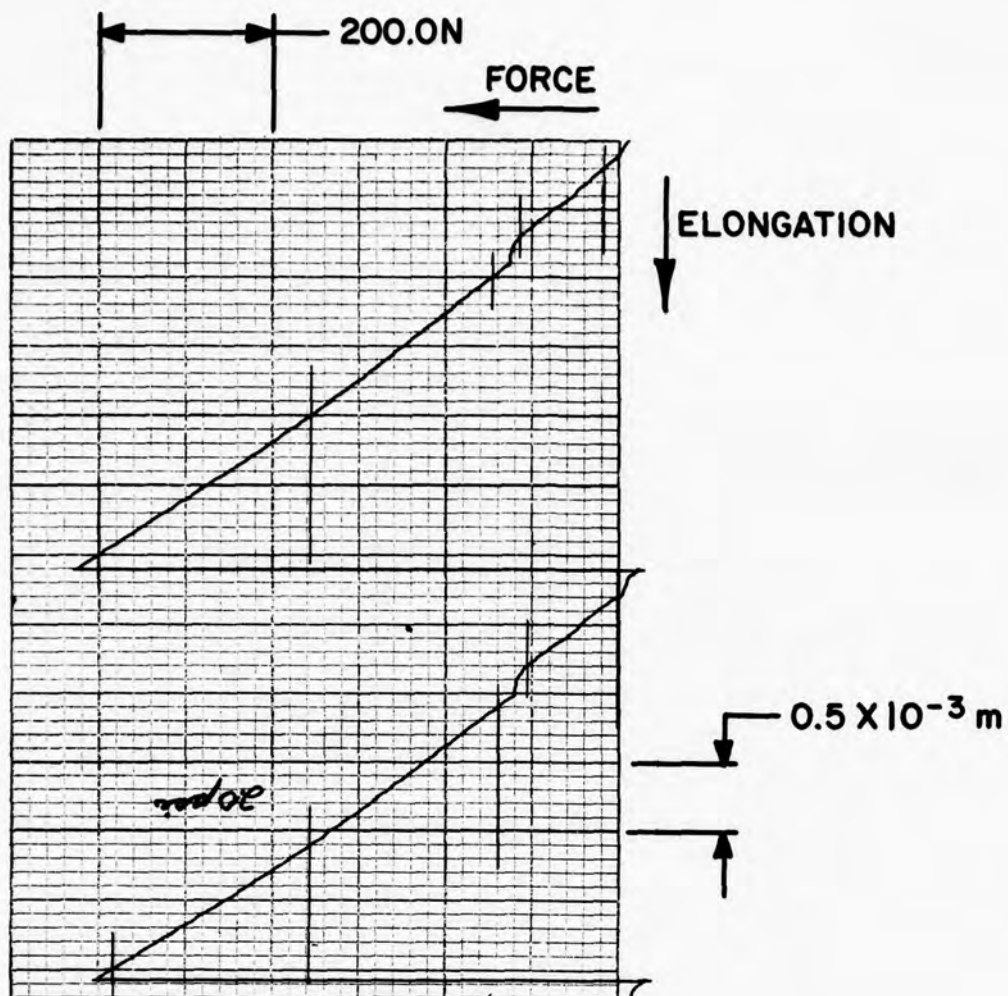


Figure 11. Schematic Diagram of the Tension Test



FIBERGLASS FABRIC WITH 4 MIL
POLYETHYLENE BLADDER

GAUGE LENGTH = 0.343m
RADIUS = 0.038m
PRESSURE = 138,000 Pa

Figure 12. Typical Force-Elongation Recordings From Tension Test.

Shear Modulus

The shear modulus was determined from the results of a torsion test, as shown schematically in Figure 13. This test is performed by inflating the specimen to a given pressure and applying a torque, T , about the axis of the cylinder and measuring ϕ , the rotation of the end of the cylinder. The theory requires the constant, C_{33} , relating the shear stress resultant, N_{12} , to the shear strain, ϵ_{12} , as

$$N_{12} = C_{33}\epsilon_{12}$$

The parameter C_{33} is the slope of the stress resultant-strain curve and can be computed from the torque-rotation curve generated from a torsion test by the expression

$$C_{33} = I_g \Delta T / 2\pi a^3 \Delta \phi$$

where ΔT and $\Delta \phi$ are, respectively, increments of applied torque and specimen rotation. The parameters, I_g and, a are as defined above and for the tests conducted have the values 0.267 m and 0.038 m, respectively. Typical torque and rotation plots from these tests are shown in Figure 14.

RESULTS AND DISCUSSION

In this section we will present the experimental results obtained with the procedures just described and compare the arch performance characteristics obtained experimentally with those predicted by the theory developed in this report.

Material Properties

The material properties required by the theory are the elastic modulus and the shear modulus. As is indicated above, these parameters are found as a function of pressure, as shown in Figures 15 and 16. In these figures are plotted the nondimensional elastic and shear moduli as a function of the nondimensional pressure parameter. These are the nondimensional parameters used in the theory with the value of the elastic modulus, C_{22} , for zero pressure being used as the reference value. It is denoted as \bar{C}_{22} . The pressure parameter which is used throughout this report is the nondimensional axial stress resultant due to internal pressure and is given in terms of the pressure, P , and the cross-section radius, a , as:

$$n = Pa/2\bar{C}_{22}$$

where n denotes the pressure parameter. In both Figures 15 and 16 the experimental results which are tabulated in Tables 1 and 2 are denoted by the symbols, and the least squares linear fits of the data used for the theoretical prediction of the arch behavior are shown both graphically and mathematically. The reference value of the elastic modulus, \bar{C}_{22} , is also given.

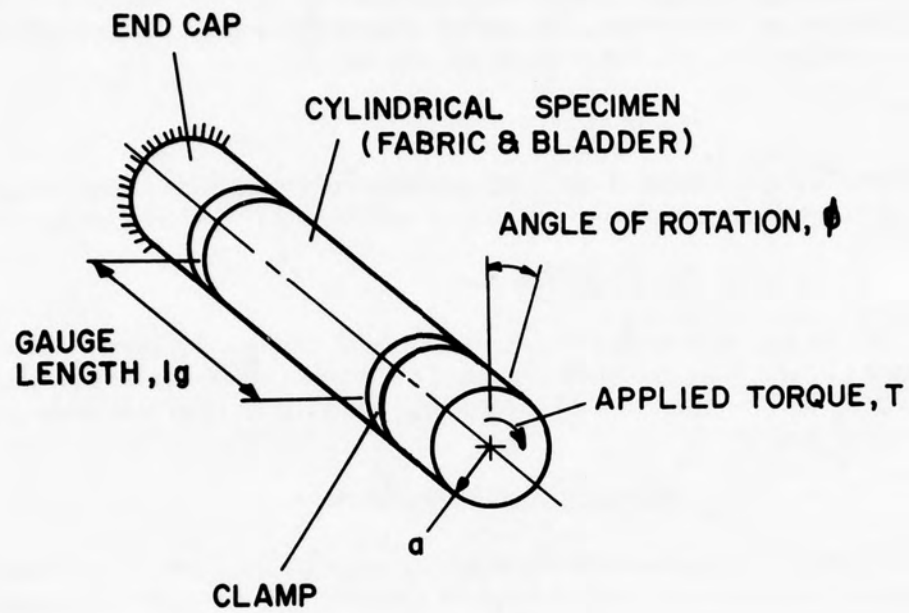


Figure 13. Schematic Diagram of the Torsion Test

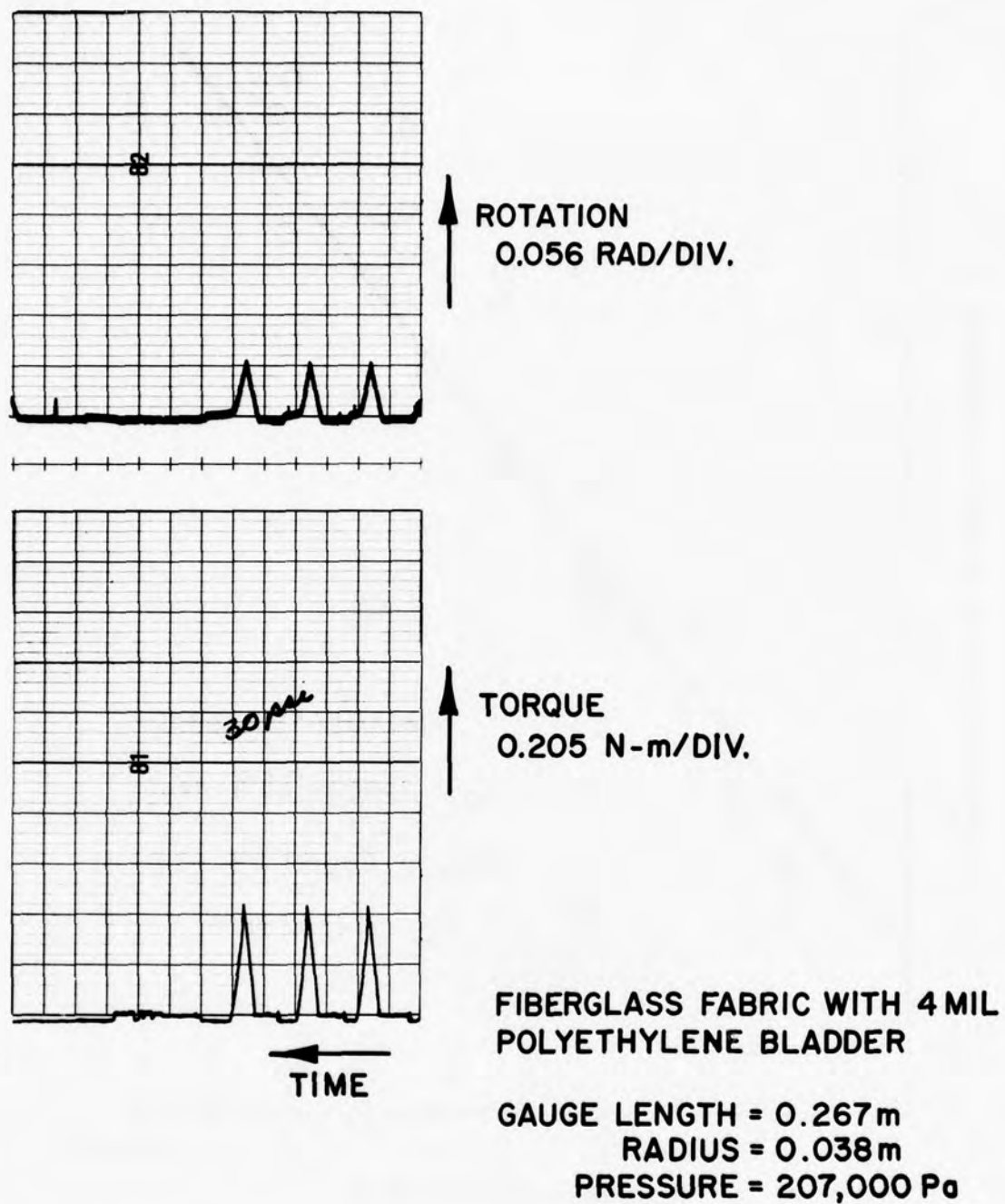


Figure 14. Typical Torque and Rotation Recordings From Torsion Test.

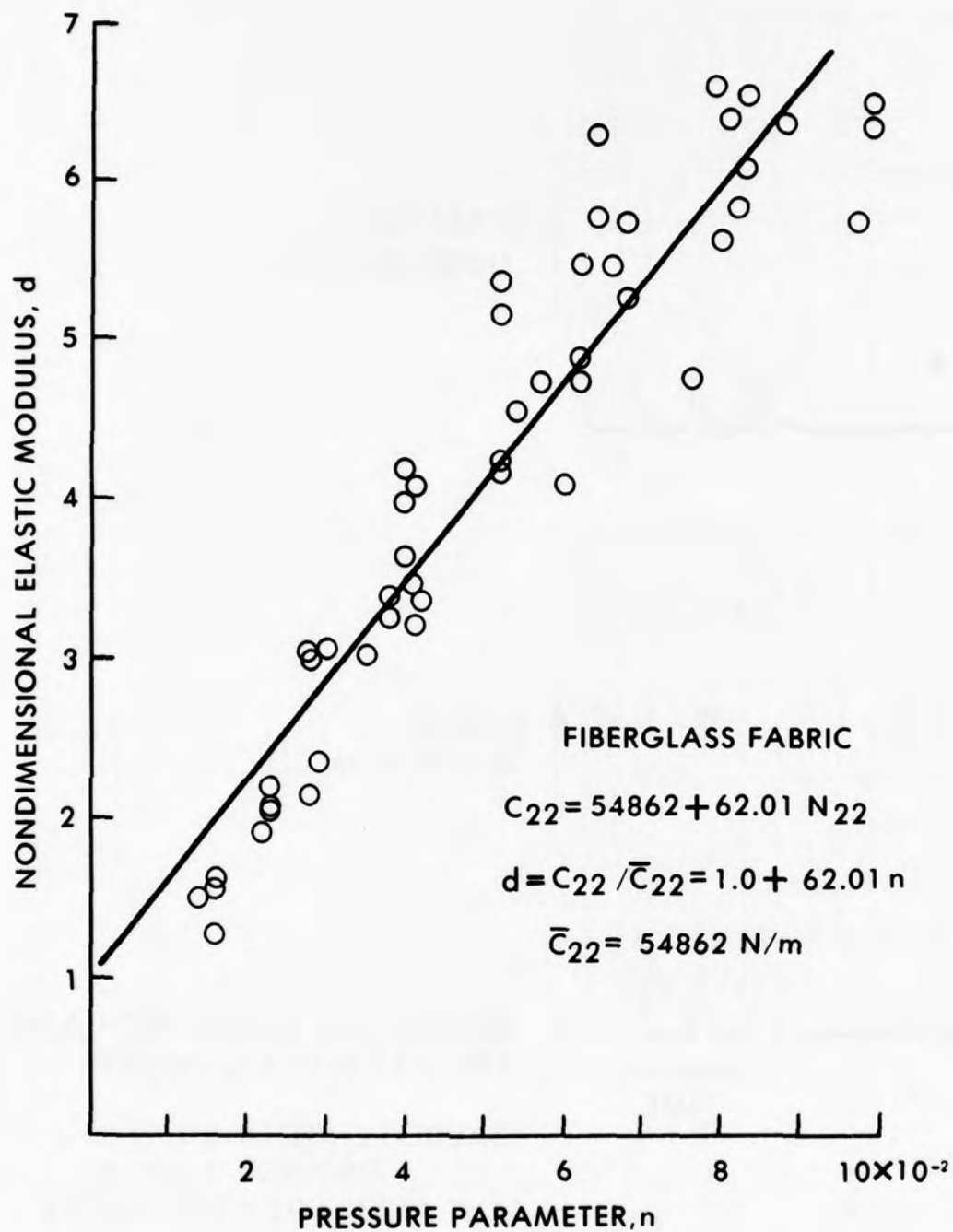


FIGURE 15. ELASTIC MODULUS AS A FUNCTION OF THE PRESSURE PARAMETER

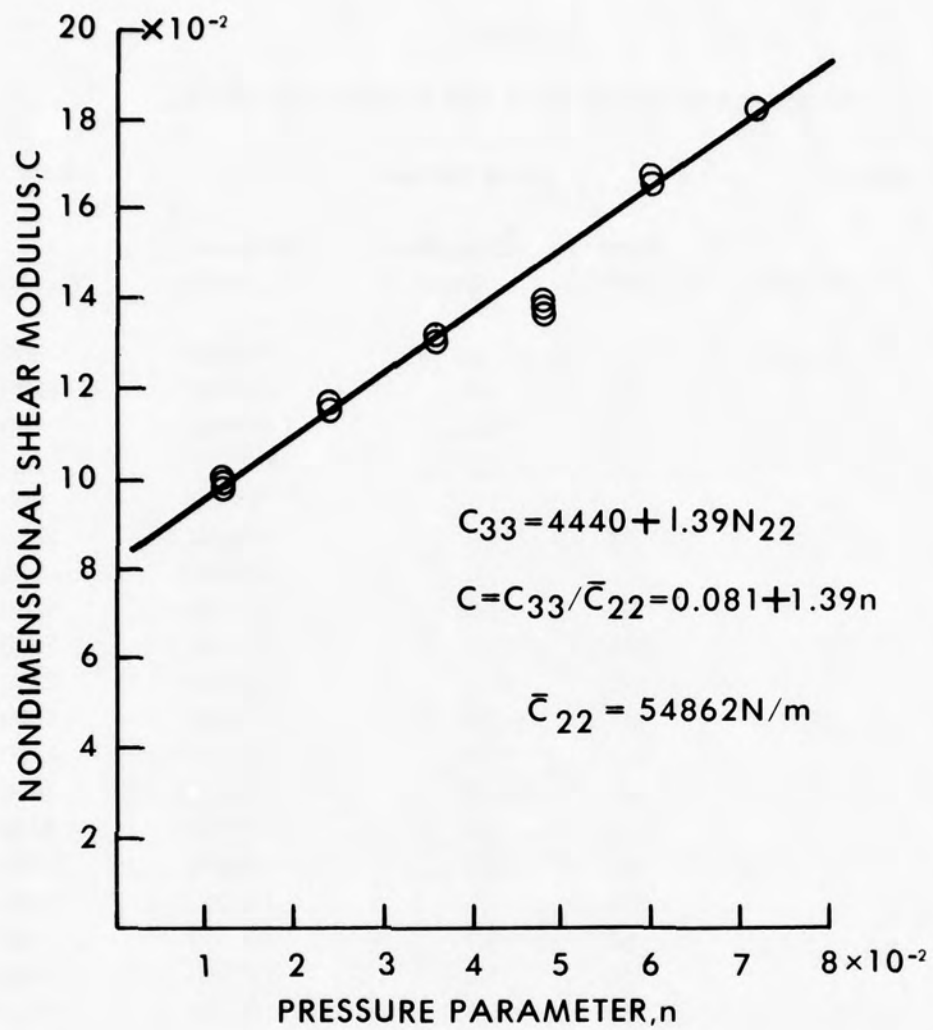


FIGURE 16. SHEAR MODULUS AS A FUNCTION OF THE PRESSURE PARAMETER

TABLE 1

ELASTIC STIFFNESS DATA FOR FIBERGLASS FABRIC

Pressure		Elastic Stiffness			Stress
P, kPa	n, Nondim	Force ΔF , N	Elongation Δe , m	Modulus $C_{22} = \text{N/m}$	N_{22} , N/m
34.5	0.012	49.	1.0×10^{-3}	70400	864
		58.	0.8	104100	1200
		57.	1.0	81900	780
		63.	0.8	113100	1280
		59.	1.0	84800	905
		79.	1.0	113500	1280
		61.	1.0	87600	864
		83.	1.0	119200	1280
		115.	1.0	165200	1910
		162.	1.0	232700	2830
69.0	0.024	81.	1.0	116400	1520
		122.	1.0	175300	2270
		94.	0.9	150000	1600
		132.	1.0	189600	2230
		82.	0.7	168300	1560
		138.	1.0	198200	2190
		80.	0.7	164100	1520
		124.	1.0	178100	2100
		81.	0.7	166200	1520
		129.	1.0	185300	2100
		81.	0.7	166200	1520
		128.	1.0	183900	2100
		173.	1.0	248500	2980
		182.	1.0	261400	4200

TABLE 1

ELASTIC STIFFNESS DATA FOR FIBERGLASS FABRIC (cont'd)

Pressure		Elastic Stiffness			Stress
P, kPa	n, Nondim	Force ΔF , N	Elongation Δe , m	Modulus C_{22} , N/m	N_{22} , N/m
103.5	0.036	64.	0.5×10^{-3}	183900	2300
		156.	1.0	224100	3300
		76.	0.5	218400	2220
		180.	1.0	258600	3390
		80.	0.5	229800	2220
		186.	1.0	267200	3390
		78.	0.5	224100	2260
		180.	1.0	258600	3140
		214.	1.0	307400	4390
		80.	0.5	229800	2870
		200.	1.0	287300	3710
		200.	0.9	319200	4500
138.0	0.048	98.	0.5	281600	2870
		208.	1.0	298800	3620
		243.	1.0	349100	4630
		102.	0.5	293100	2870
		218.	1.0	313200	3710
		224.	0.9	357600	4550
		120.	0.5	344800	3530
		232.	1.0	333300	4530
		218.	1.0	313200	5370
		104.	0.5	298800	3380
		244.	1.0	350500	4450
		242.	1.0	347600	5450
172.5	0.060	88.	0.4	316000	3530
		252.	1.0	362000	4360
		248.	1.0	356300	5450

TABLE 2

SHEAR STIFFNESS DATA FOR FIBERGLASS FABRIC

Pressure		Shear Stiffness		
P, kPa	n, Nondim.	Torque ΔT , N-m	Rotation $\Delta \phi$, rad.	Modulus C_{33} , N/m
34.5	0.012	2.32	0.319	5584.
		2.17	0.305	5510.
		2.32	0.346	5192.
69.0	0.024	2.82	0.346	6312.
		3.15	0.388	6287.
		2.71	0.332	6312.
103.5	0.036	3.11	0.332	7254.
		3.08	0.332	7184.
		3.11	0.332	7254.
138.0	0.048	3.13	0.319	7599.
		3.22	0.332	7511.
		3.58	0.360	7701.
172.5	0.060	3.94	0.332	9190.
		3.76	0.319	9128.
		3.66	0.305	9293.
207.0	0.072	3.93	0.305	9979.
		3.93	0.305	9979.
		3.93	0.305	9979.

In reducing the data for the elastic modulus, increments of axial force and elongation were taken from two or three segments of the plot as indicated in Figure 12. Once the modulus was computed using these increments a decision had to be made regarding the value of the pressure parameter or, equivalently, axial stress associated with this modulus. In previous work, reference 4, the pressure parameter, or axial stress due to pressure at which the test was run, was used. In those tests, however, only a short segment of the load-elongation curve beyond the pressurized state was used. In the present work, as indicated above, several segments beyond the pressurized state were used, and it was decided to use a corrected pressure parameter equal to the sum of the axial stress due to pressure and the axial stress due to axial load at the beginning of the increment used to calculate the modulus. This corrected value of the pressure parameter is given in the last column of Table 1 which is headed "Stress." The data from Table 1 is plotted on Figure 15 using this corrected pressure parameter.

The data in Figure 15 appears to have some curvature indicating that a higher order curve might provide a better fit. However, it was decided that in the present context a linear approximation would be sufficiently accurate.

It is interesting to compare the values of elastic stiffness used in the analysis with the limiting value obtained by considering the yarns as axial springs in parallel. The axial stiffness of a fiberglass yarn is given as 28.2 N/Tex. Thus for 512 yarns of 133 Tex in parallel, a stiffness of 1.92×10^6 N/m is obtained. The maximum value of stiffness used in the analysis is 0.62×10^6 N/m, for the 0.089-m cross-section radius at 207 kPa pressure. Thus the stiffnesses were all less than one-third of the limiting stiffness. The fiberglass was chosen for this work because it has a linear stress-strain behavior, and it was believed that this would simplify the analysis problems. As can be seen from the data shown here, the resulting fabric is far from linear. The stress-strain behavior exhibits a stiffening effect as stress is increased, which is typical of fabrics. Over the stress range shown in Figure 15 the stiffness increases by a factor of nearly seven. This is attributed to the yarn and fabric structure because fiberglass does have a linear stress-strain behavior in comparison with other materials used in fabrics such as nylon and dacron. This increase in stiffness of the fiberglass fabric is a marked contrast to very small increases for a dacron fabric and the absence of increases in a nylon fabric reported in reference 4. These facts illustrate some of the difficulties in testing fabrics as continuum structures.

The results from the torsion test are presented in Figure 16 in terms of a plot of the shear modulus as a function of the nondimensional pressure which is, as noted above, the nondimensional axial stress. These results are rather unremarkable, showing a shear stiffness of 10 to 18 percent of the reference elastic stiffness or modulus. These percentages are somewhat larger than those of the nylon and dacron fabrics of reference 4. Those fabrics had shear stiffness of 3 to 6 percent and 4 to 12 percent, respectively, of their reference elastic stiffness. However, the elastic stiffness of the nylon and dacron fabrics were found to be approximately three times the elastic stiffness of the present fiberglass fabric, so on an absolute basis the three fabrics have nearly equal shear stiffness.

Behavior of Arches Under Load

The results from the arch loading tests along with companion theoretical predictions are given in graphical form on Figures 17 through 24 for the four arches described earlier. The experimental data in numerical form on which the plots are based is given in Tables 3 through 6. For each arch a plot for both the flexibility and the wrinkling load as a function of pressure are included with the experimental results denoted by symbols and the theoretical predictions by the curves. The flexibility is defined as the deformation per unit applied force. The wrinkling load is the load for which the maximum compressive stress resulting from the applied load is equal in magnitude to the tensile stress resulting from pressurization. Since the fabric cannot resist compressive stress, any further increase in the applied load would cause wrinkling of the fabric. The flexibility and the wrinkling load are then, respectively, measures of the deformation behavior and the load-carrying capability.

Flexibility

The results for the arch flexibility are presented in Figures 17, 19, 21 and 23. Experimental results are given for the flexibility with the applied force directed inward, that is, toward the center of curvature of the arch and outward, away from the center of curvature. One would not expect these two cases to be significantly different, but for the arch with a radius ratio of 25.0, the flexibility for the inward force is significantly larger than that for the outward force. A similar situation exists for the arch having a radius ratio of 11.3 except the differences are not as great in this case. For the other two arches, the difference is of the order of magnitude of the experimental error. In general, the difference in the flexibility resulting from the change in loading direction is greatest at low pressures and becomes significantly smaller with increasing pressure. It will be observed that the flexibilities associated with the inward force are greater than those associated with the outward force except for the arch with a radius ratio of 13.0 and for this arch the opposite is true, but the differences are also the smallest for this case. A possible explanation of this behavior is a differential stiffness effect caused by the stress or internal force due to the applied load. In the arch, in contrast to the straight beam, lateral deformation is accompanied by an internal axial force which is positive for the outward force and negative for the inward force. This internal force is analogous to the internal force resulting from the pressure and if it is large enough can have the same influence. The pressure internal force is positive and decreases the flexibility of the arch. Therefore, if the internal force due to applied load were to have this same effect, it would be expected that under the outward force the arch would be less flexible than under the inward force, and this is what is observed. This phenomenon is not included in the theory since only the internal axial force due to pressure has an effect on the stiffness or flexibility of the arch. It should also be pointed out that this phenomenon is of no aid in explaining the disagreement between theory and experiment.

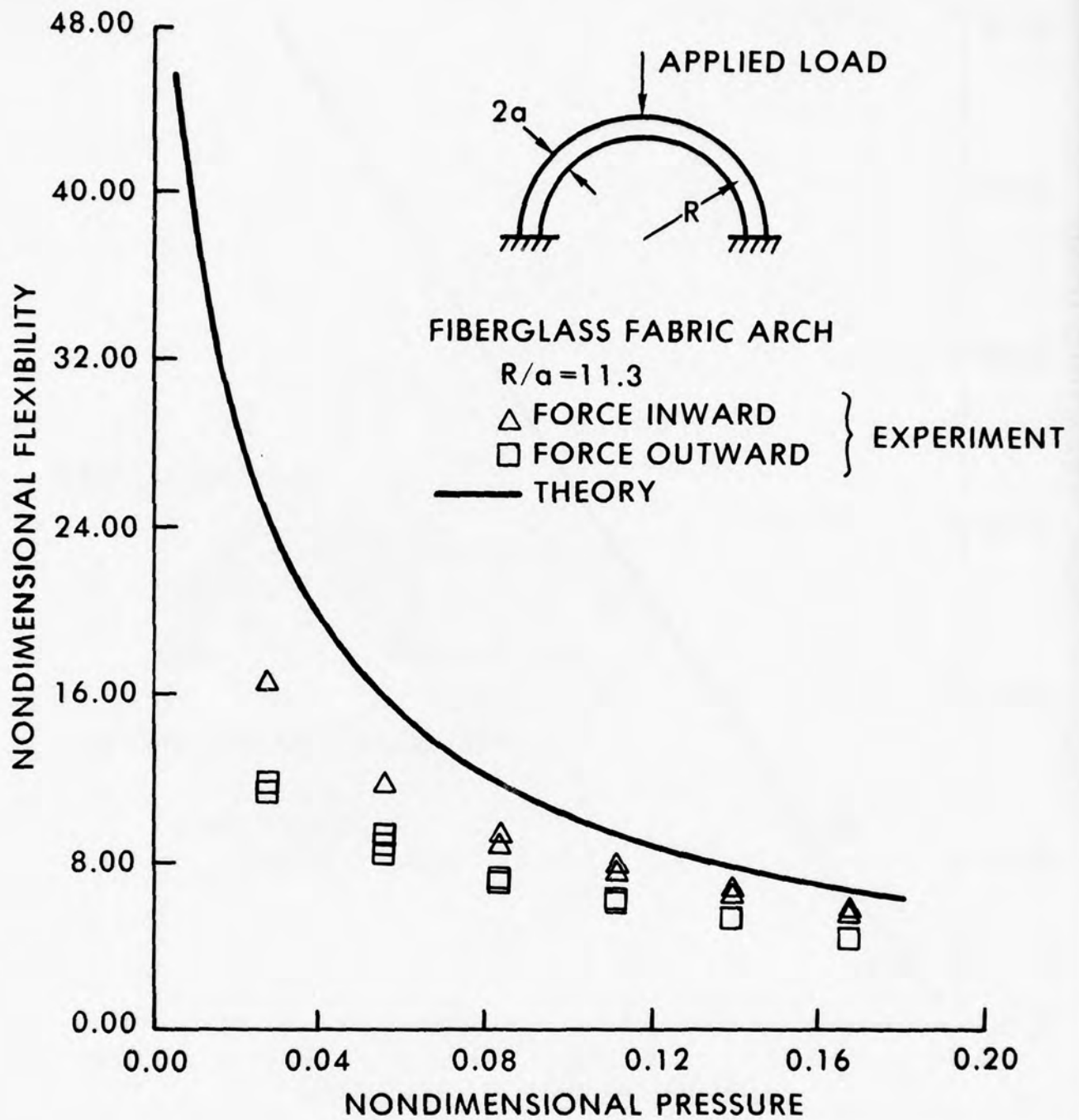


FIGURE 17. ARCH FLEXIBILITY AS A FUNCTION OF PRESSURE

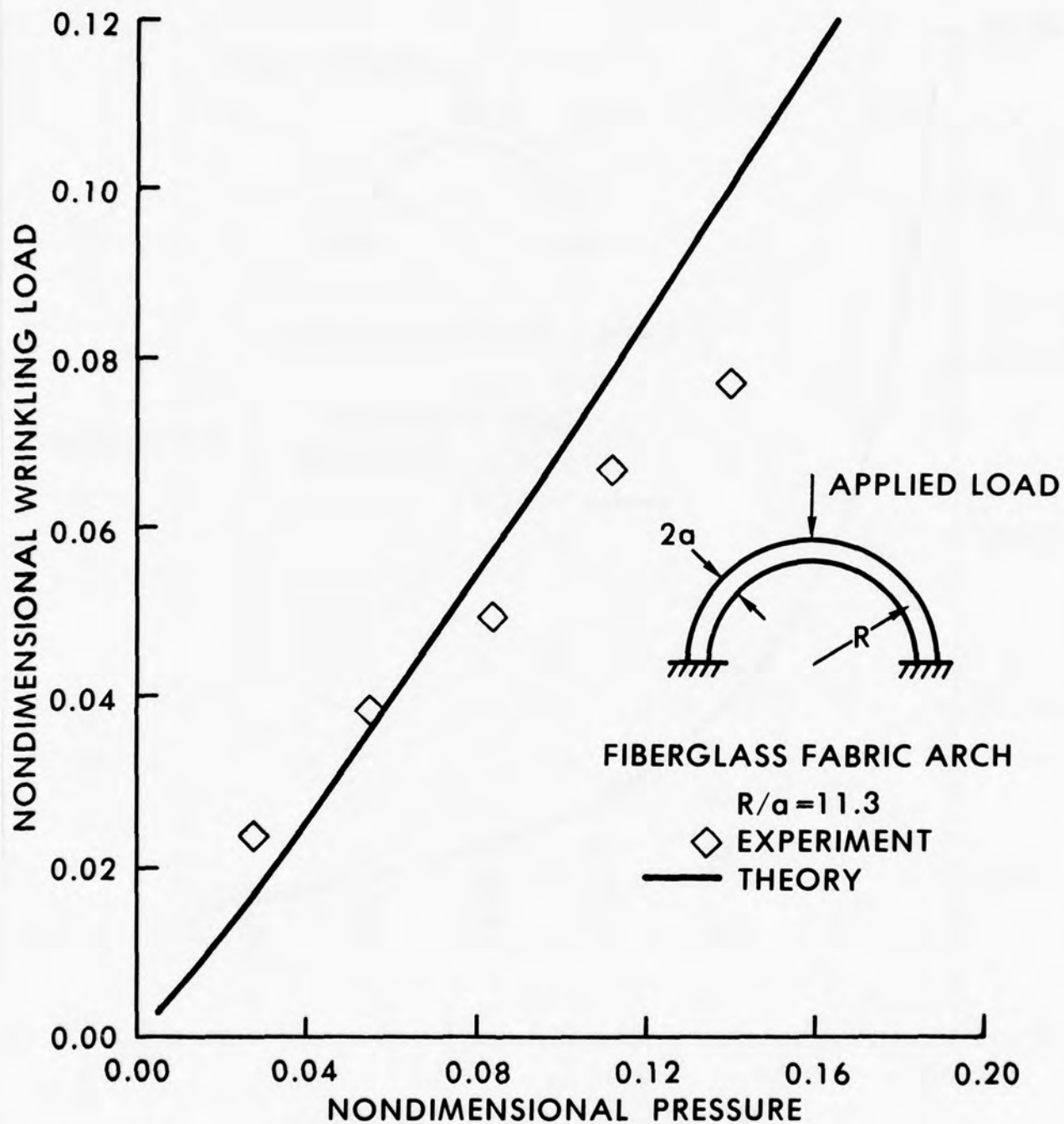


FIGURE 18. ARCH WRINKLING LOAD AS A FUNCTION OF PRESSURE

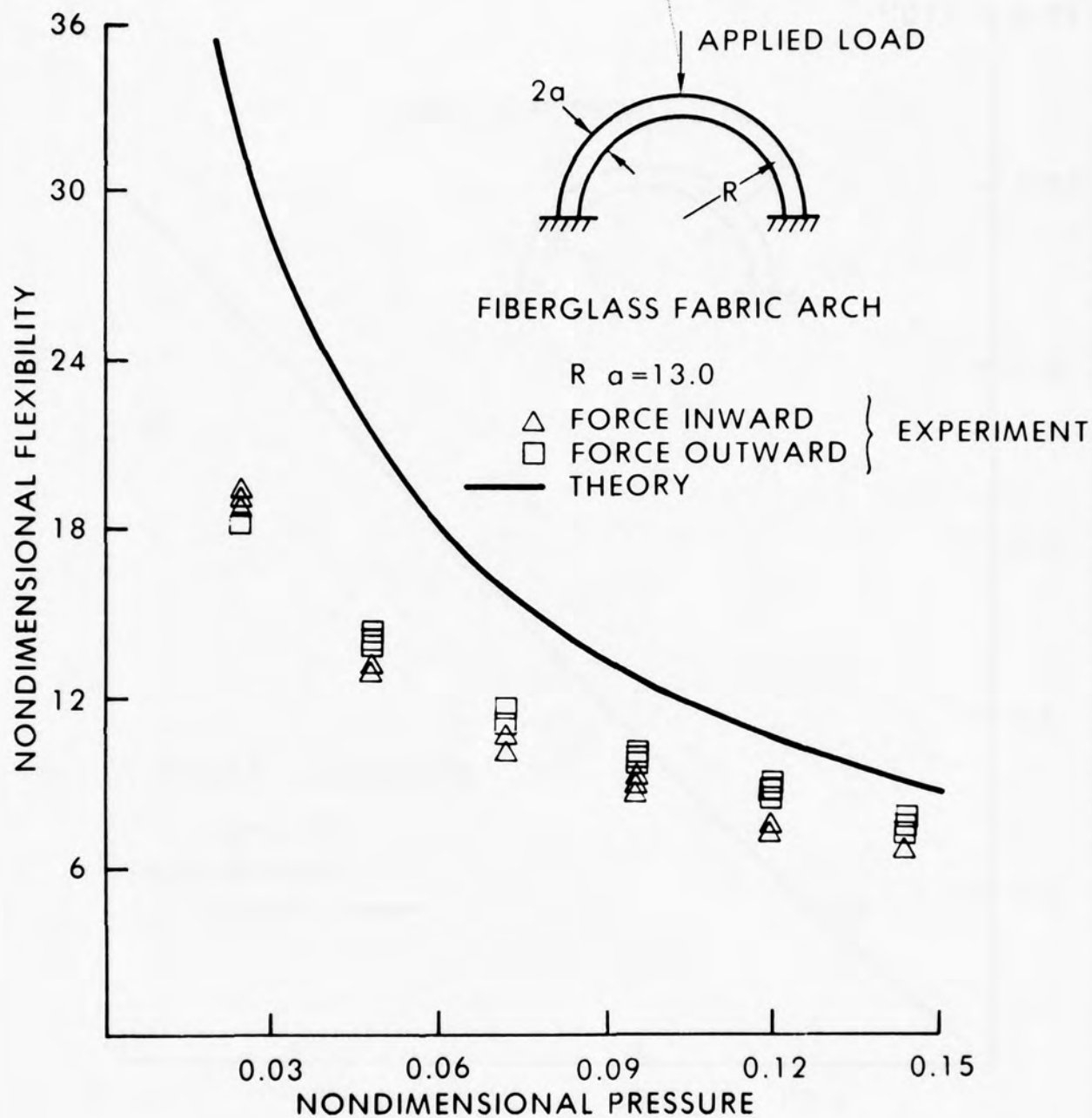


FIGURE 19. ARCH FLEXIBILITY AS A FUNCTION OF PRESSURE

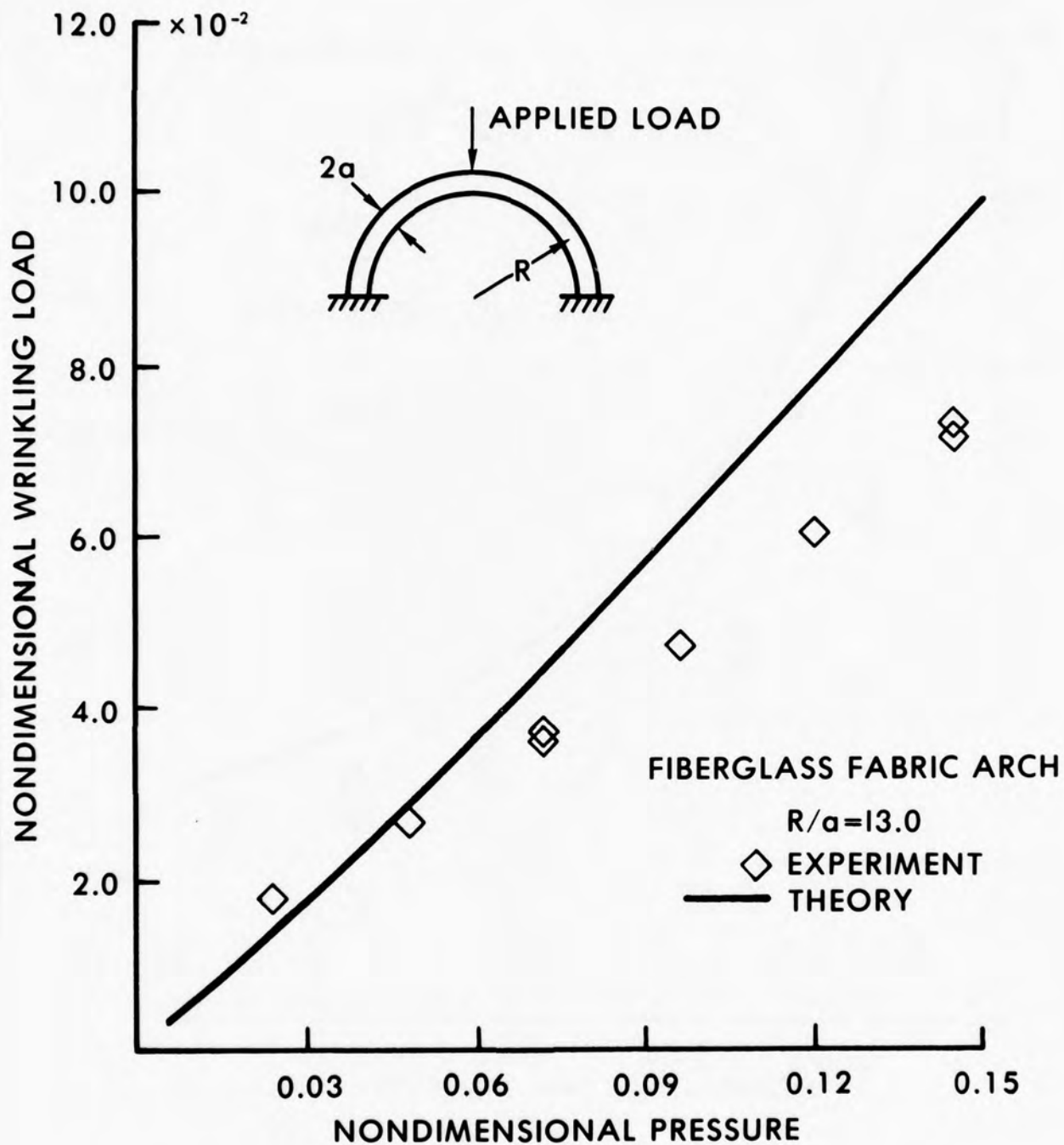


FIGURE 20. ARCH WRINKLING LOAD AS A FUNCTION OF PRESSURE

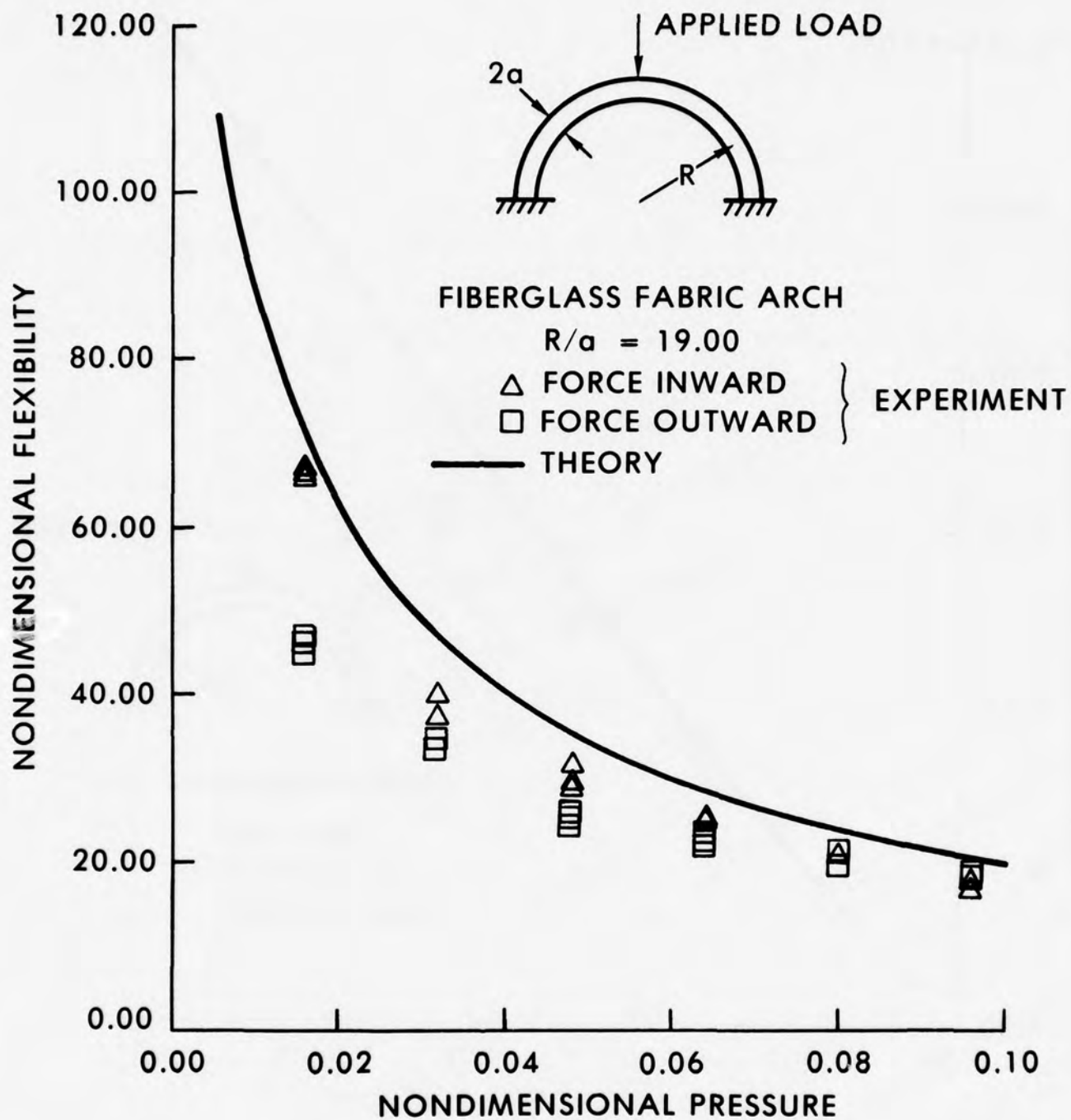


FIGURE 21. ARCH FLEXIBILITY AS A FUNCTION OF PRESSURE

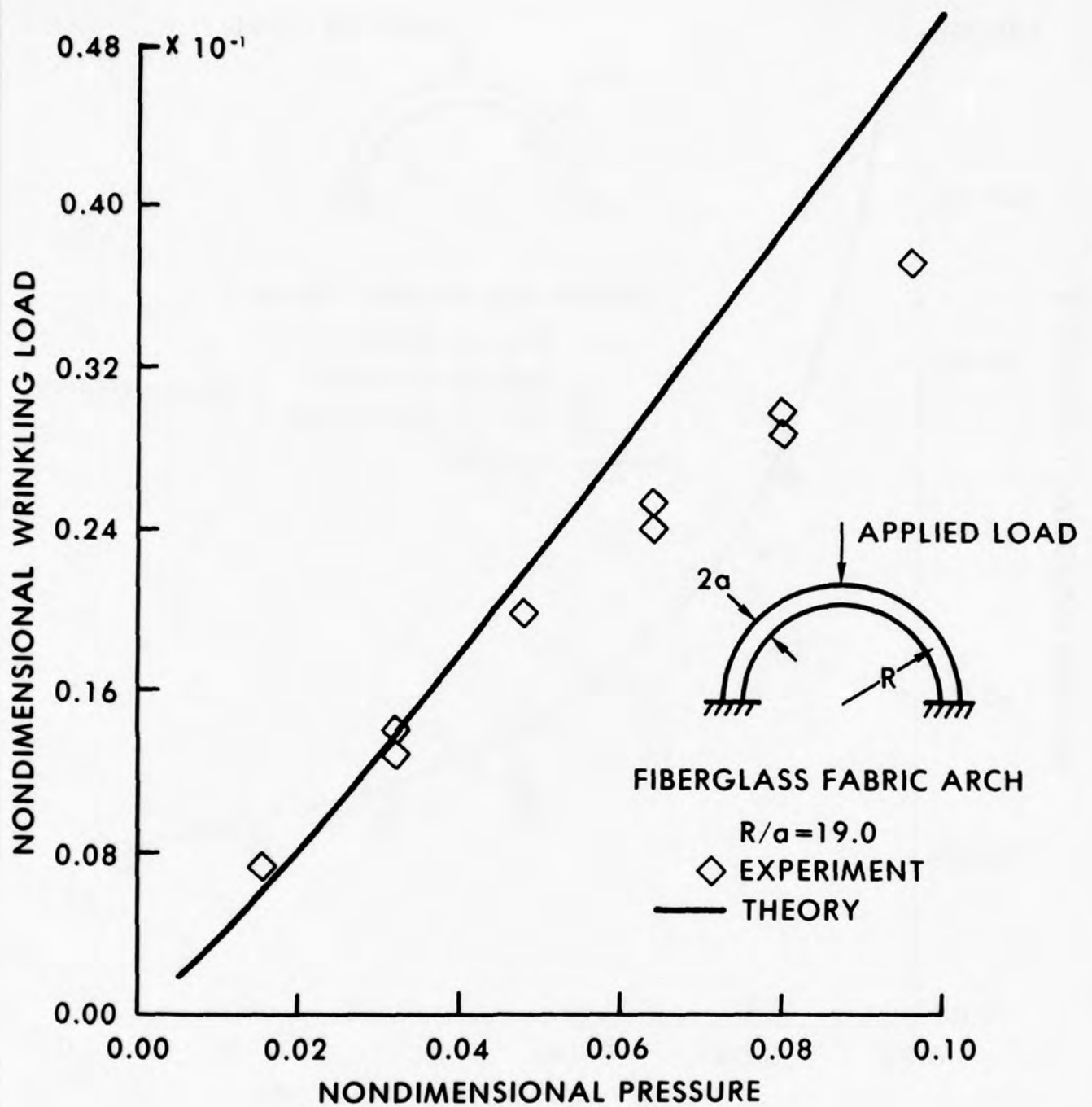


FIGURE 22. ARCH WRINKLING LOAD AS A FUNCTION OF PRESSURE

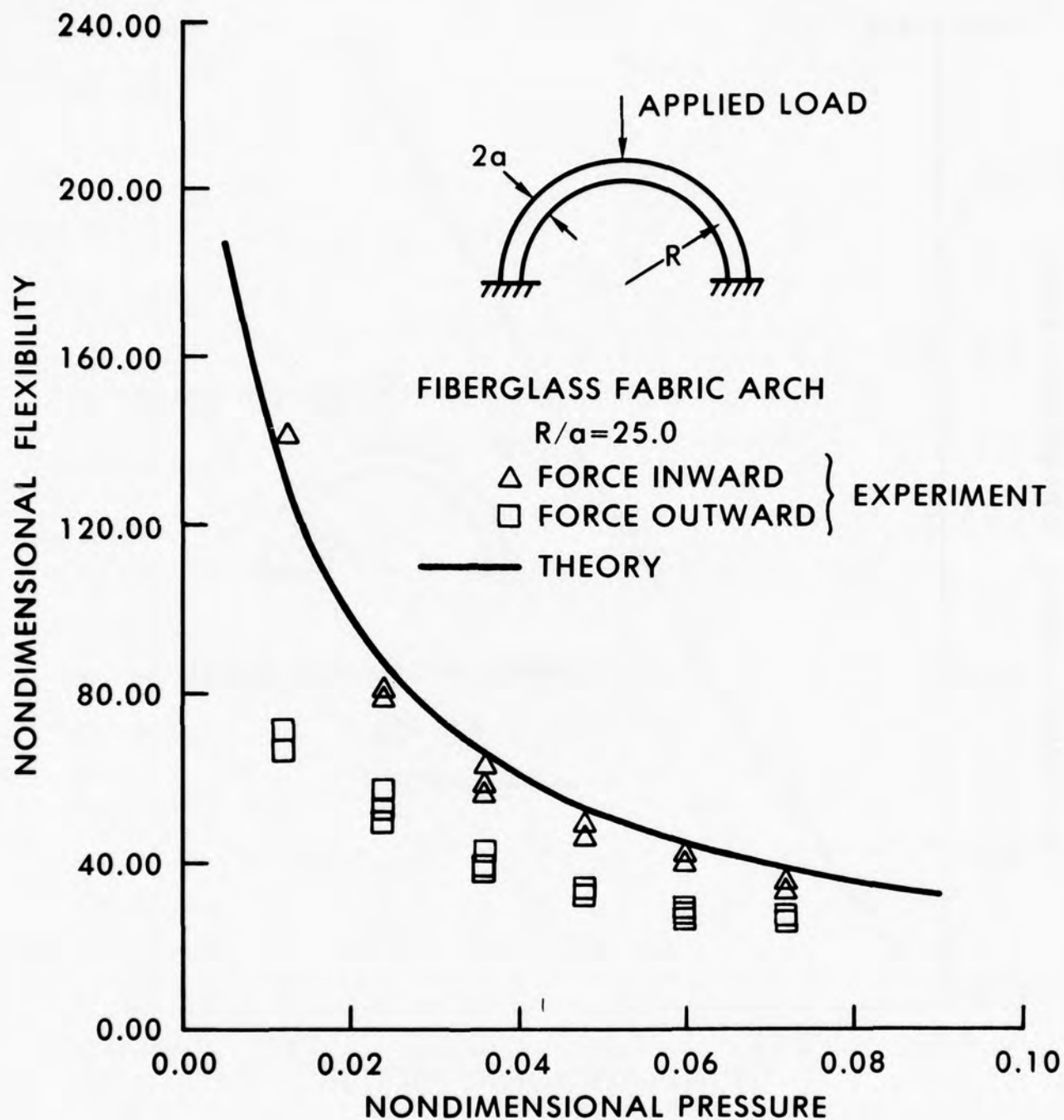


FIGURE 23. ARCH FLEXIBILITY AS A FUNCTION OF PRESSURE

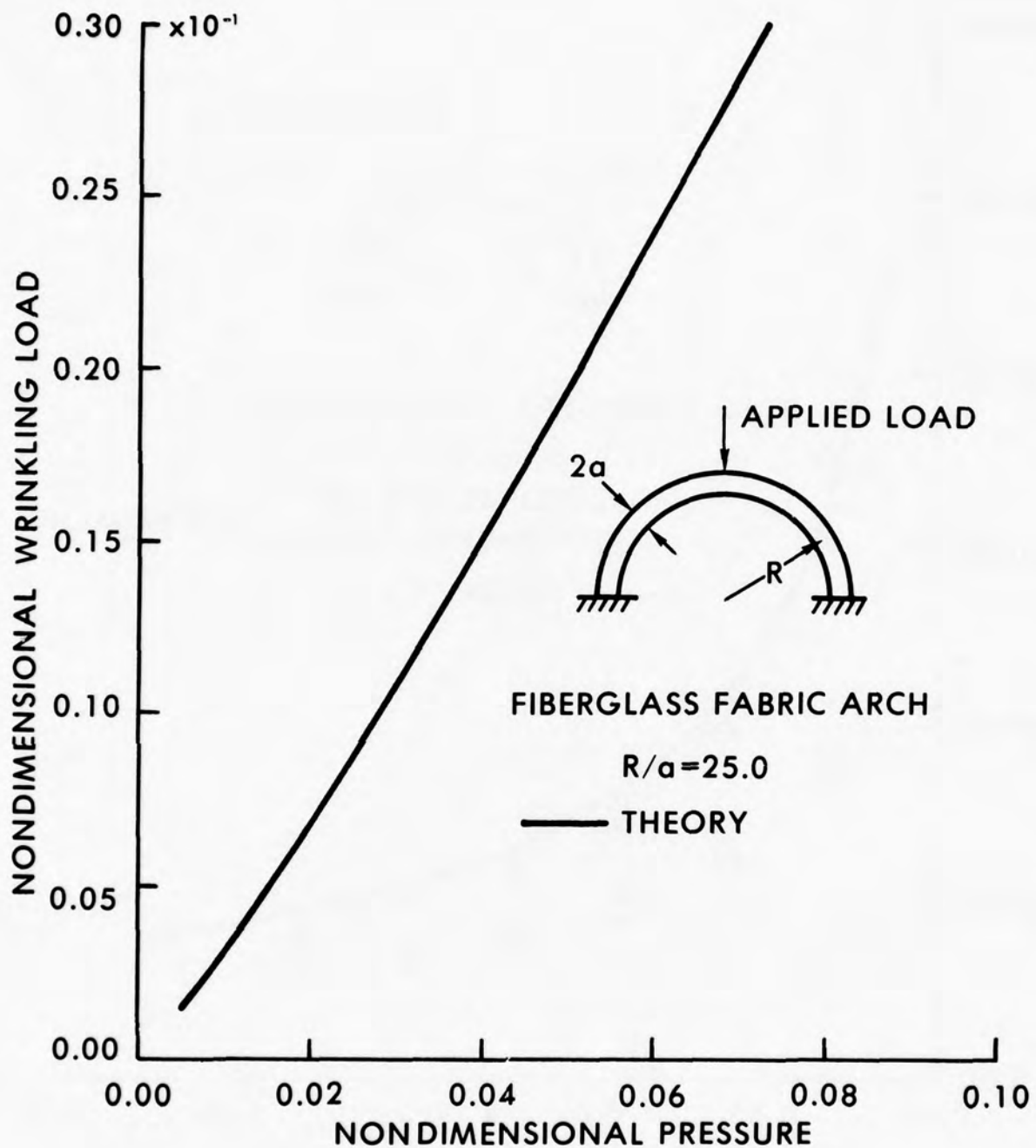


FIGURE 24. ARCH WRINKLING LOAD AS A FUNCTION OF PRESSURE

TABLE 3

TEST DATA FOR ARCH WITH $\rho = 11.3$

Flexibility

	Pressure		Force Outward		Force Inward		Wrinkling Load	
	P, kPa	n, Nondim.	w/Fa, m/N	γ , Nondim.	w/Fa, m/N	γ , Nondim.	Faw, N	gw, Nondim.
63	34.5	0.028	6.79 x 10 ⁻⁵	11.7	9.59 x 10 ⁻⁵	16.5	365.	2.38 x 10 ⁻²
			6.79	11.7	9.59	16.5	365.	2.38
			6.62	11.4	9.59	16.5	365.	2.38
	69.0	0.056	5.31	9.15	6.74	11.6	587.	3.83
			5.08	8.75	6.79	11.7	587.	3.83
			4.91	8.46	6.74	11.6	587.	3.83
	103.5	0.084	4.28	7.38	5.31	9.15	756.	4.93
			4.22	7.27	5.08	8.76	756.	4.93
			4.11	7.08	5.02	8.65	756.	4.93
	138.0	0.112	3.71	6.39	4.51	7.77	1023.	6.67
			3.65	6.29	4.34	7.48	1023.	6.67
			3.60	6.20	4.28	7.38	1023.	6.67
	172.5	0.140	3.25	5.60	3.88	6.69	1179.	7.69
			3.20	5.52	3.71	6.39	1179.	7.69
			3.20	5.52	3.71	6.39	1179.	7.69
	207.0	0.168	2.85	4.91	3.43	5.91		
			2.85	4.91	3.43	5.91		
			2.85	4.91	3.48	5.91		

TABLE 4

TEST DATA FOR ARCH WITH $\rho = 13.0$

Pressure		Flexibility				Wrinkling Load	
P, kPa	n, Nondim.	Force Outward		Force Inward		Faw, N	gw, Nondim.
		w/Fa, m/N	γ , Nondim.	w/Fa, m/N	γ , Nondim.		
64	34.5	0.024	10.9 $\times 10^{-5}$	18.8	11.4 $\times 10^{-5}$	19.6	1.76 $\times 10^{-2}$
			10.9	18.8	10.9	231.	1.76
			10.9	18.8	11.2	231.	1.76
	69.0	0.048	8.62	14.8	7.94	13.7	356.
			8.39	14.5	7.82	13.5	356.
			8.11	14.0	7.82	13.5	356.
	103.5	0.072	6.62	11.4	6.22	10.7	476.
			6.91	11.9	6.05	10.4	467.
			6.91	11.9	6.05	10.4	467.
	138.0	0.096	5.94	10.2	5.31	9.15	600.
			5.82	10.0	5.08	8.75	600.
			5.71	9.84	5.19	8.94	600.
	172.5	0.120	5.25	9.05	4.39	7.57	756.
			5.08	8.75	4.28	7.38	756.
			4.91	8.46	4.28	7.38	756.
	207.0	0.144	4.57	7.88	3.88	6.69	934.
			4.45	7.67	3.83	6.60	912.
			4.44	7.65	3.83	6.60	912.

TABLE 5
TEST DATA FOR ARCH WITH $\rho = 19$

	Pressure		Flexibility				Wrinkling Load	
	P, kPa	n, Nondim.	Force Outward		Force Inward		Faw, N	gw, Nondim.
			w/Fa, m/N	γ , Nondim.	w/Fa, m/N	γ , m/N		
69	34.5	0.016	26.9 $\times 10^{-5}$	46.4	38.6 $\times 10^{-5}$	66.5	62.3	0.71 $\times 10^{-2}$
			27.2	46.9	38.8	66.9	62.3	0.71
			26.2	45.1	38.3	66.0	62.3	0.71
	69.0	0.032	20.7	35.7	22.9	39.5	116.	1.32
			20.1	34.6	22.0	37.9	116.	1.32
			20.5	35.3	22.0	37.9	120.	1.36
	103.5	0.048	16.1	27.7	18.1	31.2	173.	1.97
			15.9	27.4	17.5	30.2	173.	1.97
			15.7	27.1	17.3	29.8	173.	1.97
	138.0	0.064	13.8	23.8	14.8	25.5	218.	2.48
			13.6	23.4	14.6	25.2	213.	2.42
			13.3	22.9	14.4	24.8	213.	2.42
	172.5	0.080	12.2	21.0	12.4	21.4	253.	2.88
			11.9	20.5	12.2	21.0	258.	2.93
			11.8	20.3	12.1	20.8	253.	2.88
	207.0	0.096	11.1	19.1	10.4	17.9	325.	3.70
			10.8	18.6	10.2	17.6	325.	3.70
			10.7	18.4	9.99	17.2	325.	3.70

TABLE 6

TEST DATA FOR ARCH WITH $\rho = 25$

Pressure		Flexibility				Wrinkling Load	
P, kPa	n, Nondim.	Force Outward		Force Inward		Faw, N	gw, Nondim.
		w/Fa, m/N	γ , Nondim.	w/Fa, m/N	γ , Nondim.		
99	34.5	0.012	40.8 $\times 10^{-5}$	70.3	81.6 $\times 10^{-5}$	140.6	
			39.1	67.4	81.6	140.6	
			39.1	67.4	81.6	140.6	
	69.0	0.024	32.8	56.5	45.7	78.8	
			30.7	52.9	46.4	80.0	
			29.4	50.7	46.4	80.0	
	103.5	0.036	24.2	41.7	37.3	64.3	
			22.8	39.3	35.5	61.2	
			22.4	38.6	35.9	61.9	
	138.0	0.048	19.3	33.3	29.0	50.0	
			18.7	32.2	27.9	48.1	
			18.7	32.2	27.7	47.7	
	172.5	0.060	16.3	28.1	24.8	42.7	
			15.6	26.9	23.6	40.7	
			15.9	27.4	23.8	41.0	
	207.0	0.072	15.6	26.9	21.0	36.2	
			14.8	25.5	20.4	35.2	
			14.8	25.5	20.3	35.0	

Both the theory and experiment show the same general behavior of the flexibility with pressure. Much like that found for pressure-stabilized beams, the flexibility of the arch varies inversely with the pressure. The theory is in better agreement with the experimental results for the inward force, and the quality of the agreement ranges from *good* over the entire pressure range for the arches with radius ratios of 25.0 and 19.0 to *poor* for the other two arches at the lower pressures. In general, agreement between theory and experiment is better at higher pressures and for larger radius ratios. The theory predicts the arches to be more flexible than they are found to be experimentally. This is somewhat unexpected because we are dealing with fixed end restraints, and it is always an experimental problem to attain full fixity of the ends. Since fixity in the theory can be attained perfectly, it is expected that the theoretical prediction will be less flexible than the experimental results. This anomaly, along with other differences between theory and experiment, may result from the treatment of the nonlinear stress-strain behavior of the fiberglass fabric, that is, linearizing it about the pressurized state. An additional factor that could contribute to the lack of agreement between theory and experiment is the use of straight woven tubes to measure the fabric moduli or stiffnesses used in the theoretical representation of the contoured arch behavior.

Wrinkling Load

The wrinkling load results are presented in Figures 18, 20, 22 and 24 which show the wrinkling as determined both experimentally and theoretically, increasing monotonically with pressure. In the lower pressure range the increase in the wrinkling load is seen to be more rapid than a linear function, but at higher pressures the behavior is essentially linear. It should be noted that these experimental results are for the applied force directed inward, since this loading puts the arch in a compressive state of stress, thus making wrinkling possible. Experimental wrinkling load data were not collected for the arch having a radius ratio of 25.0 because of experimental difficulties in getting the arch inflated without distortion. The fiberglass fabric was very easily distorted when not inflated and any such distortion had to be corrected as the arch was inflated. This difficulty was more pronounced with the arches having the larger radius ratios. For the arch with radius ratio equal to 25.0 we were able to inflate the arch satisfactorily for the flexibility tests but could not inflate it without distortion for the wrinkling load determination. The theory is in good agreement with the experimental results in the low and middle pressure ranges but beyond this middle range the agreement becomes poorer as the pressure increases. It is speculated that, as with the flexibility, the disagreement is partly due to the linearization of the stress-strain behavior of the fabric and the use of straight fiberglass fabric tube to determine the stiffnesses used to represent the three-dimensionally woven fabric arches. As will be shown below, increases in stiffness decrease the wrinkling load; therefore, the disagreement between theory and experiment for the wrinkling load is consistent with that for the flexibility. This work was begun under the assumption that the mode of failure would be wrinkling and not geometric instability, a possible failure mode for arch structures. The conduct of the experiments confirmed this assumption. The wrinkle formation could not be observed because it was covered by the strap used in the load application. However, the failure was a gradual one with no

out-of-plane deformation. This is in contrast to the character of instability failures which occur rapidly and are accompanied by out-of-plane deformation. In addition, the agreement between the theoretical prediction and the experimental determination of the wrinkling load substantiates the belief that the experimental failures occurred by the wrinkling mode and not as the result of instability.

It will be recalled that the elastic modulus of the fiberglass fabric used in these arches varied widely with the pressure parameter. This variation has an impact on the load-carrying capability of the arches as measured by the wrinkling load. The nondimensional wrinkling load is computed from the theory by the relation

$$g_w = n/\epsilon_m E(n)$$

where g_w is the nondimensional wrinkling load, n is the pressure parameter, ϵ_m is the absolute value of the maximum compressive strain and $E(n)$ is the nondimensional elastic modulus, a function of the pressure parameter. If $E(n)$ is a constant, that is, not a function of pressure, the wrinkling load increases with pressure by two factors; first, the increase in pressure itself and secondly the decrease in ϵ_m as a result of the increased stiffness caused by the pressure increase. When the elastic modulus is a function of the pressure there are two competing effects. The strain ϵ_m tends to decrease because of the stiffness increase due to both increases in pressure and the corresponding increase in $E(n)$. This decrease in strain magnitude is, however, diminished by the increased magnitude of $E(n)$. This situation is shown graphically in Figure 25, where we have a plot of the wrinkling load as a function of pressure. The different curves in this plot represent the behavior of the wrinkling load for different rates of increase of the elastic modulus. The modulus is a linear function of the pressure parameter, and the slope of this linear function is the parameter that changes in Figure 25. Thus the curve $\sigma = 0$ represents the case where $E(n)$ is a constant and that for $\sigma = 62.0$ is the behavior of the arch described in this report. The remaining curve is for intermediate rate of increase. It is clear from these results that the increase in the stiffness more than overcomes the decrease in strain resulting in a net loss in load-carrying capability. Thus to obtain the most benefit in load-carrying capability from increases in pressure, it is desirable to have the smallest increase in elastic stiffness due to pressure of the fabric used to make the arch.

These results illustrate the deformation and load-carrying capability of pressure-stabilized arches, and the comparisons of the experimental and theoretical results give confidence that the theory can predict the behavior. The theory can then serve as a useful design tool.

CONCLUDING REMARKS

The development of a linear theory for the behavior of pressure-stabilized arches under static load has been presented and solutions to the resulting governing equations obtained. Solutions were obtained in the form of a Green's Function from which solutions to general loading can be obtained. In addition, a particular solution for the uniform

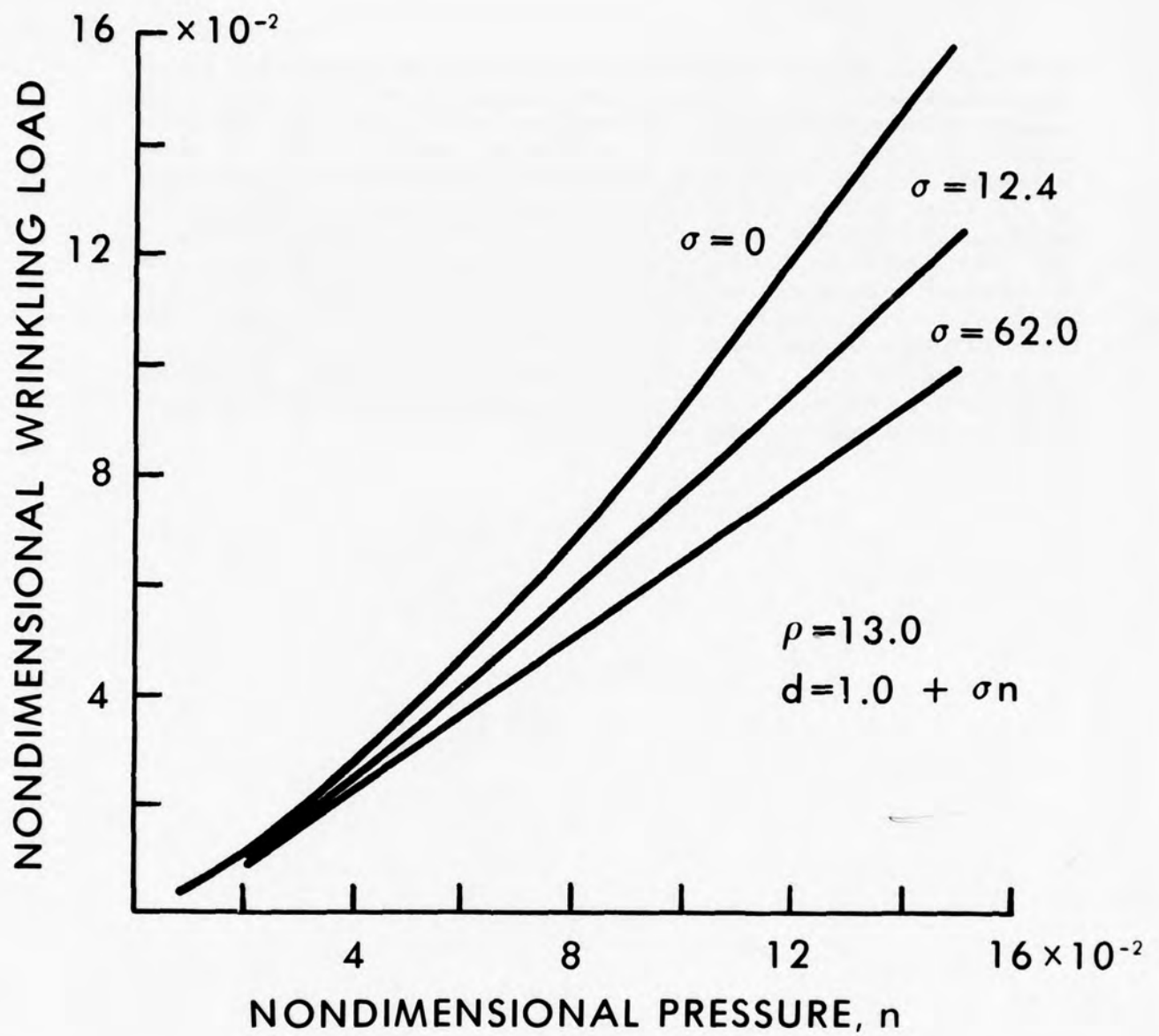


FIGURE 25. EFFECT OF MATERIAL STIFFNESS INCREASE WITH PRESSURE ON THE WRINKLING LOAD

normal load was obtained. Because of the complexity of the solutions, they are not written down explicitly but a computer program is given to carry out the solution and compute the results in terms of the deformation and stress behavior. An experimental program to measure the deformation and load-carrying capability of a series of arches is described along with measurements of elastic and shear stiffnesses of the fabric used for the arches. Results of this experimental program are presented and compared with predictions from the theory. These results are given in terms of the flexibility and wrinkling load which describe the deformation and load-carrying capability of the arches. The flexibility and wrinkling load are presented for inflation pressures ranging from 34.5 to 207.0 kPa for four arches having radius ratios of 11.3, 13.0, 19.0, and 25.0. The agreement between the experimental and theoretical results establishes the theory as being adequate for the prediction of the deformation and load-carrying capability of pressure-stabilized arches. Thus the study can provide a rational basis for the structural design of shelters using pressure-stabilized arches.

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APPENDIX A
DEVELOPMENT OF THE ONE-DIMENSIONAL ENERGY PRINCIPLE

APPENDIX A

DEVELOPMENT OF THE ONE-DIMENSIONAL ENERGY PRINCIPLE

The two-dimensional energy principle in terms of the cross-section displacements and rotation is

$$\begin{aligned}
 & \delta \int_{\theta_2} \int_0^{2\pi} 1/2 \left\{ C_{22}/\alpha_2^2 [(U' - W) - \phi'_y \cos(\theta_1) - \right. \\
 & (\phi'_z + \phi_x) \sin(\theta_1)]^2 + C_{33}/\alpha_2^2 [a(\phi'_x - \phi_z) + \\
 & (W' + U + R\phi_y) \sin(\theta_1) + (V' - R\phi_z) \cos(\theta_1)]^2 + \\
 & N_{22}^0/\alpha_2^2 [(U + W') \cos(\theta_1) - V' \sin(\theta_1) - \phi_y \cos^2(\theta_1) - \\
 & \phi_z \sin(\theta_1) \cos(\theta_1)]^2 - 2F_1 [a\phi_x + W \sin(\theta_1) + V \cos(\theta_1)] - \\
 & 2F_2 [U - \phi_y \cos(\theta_1) - \phi_z \sin(\theta_1)] - \\
 & \left. 2F_3 [V \sin(\theta_1) - W \cos(\theta_1)] \right\} \alpha_2 a d\theta_1 d\theta_2
 \end{aligned} \tag{A1}$$

Expanding this expression we obtain

$$\begin{aligned}
 & \delta \int_{\theta_2} \int_0^{2\pi} 1/2 \left\{ \frac{C_{22}}{R^2(1 + a/R \cos(\theta_1))} [(U' - W)^2 + (a\phi'_y)^2 \cos^2(\theta_1) + \right. \\
 & (a\phi'_z + a\phi_x)^2 \sin^2(\theta_1) - 2(U' - W)\phi'_y \cos(\theta_1) \\
 & - 2(U' - W)(\phi'_z + \phi_x) \sin(\theta_1) + 2\phi'_y(\phi'_z + \phi_x)a^2 \sin(\theta_1) \cos(\theta_1)] + \\
 & \frac{C_{33}}{R^2(1 + a/R \cos(\theta_1))} [(a\phi'_x - a\phi_z)^2 + (W' + U + R\phi_y)^2 \sin^2(\theta_1) + \\
 & (V' - R\phi_z)^2 \cos^2(\theta_1) + 2(W' + U + R\phi_y)(\phi'_x - \phi_z) \sin(\theta_1) + \\
 & 2(\phi'_x - \phi_z)(V' - R\phi_z) \cos(\theta_1) + 2(W' + U + R\phi_y)(V' - R\phi_z) \cos(\theta_1) \sin(\theta_1)] +
 \end{aligned} \tag{A2}$$

$$\begin{aligned}
& \frac{N_{22}^0}{R^2(1 + a/R \cos(\theta_1))} [(U + W')^2 \cos^2(\theta_1) + (V')^2 \sin^2(\theta_1) + (\phi_Y a)^2 \cos^4(\theta_1) + \\
& (a\phi_Z)^2 \sin^2(\theta_1) \cos^2(\theta_1) - 2(U + W')V' \cos(\theta_1) \sin(\theta_1) - \\
& 2(U + W')\phi_Y a \cos^3(\theta_1) - 2(U + W')\phi_Z a \sin(\theta_1) \cos^2(\theta_1) + \\
& 2V'\phi_Y a \sin(\theta_1) \cos^2(\theta_1) + 2V'\phi_Z a \sin^2(\theta_1) \cos(\theta_1) + \\
& 2\phi_Y \phi_Z a^2 \sin(\theta_1) \cos^3(\theta_1)] - 2(1 + a/R \cos(\theta_1)) [UF_2 + \\
& W(F_1 \sin(\theta_1) - F_3 \cos(\theta_1)) + V(F_1 \cos(\theta_1) + F_3 \sin(\theta_1)) + \\
& \phi_X a F_1 - \phi_Y a F_2 \cos(\theta_1) - \phi_Z a F_2 \sin(\theta_1)] \} a R d\theta_1 d\theta_2 = 0
\end{aligned}$$

The θ_1 dependence is all in explicit form in equation (A2), and we can thus evaluate the integrals with respect to θ_1 and this is done as follows, starting with

$$\int_0^{2\pi} \frac{(a/R)^4 \cos^4(\theta_1)}{1 + (a/R) \cos(\theta_1)} d\theta_1 = \pi \left(\frac{a}{R}\right)^4 Z \quad (A3)$$

which is a definition of Z for which a formula will be given later. It should be noted that Z has a nonvanishing limit as a/R becomes very small. To aid in the evaluation of the remaining integrals note that (A3) can be written with the aid of the binomial expansion as:

$$\int_0^{2\pi} \frac{(a/R)^4 \cos^4(\theta_1)}{1 + (a/R) \cos(\theta_1)} d\theta_1 = \quad (A4)$$

$$\int_0^{2\pi} \left[\left(\frac{a}{R}\right)^4 \cos^4(\theta_1) - \left(\frac{a}{R}\right)^5 \cos^5(\theta_1) + \left(\frac{a}{R}\right)^6 \cos^6(\theta_1) - \dots \right] d\theta_1$$

Taking next the integral having the third power of the cosine and using the binomial expansion we obtain:

$$\begin{aligned}
\int_0^{2\pi} \frac{(a/R)^3 \cos^3(\theta_1) d\theta_1}{1 + (a/R) \cos(\theta_1)} &= \int_0^{2\pi} \left(\frac{a}{R}\right)^3 \cos^3(\theta_1) d\theta_1 - \int_0^{2\pi} \left[\left(\frac{a}{R}\right)^4 \cos^4(\theta_1) - \left(\frac{a}{R}\right)^5 \cos^5(\theta_1) + \right. \\
&\quad \left. \left(\frac{a}{R}\right)^6 \cos^6(\theta_1) - \dots \right] d\theta_1 = -\pi \left(\frac{a}{R}\right)^4 Z
\end{aligned} \quad (A5)$$

Using this process and the trigonometric identities, the remaining integrals can be evaluated as follows:

$$\int_0^{2\pi} \frac{(a/R)^2 \cos^2(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = \pi \left(\frac{a}{R}\right)^2 \left[1 + \left(\frac{a}{R}\right)^2 Z\right] = \pi \left(\frac{a}{R}\right)^2 Z_2 \quad (\text{A6})$$

$$\int_0^{2\pi} \frac{(a/R)\cos(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = -\pi \left(\frac{a}{R}\right)^2 Z_2 \quad (\text{A7})$$

$$\int_0^{2\pi} \frac{1}{1 + (a/R)\cos(\theta_1)} d\theta_1 = \pi \left[2 + \left(\frac{a}{R}\right)^2 \left[1 + \left(\frac{a}{R}\right)^2 Z\right]\right] \quad (\text{A8})$$

$$\int_0^{2\pi} \frac{(a/R)^2 \sin^2(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = \pi \left(\frac{a}{R}\right)^2 \left[1 + \left(\frac{a}{R}\right)^2 (1 - Z) + \left(\frac{a}{R}\right)^4 Z\right] = \pi \left(\frac{a}{R}\right)^2 Z_3 \quad (\text{A9})$$

$$\int_0^{2\pi} \frac{(a/R)\sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = 0 \quad (\text{A10})$$

$$\int_0^{2\pi} \frac{(a/R)\cos(\theta_1)\sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = 0 \quad (\text{A11})$$

$$\int_0^{2\pi} \frac{(a/R)\sin^2(\theta_1)\cos^2(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = \pi \left(\frac{a}{R}\right)^4 \left[1 + Z\left(\left(\frac{a}{R}\right)^2 - 1\right)\right] = \pi \left(\frac{a}{R}\right)^4 Z_4 \quad (\text{A12})$$

$$\int_0^{2\pi} \frac{(a/R)^3 \sin^2(\theta_1)\cos(\theta_1)}{1 + (a/R)\cos(\theta_1)} d\theta_1 = -\pi \left(\frac{a}{R}\right)^4 Z_4 \quad (\text{A13})$$

Thus all the integrals can be evaluated in terms of the parameter Z , and this parameter can be evaluated by the direct integration of (A8) as:

$$\int_0^{2\pi} \frac{1}{1 + (a/R)\cos(\theta_1)} d\theta_1 = 2\pi[1 - (a/R)^2]^{-1/2} \quad (A14)$$

Equating this result with that of (A8) gives

$$Z = \left(\frac{R}{a}\right)^4 [2[1 - (a/R)^2]^{-1/2} - 2 - (a/R)^2] \quad (A15)$$

Using these integral formulas in (A2) and rearranging, we obtain the one-dimensional energy principle

$$\begin{aligned} & \delta \int \pi/2 \left\{ \frac{C_{22}}{R^2} [2(U' - W)^2 + Z_2 \left(\frac{a}{R}\right)^2 (U' - W + R\phi'_Y)^2 + a^2 Z_3 (\phi'_Z + \phi_X)^2] + \right. \\ & \frac{C_{33}}{R^2} [2a^2 (\phi'_X - \phi_Z)^2 + Z_2 \left(\frac{a}{R}\right)^2 [a(\phi'_X - \phi_Z) - \frac{R}{a} (V' - R\phi_Z)]^2 + \\ & Z_3 (W' + U - R\phi_Y)^2] + \frac{N_{22}^0}{R^2} [(U + W') + \\ & Z \left(\frac{a}{R}\right)^2 (U + W' + R\phi_Y)^2 + (V')^2 + \\ & Z_4 \left(\frac{a}{R}\right)^2 (V' - R\phi_Z)^2] - 2[Uf_2 + Wf_1 + \\ & \left. Vf_3 + a\phi_X f_4 - a\phi_Y f_5 - a\phi_Z f_6] \right\} aRd\theta_2 = 0 \end{aligned} \quad (A16)$$

The generalized force components associated with the cross-section displacement and rotations are defined by

$$f_1 = \frac{1}{\pi} \int_0^{2\pi} (F_1 \sin(\theta_1) - F_3 \cos(\theta_1)) (1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A17)$$

$$f_2 = \frac{1}{\pi} \int_0^{2\pi} F_2 (1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A18)$$

$$f_3 = \frac{1}{\pi} \int_0^{2\pi} (F_1 \cos(\theta_1) + F_3 \sin(\theta_1))(1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A19)$$

$$f_4 = \frac{1}{\pi} \int_0^{2\pi} F_1 (1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A20)$$

$$f_5 = \frac{1}{\pi} \int_0^{2\pi} F_2 \cos(\theta_1)(1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A21)$$

$$f_6 = \frac{1}{\pi} \int_0^{2\pi} F_2 \sin(\theta_1)(1 + (a/R)\cos(\theta_1)) d\theta_1 \quad (A22)$$

This completes the detail development of the one-dimensional energy principle.

APPENDIX B

DERIVATION OF ONE-DIMENSIONAL STRESS RESULTANTS AND MOMENTS

APPENDIX B

DERIVATION OF ONE-DIMENSIONAL STRESS RESULTANTS AND MOMENTS

The one-dimensional stress resultants and moments are defined as integrals of N'_{22} and N'_{12} over the cross-section and are expressed in terms of the cross-section displacement and rotations by use of the stress/strain law and the strain displacement relations which are repeated here for convenience.

$$N'_{22} = C_{22} \epsilon'_{22} \quad (B1)$$

$$N'_{12} = 2C_{33} \epsilon'_{12} \quad (B2)$$

$$\epsilon'_{22} = \frac{1}{R(1 + (a/R)\cos(\theta_1))} [(U' - W) - \phi'_y \cos(\theta_1) - (\phi'_z + \phi_x) \sin(\theta_1)] \quad (B3)$$

$$\epsilon'_{12} = \frac{1}{2R(1 + (a/R)\cos(\theta_1))} [a(\phi'_x - \phi_z) + (W' + U + R\phi_y) \sin(\theta_1) + (V' - R\phi_z) \cos(\theta_1)] \quad (B4)$$

$$\epsilon''_{22} = \frac{1}{2R^2(1 + (a/R)\cos(\theta_1))^2} [(U + W') \cos(\theta_1) - V' \sin(\theta_1) - \phi_y \cos^2(\theta_1) - \phi_z \sin(\theta_1) \cos(\theta_1)] \quad (B5)$$

The axial stress resultant is defined as:

$$t = \int_0^{2\pi} N'_{22} a d\theta_1$$

$$t = \int_0^{2\pi} C_{22} \frac{a}{R} \left[\frac{(U' - W)}{1 + (a/R)\cos(\theta_1)} - \frac{\phi'_y \cos(\theta_1)}{1 + (a/R)\cos(\theta_1)} - \frac{(\phi'_z + \phi_x) \sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} \right] d\theta_1$$

Using (A5) through (A13) for the evaluation of the integrals we have

$$t = \pi C_{22} \frac{a}{R} \left[\left(2 + \left(\frac{a}{R} \right)^2 Z_2 \right) (U' - W) + \left(\frac{a}{R} \right)^2 Z_2 R \phi'_y \right] \quad (B6)$$

The moments about the x, y, and z axes, respectively, are defined as:

$$m_x = \int_0^{2\pi} N'_{12} a^2 d\theta_1$$

$$m_y = \int_0^{2\pi} N'_{22} a^2 \cos(\theta_1) d\theta_1$$

$$m_z = \int_0^{2\pi} N'_{22} a^2 \sin(\theta_1) d\theta_1$$

Substituting the stress/strain law and the strain displacement relations we have:

$$m_x = \int_0^{2\pi} C_{33} \frac{a^2}{R} \left[\frac{a(\phi'_x - \phi_z)}{1 + (a/R)\cos(\theta_1)} + \frac{(V' - R\phi_z)\cos(\theta_1)}{(1 + (a/R)\cos(\theta_1))} + \frac{(W' + U + R\phi_y)\sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} \right] d\theta_1$$

$$m_y = \int_0^{2\pi} C_{22} \frac{a^2}{R} \left[\frac{(U' - W)\cos(\theta_1)}{1 + (a/R)\cos(\theta_1)} - \frac{\phi'_y a \cos^2(\theta_1)}{1 + (a/R)\cos(\theta_1)} - \frac{(\phi'_z + \phi_x) a \cos(\theta_1) \sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} \right] d\theta_1$$

$$m_z = \int_0^{2\pi} C_{22} \frac{a^2}{R} \left[\frac{(U' - W)\sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} - \frac{\phi'_y a \cos(\theta_1) \sin(\theta_1)}{1 + (a/R)\cos(\theta_1)} - \frac{(\phi'_z + \phi_x) a \sin^2(\theta_1)}{1 + (a/R)\cos(\theta_1)} \right] d\theta_1$$

Carrying out the integral with respect to θ_1 using the formulas (A5) through (A13) we have

$$m_x = \pi C_{33} \frac{a^3}{R^2} [R(2 + (\frac{a}{R})^2 Z_2)(\phi'_x + \phi_z) - Z(V' - R\phi_z)] \quad (B7)$$

$$m_y = -\pi C_{22} Z_2 \frac{a^3}{R^2} [U' - W + R\phi'_y] \quad (B8)$$

$$m_z = -\pi C_{22} Z_3 \frac{a^3}{R^2} [R(\phi'_z + \phi_x)] \quad (B9)$$

The remaining two stress resultants are the transverse shear resultant defined by:

$$q_z = \int_0^{2\pi} [N'_{12} \sin(\theta_1) + N^o_{22} \sqrt{2\epsilon''_{22}} \cos(\theta_1)] a d\theta_1$$

$$q_y = \int_0^{2\pi} [N'_{12} \cos(\theta_1) - N^o_{22} \sqrt{2\epsilon''_{22}} \sin(\theta_1)] a d\theta_1$$

Substituting the stress/strain law and the strain displacement relations we have:

$$q_z = \int_0^{2\pi} \left\{ C_{33} \frac{a}{R} \left[\frac{(\phi'_x - \phi_z) a \sin(\theta_1)}{1 + (a/R) \cos(\theta_1)} + \frac{(V' - R\phi_z) \cos(\theta_1) \sin(\theta_1)}{1 + (a/R) \cos(\theta_1)} + \right. \right. \\ \left. \left. \frac{(W' + U + R\phi_y) \sin^2 \theta}{1 + (a/R) \cos(\theta_1)} \right] + N^o_{22} \frac{a}{R} \left[\frac{(U + W') \cos^2(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \frac{\phi_y a \cos^3(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \right. \right. \\ \left. \left. \frac{V' \sin(\theta_1) \cos(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \frac{\phi_z a \sin(\theta_1) \cos^2(\theta_1)}{1 + (a/R) \cos(\theta_1)} \right] \right\} d\theta_1$$

$$q_y = \int_0^{2\pi} \left\{ C_{33} \frac{a}{R} \left[\frac{(\phi'_x - \phi_z) a \cos(\theta_1)}{1 + (a/R) \cos(\theta_1)} + \frac{(W' + U + R\phi_y) \cos(\theta_1) \sin(\theta_1)}{1 + (a/R) \cos(\theta_1)} + \right. \right. \\ \left. \left. \frac{(V' - R\phi_z) \cos^2(\theta_1)}{1 + (a/R) \cos(\theta_1)} \right] - N_{22}^0 \frac{a}{R} \left[\frac{(U + W') \cos(\theta_1) \sin(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \frac{V' \sin^2(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \right. \right. \\ \left. \left. \frac{\phi_y a \cos^2(\theta_1) \sin(\theta_1)}{1 + (a/R) \cos(\theta_1)} - \frac{\phi_z a \sin^2(\theta_1) \cos(\theta_1)}{1 + (a/R) \cos(\theta_1)} \right] \right\} d\theta_1$$

Again we integrate with respect to θ_1 using (A5) through (A13) to give

$$q_z = \pi C_{33} Z_3 \frac{a}{R} (W' + U + R\phi_y) + \quad (B10)$$

$$\pi N_{22}^0 \frac{a}{R} [Z_2 (U + W') + \left(\frac{a}{R}\right)^2 ZR\phi_y]$$

$$q_y = \pi C_{33} Z_2 \frac{a}{R} [(V' - R\phi_z) - \left(\frac{a}{R}\right)^2 R(\phi'_x - \phi_z)] - \quad (B11)$$

$$\pi N_{22}^0 \frac{a}{R} (-Z_3 V' + \left(\frac{a}{R}\right)^2 RZ_4 \phi_z)$$

These stress resultants and moments are shown graphically in Figure 2. In addition to being the definitions of the stress resultants and moments, the above expressions are also the force displacement relations for the one-dimensional theory.

APPENDIX C
THEORY IN NONDIMENSIONAL FORM

APPENDIX C

THEORY IN NONDIMENSIONAL FORM

When obtaining solutions and results from theory it is useful to have the equations, including the basic definitions, in nondimensional form. To do this for the present theory, we begin by defining nondimensional displacements.

$$U = U/a \quad (C1)$$

$$W = W/a \quad (C2)$$

$$V = V/a \quad (C3)$$

The nondimensional strain measures are obtained from equations (18) as

$$E = (U' - W)/\rho \quad (C4)$$

$$K_y = R\kappa_y = \phi'_y \quad (C5)$$

$$K_z = R\kappa_z = \phi'_z + \phi_x \quad (C6)$$

$$K_x = R\kappa_x = \phi'_x - \phi_z \quad (C7)$$

$$\Gamma_z = (U + W' + \rho\phi_y)/\rho \quad (C8)$$

$$\Gamma_y = (V' - \rho\phi_z)/\rho \quad (C9)$$

where $\rho = R/a$. The nondimensional stress resultant and moments are defined as follows, and the nondimensional stress-displacement relations follow from equations (16):

$$T = t/\bar{C}_{22}a = (\pi d/\rho)[(2 + Z_2/\rho^2)(U' - W) + Z_2\phi'_y/\rho] \quad (C10)$$

$$Q_y = q_y/\bar{C}_{22}a = (\pi cZ_2/\rho)[(V' - \rho\phi_z) - (\phi'_x - \phi_z)/\rho] - (\pi n/\rho)[-Z_3V' + Z_4\phi_z/\rho] \quad (C11)$$

$$Q_z = q_z/\bar{C}_{22}a = (\pi cZ_3/\rho)[W' + U + \rho\phi_y] + (\pi n/\rho)[Z_2(U + W') + Z\phi_y/\rho] \quad (C12)$$

$$M_x = m_x/\bar{C}_{22}a^2 = (\pi c/\rho)[(2 + Z_2/\rho^2)(\phi'_x - \phi_z) - Z_2(V' - \rho\phi_z)/\rho] \quad (C13)$$

$$M_y = m_y/\bar{C}_{22}a^2 = -(\pi dZ_2/\rho^2)[U' - W + \rho\phi'_y] \quad (C14)$$

$$M_z = m_z/\bar{C}_{22}a^2 = -(\pi dZ_3/\rho^2)[\phi'_z + \phi'_x] \quad (C15)$$

The equilibrium equations in terms of the nondimensional stress resultants and moments are obtained by dividing equations (20) by $C_{22}a$ to yield

$$-T' + Q_z - \pi\bar{f}_2 = 0 \quad (C16)$$

$$-(T + Q'_z) - \pi\bar{f}_1 = 0 \quad (C17)$$

$$M'_y/\rho + Q_z - (\pi n/\rho)(U + W') + \pi\bar{f}_5/\rho = 0 \quad (C18)$$

$$-Q'_y - \pi\bar{f}_3 = 0 \quad (C19)$$

$$(M'_z - M'_x)/\rho - Q_y + (\pi n/\rho)V' + \pi\bar{f}_6/\rho = 0 \quad (C20)$$

$$-(M_z + M'_x)/\rho - \pi\bar{f}_4/\rho = 0 \quad (C21)$$

The nondimensional forces are given as $\bar{f}_i = Rf_i/C_{22}$ and $n = N_{22}^\circ/\bar{C}_{22}$ is the nondimensional stress due to the internal pressure. The parameters $d = C_{22}/\bar{C}_{22}$ and $c = C_{33}/\bar{C}_{22}$ are the nondimensional stiffnesses and \bar{C}_{22} is a reference value of C_{22} . The governing equations in terms of the nondimensional displacement parameters are obtained from equations (22) by dividing by $\bar{C}_{22}a$ to give

$$-[2d/\rho + dZ_2/\rho^3] U'' + [cZ_3/\rho + nZ_2/\rho]U - [dZ_2/\rho^2]\phi''_y + \quad (C22)$$

$$[cZ_3 + nZ/\rho^2]\phi_y + [2d/\rho + dZ_2/\rho^3 + cZ_3/\rho + nZ_2/\rho]W' - \bar{f}_2 = 0$$

$$-[cZ_3/\rho + nZ_2/\rho]W'' + [d(2 + Z_2/\rho^2)/\rho]W - [dZ_2/\rho^2 + cZ_3 + nZ/\rho^2]\phi'_y - \quad (C23)$$

$$[d(2 + Z_2/\rho^2)/\rho + cZ_3/\rho + nZ_2/\rho]U' - \bar{f}_1 = 0$$

$$-[dZ_2/\rho]\phi''_y + [cZ_3\rho + nZ/\rho]\phi_y - [dZ_2/\rho^2]U'' + [cZ_3 + nZ/\rho^2]U + \quad (C24)$$

$$[dZ_2/\rho^2 + cZ_3 + nZ/\rho^2]W' + \bar{f}_5 = 0$$

$$-[cZ_2/\rho + nZ_3/\rho]V'' + [cZ_2/\rho^2]\phi''_x + \quad (C25)$$

$$[cZ_2(1 - 1/\rho^2) + nZ_4/\rho^2]\phi'_z - \bar{f}_3 = 0$$

$$-[dZ_3/\rho^2]\phi''_z + [c(2/\rho^2 + Z_2(1 - 1/\rho^2)^2) + nZ_4/\rho^2]\phi_z - \quad (C26)$$

$$[dZ_3/\rho^2 + c[2 - Z_2(1 - 1/\rho^2)]/\rho^2]\phi'_x -$$

$$[cZ_2(1 - 1/\rho^2)/\rho - n(1 - Z_3)/\rho]V' + \bar{f}_6/\rho = 0$$

$$\begin{aligned}
& -[c(2 + Z_2/\rho^2)/\rho^2]\phi''_x + [dZ_3/\rho^2]\phi_x + [cZ_2/\rho^3]V'' + \\
& [dZ_3/\rho^2 + c(2 - Z_2(1 - 1/\rho^2))/\rho^2]\phi'_z - \tau_4/\rho = 0
\end{aligned}
\tag{C27}$$

The boundary conditions are similarly expressed in terms of the nondimensional displacement parameter or the nondimensional stress resultants and moments. The Green's function discontinuity conditions are put in nondimensional form by dividing the stress resultant equations by $a\bar{C}_{22}$ and the moment equations by $a^2\bar{C}_{22}$ to give

$$T_1 - T_2 = \pi\bar{g}_2 \tag{C28}$$

$$M_{y1} - M_{y2} = \pi\bar{g}_5 \tag{C29}$$

$$Q_{z1} - Q_{z2} = \pi\bar{g}_1 \tag{C30}$$

$$M_{z1} - M_{z2} = \pi\bar{g}_6 \tag{C31}$$

$$M_{x1} - M_{x2} = \pi\bar{g}_4 \tag{C32}$$

$$Q_{y1} - Q_{y2} = \pi\bar{g}_3 \tag{C33}$$

where the nondimensional forces are $\bar{g}_i = g_i/C_{22}$, $i = 1, 6$.

APPENDIX D
RELATIONSHIP AMONG THE CONSTANTS OF INTEGRATION

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RELATIONSHIP AMONG THE CONSTANTS OF INTEGRATION

The homogenous solution as expressed by equations (37) contains 18 unknown constants. But, because the characteristic numbers cause the determinate of equation (33) to vanish, there is for each of these characteristic numbers a relationship among these constants which is used here to express the A_i and B_i in terms of the C_i . To obtain these relationships the solution (37) is substituted into the governing differential equations (30) and causing the coefficients of the functions $\cosh(\lambda\theta_2)$, $\sinh(\lambda\theta_2)$, $\cos(\theta_2)$, $\sin(\theta_2)$, $\theta_2\cos(\theta_2)$ and $\theta_2\sin(\theta_2)$ to vanish independently yielding 18 homogenous equations in 18 unknowns. This set of equations, however, has a rank of only 12, thus 12 of the unknowns can be expressed in terms of the remaining 6. The 18 equations in matrix form take the form shown on the following page

where

$$\begin{aligned} J_1 &= H_2 - \lambda^2 H_1 \\ J_2 &= H_4 - \lambda^2 H_3 \\ J_3 &= H_1 + H_2 \\ J_4 &= H_3 + H_4 \\ J_5 &= H_1 - \lambda^2 H_2 \end{aligned} \tag{2D}$$

Examination of these equations reveals that the relation among the constants A_1 , B_1 and C_1 is the same as that among A_2 , B_2 , and C_2 ; thus we obtain from two of the three equations

$$\begin{Bmatrix} A_1 \\ B_1 \end{Bmatrix} = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \{C_2\}$$

and

$$\begin{Bmatrix} A_2 \\ B_2 \end{Bmatrix} = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \{C_1\}$$

$$\begin{bmatrix}
 J_1 & J_2 & \lambda_3 \\
 J_2 & \rho J_2 & \lambda_4 \\
 -\lambda_3 & -\lambda_4 & J_5 \\
 \\
 J_1 & J_2 & \lambda_3 \\
 J_2 & \rho J_2 & \lambda_4 \\
 -\lambda_3 & -\lambda_4 & J_5 \\
 \\
 J_3 & J_4 & 2H_1 & 2H_3 & -J_3 & J_3 \\
 J_4 & \rho J_4 & 2H_3 & 2\rho H_3 & -J_4 & J_4 \\
 -J_3 & -J_4 & -J_3 & -J_4 & J_3 & -2H_2 \\
 & & J_3 & J_4 & & J_3 \\
 & & J_4 & \rho J_4 & & J_4 \\
 & & J_3 & J_4 & & J_3 \\
 \\
 J_3 & J_4 & 2H_1 & 2H_3 & -J_3 & J_3 \\
 J_4 & \rho J_4 & 2H_3 & 2\rho H_3 & -J_4 & J_4 \\
 -J_3 & -J_4 & -J_3 & -J_4 & J_3 & -2H_2 \\
 & & J_3 & J_4 & & J_3 \\
 & & J_4 & \rho J_4 & & J_4 \\
 & & J_3 & J_4 & & J_3
 \end{bmatrix}
 \begin{Bmatrix}
 A_1 \\
 B_1 \\
 C_2 \\
 A_2 \\
 B_2 \\
 C_1 \\
 A_3 \\
 B_3 \\
 A_6 \\
 B_6 \\
 C_4 \\
 C_5 \\
 A_4 \\
 B_4 \\
 A_5 \\
 B_5 \\
 C_3 \\
 C_6
 \end{Bmatrix} = 0 \quad (1D)$$

where

$$\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = - \begin{bmatrix} J_1 & J_2 \\ J_2 & \rho J_2 \end{bmatrix}^{-1} \begin{bmatrix} \lambda J_3 \\ \lambda J_4 \end{bmatrix}$$

Similarly, the relation among A_3 , B_3 , A_6 , B_6 , C_4 , and C_5 is the same as that among A_4 , B_4 , $-A_5$, $-B_5$, $-C_3$, and C_6 ; thus we obtain from equations (7), (8), (10), and (11)

$$\begin{Bmatrix} A_3 \\ B_3 \\ A_6 \\ B_6 \end{Bmatrix} = \begin{bmatrix} \beta_3 & \beta_5 \\ \beta_4 & \beta_6 \\ 0 & -\beta_3 \\ 0 & -\beta_4 \end{bmatrix} \begin{Bmatrix} C_4 \\ C_5 \end{Bmatrix}$$

and

$$\begin{Bmatrix} A_4 \\ B_4 \\ -A_5 \\ -B_5 \end{Bmatrix} = \begin{bmatrix} \beta_3 & \beta_5 \\ \beta_4 & \beta_6 \\ 0 & -\beta_3 \\ 0 & -\beta_4 \end{bmatrix} \begin{Bmatrix} -C_3 \\ C_6 \end{Bmatrix}$$

where

$$\begin{bmatrix} \beta_3 & \beta_5 \\ \beta_4 & \beta_6 \\ 0 & -\beta_3 \\ 0 & -\beta_4 \end{bmatrix} = \begin{bmatrix} J_3 & J_4 & 2H_1 & 2H_3 \\ J_4 & \rho J_4 & 2H_3 & 2\rho H_3 \\ 0 & 0 & J_3 & J_4 \\ 0 & 0 & J_4 & \rho J_4 \end{bmatrix}^{-1} \begin{bmatrix} -J_3 & J_3 \\ -J_4 & J_4 \\ 0 & J_3 \\ 0 & J_4 \end{bmatrix}$$

APPENDIX E
SYSTEMS OF EQUATIONS FOR DETERMINATION OF THE
CONSTANTS OF INTEGRATION

APPENDIX E

SYSTEMS OF EQUATIONS FOR DETERMINATION OF THE CONSTANTS OF INTEGRATION

Our purpose here is to give the expressions for the coefficients of the systems of equations which determine the constants of integration for the solution of the arch equations. The coefficients for the Green's function will be given first, followed by those for the uniform load solution.

The Green's Function contains 12 constants of integration; therefore, 12 equations are required for their determination. Six of these constants, C_1 through C_6 , define the solution over $-\alpha < \theta_2 \leq \bar{\theta}_2$ and the remaining six define the solution over $\bar{\theta}_2 \leq \theta_2 \leq \alpha$. These equations can be written in matrix form as

$$[S] \quad C \quad = \quad b$$

where C is the vector of 12 constants of integration and the matrix of coefficients S are presented below. The first three equations impose the boundary conditions at $\theta_2 = -\alpha$, and equations (4) through (6) impose the boundary conditions at $\theta_2 = \alpha$. Coefficients will be given for both the simply supported and the fixed boundary conditions. Equations (7) through (9) state the continuity of displacements and rotation at $\theta_2 = \bar{\theta}_2$, the location of the concentrated load and equations (10) through (12) are the discontinuity condition on the axial force, the moment and the transverse shear force. The coefficients, s_{ij} ($i = 1,3; j = 1,6$) are evaluated with ease by evaluation of U_1, W_1 , and ϕ_{Y1} at $\theta_2 = -\alpha$ for the fixed boundary condition and U_1, W_1 , and $(U'_1 - W_1 + \rho\phi'_{Y1})$ at $\theta_2 = -\alpha$ for the simply supported boundary conditions. For s_{ij} ($i = 4,6; j = 7,12$) the parameters U_2, W_2 , and ϕ_{Y2} replace U_1, W_1 , and ϕ_{Y1} and are evaluated at $\theta_2 = \alpha$. In addition, we have $s_{ij} = 0$ for $i = 1,3; j = 7,12$ and $i = 4,6; j = 1,6$. Since equations (7) through (9) impose continuity of displacement at $\theta_2 = \bar{\theta}_2$ the coefficients, s_{ij} ($i = 7,9; j = 1,6$) are found by evaluating U_1, W_1 , and ϕ_{Y1} at $\theta_2 = \bar{\theta}_2$ and the coefficients, s_{ij} ($i = 7,9; j = 7,12$) are found by evaluating U_2, W_2 , and ϕ_{Y2} at $\theta_2 = \bar{\theta}_2$. The coefficients of the last three equations are given in detail below.

$$s_{10,1} = L_1 \cosh(\lambda \bar{\theta}_2)$$

$$s_{10,2} = L_1 \sinh(\lambda \bar{\theta}_2)$$

$$s_{10,3} = L_2 \sin(\bar{\theta}_2)$$

$$s_{10,4} = L_2 \cos(\bar{\theta}_2)$$

$$s_{10,5} = L_3 \cos(\bar{\theta}_2) + L_2 \bar{\theta}_2 \sin(\bar{\theta}_2)$$

$$s_{10,6} = -L_3 \sin(\bar{\theta}_2) + L_2 \bar{\theta}_2 \cos(\bar{\theta}_2)$$

$$L_1 = (\beta_1 \lambda - 1) H_1 + H_3 \beta_2 \lambda$$

$$L_2 = (\beta_3 - 1) H_1 + H_3 \beta_4$$

$$L_3 = (\beta_5 - \beta_3) H_1 + (\beta_6 - \beta_4) H_3$$

$$s_{11,1} = L_4 \cosh(\lambda \bar{\theta}_2)$$

$$s_{11,2} = L_4 \sinh(\lambda \bar{\theta}_2)$$

$$s_{11,3} = L_5 \sin(\bar{\theta}_2)$$

$$s_{11,4} = L_5 \cos(\bar{\theta}_2)$$

$$s_{11,5} = L_6 \cos(\bar{\theta}_2) + L_5 \bar{\theta}_2 \sin(\bar{\theta}_2)$$

$$s_{11,6} = -L_6 \sin(\bar{\theta}_2) + L_5 \theta_2 \cos(\bar{\theta}_2)$$

$$L_4 = [(\beta_1 \lambda - 1) + \rho \beta_2 \lambda] H_3$$

$$L_5 = [(\beta_3 - 1) + \rho \beta_4] H_3$$

$$L_6 = [(\beta_5 - \beta_3) + \rho(\beta_6 - \beta_4)] H_3$$

$$s_{12,1} = L_7 \sinh(\lambda \bar{\theta}_2)$$

$$s_{12,2} = L_7 \cosh(\lambda \bar{\theta}_2)$$

$$s_{12,3} = L_8 \cos(\bar{\theta}_2)$$

$$s_{12,4} = -L_8 \sin(\bar{\theta}_2)$$

$$s_{12,5} = L_9 \sin(\bar{\theta}_2) + L_8 \bar{\theta}_2 \cos(\bar{\theta}_2)$$

$$s_{12,6} = L_9 \cos(\bar{\theta}_2) - L_8 \bar{\theta}_2 \sin(\bar{\theta}_2)$$

$$L_7 = (\lambda + \beta_1) H_2 + H_4 \beta_2$$

$$L_8 = (1 - \beta_3) H_2 - H_4 \beta_4$$

$$L_9 = (1 + \beta_5) H_2 + H_4 \beta_6$$

The last six columns of these three equations are given by the relation

$$s_{i, j+6} = -s_{i,j}$$

$$i = 10, 12$$

$$j = 1, 6$$

The system of equations is completed by specification of the elements of the force matrix, b , as follows

$$b_i = 0 \quad i = 1, 9$$

$$b_{1,0} = \bar{g}_2$$

$$b_{1,1} = -\bar{g}_5$$

$$b_{1,2} = -\bar{g}_1$$

where $\bar{g}_1, \bar{g}_2, \bar{g}_5$ are the nondimensional applied forces.

For the uniform load, the symmetry of the structure and the load about $\theta_2 = 0$ makes it possible to reduce the number of constants of integration to three, which are determined from the boundary conditions. The equation for these three constants can be written in matrix form as:

$$\begin{bmatrix} s_{1,1} & s_{1,2} & s_{1,3} \\ s_{2,1} & s_{2,2} & s_{2,3} \\ s_{3,1} & s_{3,2} & s_{3,3} \end{bmatrix} \begin{Bmatrix} C_1 \\ C_4 \\ C_5 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ \rho f_1 / d(2 + Z_2 / \rho^2) \end{Bmatrix}$$

For fixed boundary conditions the coefficients are

$$s_{1,1} = \beta_1 \sinh(\lambda\alpha)$$

$$s_{1,2} = \beta_3 \sin(\alpha)$$

$$s_{1,3} = \beta_5 \sin(\alpha) - \beta_3 \alpha \cos(\alpha)$$

$$s_{2,1} = \beta_2 \sinh(\lambda\alpha)$$

$$s_{2,2} = \beta_4 \sin(\alpha)$$

$$s_{2,3} = \beta_6 \sin(\alpha) - \beta_4 \alpha \cos(\alpha)$$

$$s_{31} = \cosh(\lambda\alpha)$$

$$s_{32} = \cos(\alpha)$$

$$s_{33} = \alpha \sin(\alpha)$$

and for simply supported boundary conditions, the second equation is changed as follows to set the moment equal to zero.

$$s_{21} = [(\beta_1 \lambda - 1)H_1 + H_3 \beta_2 \lambda] \cosh(\lambda\alpha)$$

$$s_{22} = [(\beta_3 - 1)H_1 + H_3 \beta_4] \cos(\alpha)$$

$$s_{23} = [(\beta_5 - \beta_3)H_1 + (\beta_6 - \beta_4)H_3] \cos(\alpha) + \\ [(\beta_3 - 1)H_1 + H_3 \beta_4] \alpha \sin(\alpha)$$

APPENDIX F
COMPUTER PROGRAM FOR SOLUTION OF GOVERNING EQUATIONS

APPENDIX F

COMPUTER PROGRAM FOR SOLUTION OF GOVERNING EQUATIONS

Our purpose here is to describe the computer program which carries out the computations involved to obtain specific results from the solution described in the body of the report and Appendix E.

General Organization of Program

The flow of calculations in the program, a copy of which is given at the end of the appendix, is illustrated by the flow chart in Figure F-1. This flow chart is not intended to depict the details of the calculation but only the general organization or sequence of the calculations. The program includes a main program which calls 2 subroutines peculiar to this program, all of which carry out computations in double precision. The program also calls a system subroutine for the solution of system of linear equation. Because the program is in double precision this system subroutine must also be double precision. The program was written for the UNIVAC 1106 computer with the EXEC-8 operating system and the system subroutine called is associated with this computer system. It is believed that the program written in FORTRAN could be easily adapted to other systems.

The program contains options for the type of loading, the boundary conditions and plotting the output. The loading option includes a uniform normal loaded, a concentrated load either normal to the arch or vertical and at an arbitrary position, and a general distributed load. The concentrated load solution is a Green's function which is used to compute the solution for the general distributed load by quadrature. The functional form of the distributed load must be specified in SUBROUTINE CALPAR. The quadrature for the general load is carried out using the Gaussian numerical technique. The coordinates and weighting factors for this technique must be on logical unit 10 and written according to FORMAT (2E18.8). Two boundary condition options are provided. One has both ends fixed and the other both ends simply supported. Other options could be included by modification of the program. The plotting option when exercised provides for the plotting of the computed flexibility and wrinkling load as a function of the pressure parameter. In addition, experimental results will be plotted along with the corresponding calculated results. This experimental data must be located on logical unit 16 and written according to FORMAT (5E15.6). The CALCOMP plotter is used, and it operates a plot tape which must be assigned as logical unit 20. The program also uses a scratch file which must be assigned as logical unit 15.

Input and Execution

The input, both control parameters and data, required to operate the program is described in this section.

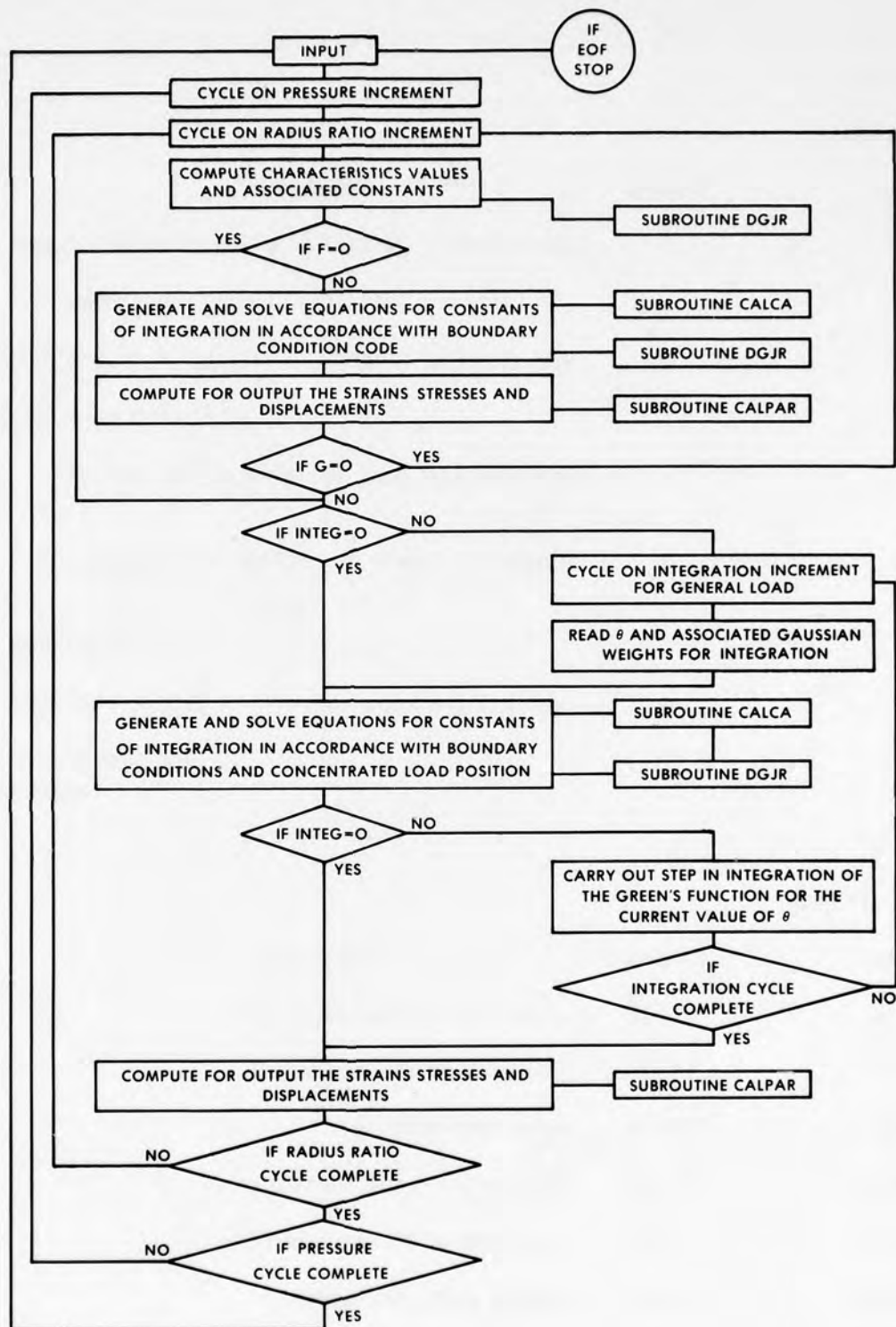


FIGURE F-1 FLOW CHART OF ARCH ANALYSIS PROGRAM

CARD #1

Format (I4)

Parameter	Column	Description
IPLOT	1	plot control IPLOT = 1 output is not plotted IPLOT = 0 output is plotted
ILOAD	2	load direction control ILOAD = 1 vertical load ILOAD = 0 normal load this parameter does not apply to the uniform load
INTEG	3	Integration control INTEG = 1 general load INTEG = 0 uniform and concentrated load
IBOUN	4	boundary condition control IBOUN = 0 fixed IBOUN = 1 simply supported

CARD #2

Format (7F10.0)

Parameter	Column	Description
RLIM(1)	1-10	initial value of the radius ratio
RLIM(2)	11-20	final value of the radius ratio
RLIM(3)	21-30	radius ratio increment
XNLIM(1)	31-40	initial value of the pressure parameter
XNLIM(2)	41-50	final value of the pressure parameter
XNLIM(3)	51-60	pressure parameter increment

CARD #3

Format (3F10.0)

Parameter	Column	Description
ALPHA	1-10	half span angle of the arch
THETA	11-20	location of concentrated load on the arch
THEHAT	21-30	location of load on the cross-section, see equation (43)

CARD #4

Format (2F10.0, I5)

Parameter	Column	Description
F	1-10	intensity of uniform load; $F = 0$ causes the uniform load calculation to be omitted
SMG	11-20	concentrated load magnitude; $SMG = 0$ causes the concentrated load computation to be omitted. For the general distributed load SMG must be put equal to unity
NMAX	21-25	number of output intervals; if $NMAX = 18$ and the arch spans 180° , program will print output every 10° .

CARD #5

Format (7F10.7)

Parameter	Column	Description
AC	1-10	the program allows the nondimensional shear modulus, c , and the nondimensional elastic modulus, d , to be linear functions of the pressure parameter, XN . These four parameters define these linear functions as
BC	11-20	
AE	21-30	
BE	31-40	

$$c = AC \cdot XN + BC$$

$$d = AE \cdot XN + BE$$

CARD #6

Format (IX, 13A6)

Parameter	Column	Description
QIDEN	2-79	an identification of the job to be printed out with the output

An example of the coded input is given in Table F-1. This input was used to generate the sample output to be discussed subsequently. The execution of the program on the UNIVAC 1106 computer with the EXEC-8 operating system can be accomplished with the runstream shown on page 107. This includes reduction of experimental data for plotting, computation of Gaussian integration constants, assignment of the required files, compilation and assembly of the arch analysis program, execution of the program and input data. The computer output resulting from the execution of this runstream is present on pages 108 to 144. The runstream begins with the assignment of tape no. 1962 which contains the raw experimental data presented in this report and a program entitled NONDIM which reads the raw data from file 15, reduces this data to nondimensional form, and writes the nondimensional data on file 16. If it is desired to plot different flexibility and wrinkling load data against pressure, the raw data must be entered into file 15 before execution of the data reduction program. If no plotting is desired, statements 1-16 of the runstream may be omitted. Upon execution of the data reduction program, the reference value of the elastic modulus is called for as input. This input is the number 313.0 appearing as statement 12 in the runstream. This is the English unit system equivalent of the number given in the body of the report and is given in these units because the raw data is in English units. This number must also be changes for a different set of data. If plots are to be made, this experimental data must be present. Following the data reduction we have the generation of the Gaussian integration constants. This is accomplished with a short FORTRAN program which calls the subroutine LGAUSS to generate the constants, and upon return, writes them on file 10. As presented, 90 integration increments are used. A change in the number of increments is accomplished by changing the parameter N on line 20 of the runstream. The subroutine LGAUSS computes the integration coordinates over the range -1 to 1. These coordinates are transformed to the range $-\alpha$ to α at the time they are used in the arch analysis. If either a concentrated load or a uniform load is being treated which does not require integration, then statements 17 through 32 may be omitted from the runstream. After generation of the integration constants tape no. 1964 is called and the arch analysis programs are read into a mass storage file. These programs are compiled and collected using the MAP processor. The absolute executable program is put in B. If a general distributed load is being treated, its functional form must be specified in subroutine CALPAR which is the symbolic element TPF\$.ARCHRESULTS. This must be done before compilation of this subroutine. If plots are to be made, a plot tape assigned as file 20 must be assigned before execution of the program.

Table F1. Input data in coded format.

[illegible]

Output

A sample of the output generated by the program is given in pages 141 to 144. This output corresponds to the input given in Table F1. As is seen, the heading contains a title followed by specification of the type of loading and the boundary conditions. The user-provided-problem description, the linear expressions for the shear and elastic moduli and the problem parameters then appear. The main body of the output consists of the normal and longitudinal deflection, the rotation, the strains at the outer and inner arch radii, the axial force, and the moment for a series of equal spaced angular positions. As can be seen, these positions begin with the smallest and increase to the largest position. All of the output are in nondimensional form.

```

ECS*JUNK(1).RSAREP
1  @ASG,T  TP.,6C9,1962 . TAPE WITH DATA & REDUCTION PROGRAM
2  @MOVE   TP,2
3  @COPIN  TP.,
4  @FREE   TP.
5  @ASG,T  15.,F14 . SCRATCH FILE
6  @ASG,T  16.,F14 . FILE WITH EXPERIMENTAL DATA FOR PLOTTING
7  @DATA,IL 15.
8  @ADD,D  TPF$.RAWADA
9  @END
10 @FOR,S  TPF$.NONDIM,N
11 @XQT
12 313.0
13 @DATA,L 16.
14 @END
15 @ERS
16 @ERS 15.
17 @ASG,T  10.,F14 . FILE WITH GAUSSIAN INTEGRATION CONSTANTS
18 @FOR,IS
19     DIMENSION X(100),W(100)
20     N=90
21     CALL LGAUSS(X,W,N,$1)
22     1 CONTINUE
23     WRITE(10,2) N
24     2 FORMAT(I4)
25     WRITE(10,3) (X(I),W(I),I=1,N)
26     3 FORMAT(2E18.8)
27     STOP
28     END
29 @XQT
30 @DATA,L 10.
31 @END
32 @ERS
33 @ASG,T  TP.,6C9,1964 . TAPE WITH ARCH ANALYSIS PROGRAMS
34 @MOVE   TP,7
35 @COPIN  TP.,
36 @FREE   TP.
37 @FOR,S  TPF$.MAINARCH,M
38 @FOR,S  TPF$.ARCHRESULTS,R
39 @FOR,S  TPF$.BOUNDARYARCH,B
40 @MAP,IN  A,B
41     IN TPF$.M
42     LIB CALCOMP*BASIC.
43     END
44 @ASG,T  20.,6C9,0928W . PLOT TAPE WITH APPROPRIATE NO.
45 @XQT  B
46 1001
47 20.0      30.0      10.0      0.05667  0.06667  0.01
48 90.0      0.0       0.0
49 0.0       -0.0000663  10
50 0.0       0.05      0.0      1.0
51     FINITE ELEMENT CHECK CASE

```

@ADD,P

J.RSAREP

@ASG,T TP.,6C9,1962 . TAPE WITH DATA & REDUCTION PROGRAM

@MOVE TP,2
FURPUR 27R2 RL72R1 11/03/77 15:26:14

@COPIN TP.,
27 SYM 2 REL

@FREE TP.

@ASG,T 15.,F14 . SCRATCH FILE

@ASG,T 16.,F14 . FILE WITH EXPERIMENTAL DATA FOR PLOTTING

@DATA,IL 15.
DATA T7 RL70-5 11/03-15:29:22

1.	4			
2.	38.0	2.0	18	
3.	5.0	0.0472	0.0676	14.0
4.	5.0	0.0476	0.068	14.0
5.	5.0	0.0459	0.0671	14.0
6.	10.0	0.0362	0.0402	26.0
7.	10.0	0.0352	0.0386	26.0
8.	10.0	0.036	0.0385	27.0
9.	15.0	0.0282	0.0317	39.0
10.	15.0	0.0279	0.0306	39.0
11.	15.0	0.0275	0.0303	39.0
12.	20.0	0.0241	0.026	49.0
13.	20.0	0.0238	0.0256	48.0
14.	20.0	0.0233	0.0253	48.0
15.	25.0	0.0213	0.0217	57.0
16.	25.0	0.0208	0.0214	58.0
17.	25.0	0.0206	0.0212	57.0
18.	30.0	0.0194	0.0182	73.0
19.	30.0	0.0189	0.0179	73.0
20.	30.0	0.0187	0.0175	73.0
21.	37.5	1.5	18	
22.	5.0	0.0714	0.143	
23.	5.0	0.0684	0.143	
24.	5.0	0.0684	0.143	
25.	10.0	0.0574	0.08	
26.	10.0	0.0538	0.0813	
27.	10.0	0.0515	0.0813	
28.	15.0	0.0424	0.0654	
29.	15.0	0.04	0.0621	
30.	15.0	0.0393	0.0629	
31.	20.0	0.0338	0.0508	
32.	20.0	0.0327	0.0488	
33.	20.0	0.0327	0.0485	
34.	25.0	0.0286	0.0435	
35.	25.0	0.0273	0.0413	
36.	25.0	0.0279	0.0417	
37.	30.0	0.0273	0.0368	
38.	30.0	0.0260	0.0357	
39.	30.0	0.0260	0.0355	
40.	39.0	3.0	18	
41.	5.0	0.0192	0.02	52.0
42.	5.0	0.0192	0.0192	52.0
43.	5.0	0.0192	0.0196	
44.	10.0	0.0151	0.0139	80.0
45.	10.0	0.0147	0.0137	80.0
46.	10.0	0.0142	0.0137	
47.	15.0	0.0116	0.0109	107.0
48.	15.0	0.0121	0.0106	105.0
49.	15.0	0.0121	0.0106	
50.	20.0	0.0104	0.0093	135.0
51.	20.0	0.0102	0.0089	135.0
52.	20.0	0.0100	0.0091	
53.	25.0	0.0092	0.0077	170.0
54.	25.0	0.0089	0.0075	170.0
55.	25.0	0.0086	0.0075	

56.	30.0	0.0080	0.0068	210.0
57.	30.0	0.0078	0.0067	205.0
58.	30.0	0.0076	0.0067	205.0
59.	39.5	3.5	18	
60.	5.0	0.0119	0.0168	82.0
61.	5.0	0.0119	0.0168	82.0
62.	5.0	0.0116	0.0168	82.0
63.	10.0	0.0093	0.0118	132.0
64.	10.0	0.0089	0.0119	132.0
65.	10.0	0.0086	0.0118	132.0
66.	15.0	0.0075	0.0093	170.0
67.	15.0	0.0074	0.0089	170.0
68.	15.0	0.0072	0.0088	170.0
69.	20.0	0.0065	0.0079	230.0
70.	20.0	0.0064	0.0076	230.0
71.	20.0	0.0063	0.0075	230.0
72.	25.0	0.0057	0.0068	265.0
73.	25.0	0.0056	0.0065	265.0
74.	25.0	0.0056	0.0065	265.0
75.	30.0	0.005	0.006	
76.	30.0	0.0050	0.0060	
77.	30.0	0.0050	0.0061	

END DATA.

@FOR,S TPF\$.NONDIM,N
FOR 00E3-11/03/77-15:31:29 (1,)

MAIN PROGRAM

STORAGE USED: CODE(1) 000156; DATA(0) 000135; BLANK COMMON(2) 000000

EXTERNAL REFERENCES (BLOCK, NAME)

0003 NINTR\$
0004 NRDU\$
0005 NIO2\$
0006 NWDU\$
0007 NWEF\$
0010 NSTOPS

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

0000	000023	1F	0000	000025	100F	0000	000102	101F	0000	000111	102F	0000	000100	103F					
0001	000025	113G	0001	000054	132G	0000	000076	2F	0001	000145	201L	0000	000021	3F					
0000	000022	4F	0001	000140	999L	0000	R	000000	C22B	0000	R	000012	FLEXI	0000	R	000011	FLEXO		
0000	I	000007	ID	0000	I	000002	IS	0000	I	000005	JDATA	0000	I	000001	JSETS	0000	R	000010	P
0000	R	000014	PI	0000	R	000016	QFLEXI	0000	R	000017	QFLEXO	0000	R	000015	QNX	0000	R	000020	QWLOAD
0000	R	000003	R	0000	R	000006	RHO	0000	R	000004	SR	0000	R	000013	WLOAD				

111

00101	1*	READ(5,3) C22B	000000
00105	2*	3 FORMAT(F8.2)	000007
00106	3*	READ(15,4) JSETS	000007
00111	4*	4 FORMAT(I4)	000020
00112	5*	DO 201 IS=1,JSETS	000020
00115	6*	READ(15,1) R,SR,JDATA	000025
00122	7*	1 FORMAT (2F8.2,I4)	000037
00123	8*	RHO=R/SR	000037
00124	9*	WRITE(6,100) RHO,C22B	000042
00130	10*	100 FORMAT(1H1, // 10X, 'NONDIMENSIONAL DATA FOR PRESSURE STABILIZED ARCH	000054
00130	11*	1' ///.5X'RADIUS RATIO='F10.4,/2X,'REFERENCE RATIO='F10.4, //	000054
00130	12*	215X,'NONDIMENSIONAL'/2X,'PRESSURE',6X'FLEXIBILITY',6X,'FLEXIBILITY	000054
00130	13*	3',4X,'WRINKLING LOAD'/21X,'OUT',18X,'IN'//)	000054
00131	14*	DO 200 ID=1,JDATA	000054
00134	15*	READ(15,2,END=999) P,FLEXO,FLEXI,WLOAD	000054
00142	16*	PI=3.1415	000066
00143	17*	2 FORMAT(4F8.2)	000070
00144	18*	QNX=P*SR/(2.0*C22B)	000070
00145	19*	QFLEXI= FLEXI*PI*C22B	000074
00146	20*	QFLEXO=FLEXO*PI*C22B	000077
00147	21*	QWLOAD=WLOAD/(PI*SR*C22B)	000103
00150	22*	WRITE(6,101) QNX,QFLEXO,QFLEXI,QWLOAD	000111
00156	23*	WRITE(16,103) RHO,QNX,QFLEXO,QFLEXI,QWLOAD	000122
00165	24*	103 FORMAT(5E15.6)	000136
00166	25*	101 FORMAT(1X,E13.6,3X,E13.6,3X,E13.6,3X,E13.6)	000136
00167	26*	200 CONTINUE	000136
00171	27*	GO TO 201	000136

00172	28*	999 WRITE(6,102)	000140
00174	29*	102 FORMAT(1X,'END OF FILE ENCOUNTERED BEFORE ALL EXPECTED DATA WAS RE	000146
00174	30*	1AD')	000146
00175	31*	201 CONTINUE	000146
00177	32*	END FILE 16	000146
00200	33*	STOP	000151
00201	34*	END	000155

END OF COMPILATION: NO DIAGNOSTICS.

@XQT
MAP2BR1 RL71-3 11/03/77 15:32:57

ADDRESS LIMITS	001000 013735	5598 IBANK WORDS DECIMAL
	040000 044202	2179 DBANK WORDS DECIMAL
STARTING ADDRESS	012142	

	SEGMENT \$MAINS	001000 013735	040000 044202
NRWNS\$/FOR-E3	\$(1)	001000 001063	\$(2) 040000 040011
NFTCH\$/FOR-E2	\$(1)	001064 001346	\$(2) 040012 040025
NBF00\$			\$(2) 040026 042253
NCNVT\$/FOR68	\$(1)	001347 001570	\$(2) 042254 042350
NFTV\$/FOR-E2	\$(1)	001571 001613	
NBDCV\$/FOR-E0	\$(1)	001614 001744	\$(2) 042351 042426
NCLOSS\$/FOR-E3	\$(1)	001745 002202	\$(2) 042427 042454
NSWTC\$/FOR69	\$(1)	002203 002227	
NWBLK\$/FOR68	\$(1)	002230 002341	
NBSBL\$/FOR68	\$(1)	002342 002402	
NUPDA\$/FOR68	\$(1)	002403 002436	
NRBLK\$/FOR-E2	\$(1)	002437 002461	
NOTIN\$/FOR-E3	\$(1)	002462 002756	\$(2) 042455 042460
NININ\$/FOR-E3	\$(1)	002757 003205	\$(2) 042461 042466
NINPT\$/FOR-E3	\$(1)	003206 004575	\$(2) 042467 042522
NFCHK\$/FOR-E3	\$(1)	004576 005567	\$(2) 042523 042673
	\$(3)	005570 005570	\$(4) 042674 042745
FORCOM\$/FORFTN			\$(2) 042746 042753
FORVCOM\$/FOR-TE3			\$(2) 042754 042763
ERUS\$/SYS72-8			
NERCOM\$/FOR-TE3	\$(1)	005571 005650	\$(2) 042764 042777
NIDERS\$/FOR-E3	\$(1)	005651 006070	\$(2) 043000 043147
NFMT\$/FOR-E3	\$(1)	006071 006753	\$(2) 043150 043224
NOUT\$/FOR-E3	\$(1)	006754 010470	\$(2) 043225 043266
NTAB\$/FOR-TE3			\$(2) 043267 043325
NSTO\$/FOR-TE3	\$(1)	010471 010533	\$(2) 043326 043335
NWEF\$/FOR-E2	\$(1)	010534 010741	\$(2) 043336 043355
NOBUF\$/FOR68	\$(1)	010742 011002	
NIBUF\$/FOR-E2	\$(1)	011003 011042	\$(2) 043356 043356
NINTR\$/FOR-E3	\$(1)	011043 011115	\$(2) 043357 043374
SQRT\$/FOR59	\$(1)	011116 011156	\$(2) 043375 043406
NERR\$/FOR-E3	\$(1)	011157 011520	\$(2) 043407 043566

NIERS/FOR-E3	\$(1)	011521 011676	\$(2)	043567 043706
NOSYMS/FOR-E3	\$(1)	011677 012141	\$(2)	043707 043710
BLANK\$COMMON(COMMONBLOCK)				
N	\$(1)	012142 012317	\$(0)	043711 044045
			\$(2)	BLANK\$COMMON
FPMIN	\$(1)	012320 013545	\$(0)	044046 044127
			\$(2)	BLANK\$COMMON
WRITEMATRIX	\$(1)	013546 013735	\$(0)	044130 044202
			\$(2)	BLANK\$COMMON

SYSS*RLIB\$. LEVEL 72-8
END MAP

NONDIMENSIONAL DATA FOR PRESSURE STABILIZED ARCH

RADIUS RATIO= 19.0000
 REFERENCE RATIO= 313.0000

PRESSURE	NONDIMENSIONAL FLEXIBILITY OUT	FLEXIBILITY IN	WRINKLING LOAD
.159744-01	.464113+02	.664704+02	.711896-02
.159744-01	.468046+02	.668637+02	.711896-02
.159744-01	.451330+02	.659787+02	.711896-02
.319489-01	.355951+02	.395282+02	.132209-01
.319489-01	.346118+02	.379550+02	.132209-01
.319489-01	.353984+02	.378566+02	.137294-01
.479233-01	.277288+02	.311703+02	.198314-01
.479233-01	.274338+02	.300887+02	.198314-01
.479233-01	.270405+02	.297937+02	.198314-01
.638978-01	.236973+02	.255655+02	.249164-01
.638978-01	.234023+02	.251722+02	.244079-01
.638978-01	.229106+02	.248772+02	.244079-01
.798722-01	.209441+02	.213374+02	.289843-01
.798722-01	.204524+02	.210424+02	.294928-01
.798722-01	.202538+02	.208457+02	.289843-01
.958466-01	.190758+02	.178959+02	.371203-01
.958466-01	.185842+02	.176009+02	.371203-01
.958466-01	.183875+02	.172076+02	.371203-01

NONDIMENSIONAL DATA FOR PRESSURE STABILIZED ARCH

RADIUS RATIO= 25.0000
REFERENCE RATIO= 313.0000

PRESSURE	NONDIMENSIONAL FLEXIBILITY OUT	FLEXIBILITY IN	WRINKLING LOAD
.119808-01	.702069+02	.140610+03	.000000
.119808-01	.672570+02	.140610+03	.000000
.119808-01	.672570+02	.140610+03	.000000
.239617-01	.564408+02	.786632+02	.000000
.239617-01	.529010+02	.799414+02	.000000
.239617-01	.506394+02	.799414+02	.000000
.359425-01	.416915+02	.643071+02	.000000
.359425-01	.393316+02	.610623+02	.000000
.359425-01	.386433+02	.618489+02	.000000
.479233-01	.332352+02	.499511+02	.000000
.479233-01	.321536+02	.479845+02	.000000
.479233-01	.321536+02	.476895+02	.000000
.599042-01	.281221+02	.427731+02	.000000
.599042-01	.268438+02	.406099+02	.000000
.599042-01	.274338+02	.410032+02	.000000
.718850-01	.268438+02	.361851+02	.000000
.718850-01	.255655+02	.351034+02	.000000
.718850-01	.255655+02	.349068+02	.000000

NONDIMENSIONAL DATA FOR PRESSURE STABILIZED ARCH

RADIUS RATIO= 13.0000
 REFERENCE RATIO= 313.0000

PRESSURE	NONDIMENSIONAL FLEXIBILITY OUT	FLEXIBILITY IN	WRINKLING LOAD
.239617-01	.188792+02	.196658+02	.176279-01
.239617-01	.188792+02	.188792+02	.176279-01
.239617-01	.188792+02	.192725+02	.000000
.479233-01	.148477+02	.136677+02	.271199-01
.479233-01	.144544+02	.134711+02	.271199-01
.479233-01	.139627+02	.134711+02	.000000
.718850-01	.114062+02	.107179+02	.362728-01
.718850-01	.118978+02	.104229+02	.355948-01
.718850-01	.118978+02	.104229+02	.000000
.958466-01	.102262+02	.914459+01	.457648-01
.958466-01	.100296+02	.875128+01	.457648-01
.958466-01	.983289+01	.894793+01	.000000
.119808+00	.904626+01	.757133+01	.576297-01
.119808+00	.875128+01	.737467+01	.576297-01
.119808+00	.845629+01	.737467+01	.000000
.143770+00	.786632+01	.668637+01	.711896-01
.143770+00	.766966+01	.658304+01	.694946-01
.143770+00	.747300+01	.658804+01	.694946-01

NONDIMENSIONAL DATA FOR PRESSURE STABILIZED ARCH

RADIUS RATIO= 11.2857
REFERENCE RATIO= 313.0000

PRESSURE	NONDIMENSIONAL FLEXIBILITY OUT	FLEXIBILITY IN	WRINKLING LOAD
.279553-01	.117011+02	.165193+02	.238267-01
.279553-01	.117011+02	.165193+02	.238267-01
.279553-01	.114062+02	.165193+02	.238267-01
.559105-01	.914459+01	.116028+02	.383552-01
.559105-01	.875128+01	.117011+02	.383552-01
.559105-01	.845629+01	.116028+02	.383552-01
.838658-01	.737467+01	.914459+01	.493969-01
.838658-01	.727634+01	.875128+01	.493969-01
.838658-01	.707969+01	.865295+01	.493969-01
.111821+00	.639138+01	.776799+01	.668311-01
.111821+00	.629305+01	.747300+01	.668311-01
.111821+00	.619472+01	.737467+01	.668311-01
.139776+00	.560475+01	.668637+01	.770010-01
.139776+00	.550642+01	.639138+01	.770010-01
.139776+00	.550642+01	.639138+01	.770010-01
.167732+00	.491645+01	.589974+01	.000000
.167732+00	.491645+01	.589974+01	.000000
.167732+00	.491645+01	.599807+01	.000000

DATA, L 16.
DATA T7 RL70-5 11/03-15:34:52

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1.	.190000+02	.159744-01	.464113+02	.664704+02	.711896-02
2.	.190000+02	.159744-01	.468046+02	.666637+02	.711896-02
3.	.190000+02	.159744-01	.451330+02	.659787+02	.711896-02
4.	.190000+02	.319489-01	.355951+02	.395262+02	.132209-01
5.	.190000+02	.319489-01	.346118+02	.379550+02	.132209-01
6.	.190000+02	.319489-01	.353984+02	.375566+02	.137294-01
7.	.190000+02	.479233-01	.277288+02	.311703+02	.198314-01
8.	.190000+02	.479233-01	.274338+02	.300887+02	.198314-01
9.	.190000+02	.479233-01	.270405+02	.297937+02	.198314-01
10.	.190000+02	.638978-01	.236973+02	.255655+02	.249164-01
11.	.190000+02	.638978-01	.234023+02	.251722+02	.244079-01
12.	.190000+02	.638978-01	.229106+02	.248772+02	.244079-01
13.	.190000+02	.798722-01	.209441+02	.213374+02	.289843-01
14.	.190000+02	.798722-01	.204524+02	.210424+02	.294928-01
15.	.190000+02	.798722-01	.202558+02	.208457+02	.289843-01
16.	.190000+02	.958466-01	.190758+02	.178959+02	.371203-01
17.	.190000+02	.958466-01	.185842+02	.176009+02	.371203-01
18.	.190000+02	.958466-01	.183875+02	.172076+02	.371203-01
19.	.250000+02	.119808-01	.702069+02	.140610+03	.000000
20.	.250000+02	.119808-01	.672570+02	.140610+03	.000000
21.	.250000+02	.119808-01	.672570+02	.140610+03	.000000
22.	.250000+02	.239617-01	.564408+02	.786632+02	.000000
23.	.250000+02	.239617-01	.529010+02	.799414+02	.000000
24.	.250000+02	.239617-01	.506394+02	.799414+02	.000000
25.	.250000+02	.359425-01	.416915+02	.643071+02	.000000
26.	.250000+02	.359425-01	.393316+02	.610623+02	.000000
27.	.250000+02	.359425-01	.386433+02	.618489+02	.000000
28.	.250000+02	.479233-01	.332352+02	.499511+02	.000000
29.	.250000+02	.479233-01	.321536+02	.479845+02	.000000
30.	.250000+02	.479233-01	.321536+02	.476895+02	.000000
31.	.250000+02	.599042-01	.281221+02	.427731+02	.000000
32.	.250000+02	.599042-01	.268438+02	.406099+02	.000000
33.	.250000+02	.599042-01	.274338+02	.410032+02	.000000
34.	.250000+02	.718850-01	.268438+02	.361851+02	.000000
35.	.250000+02	.718850-01	.255655+02	.351034+02	.000000
36.	.250000+02	.718850-01	.255655+02	.349068+02	.000000
37.	.130000+02	.239617-01	.188792+02	.196658+02	.176279-01
38.	.130000+02	.239617-01	.188792+02	.188792+02	.176279-01
39.	.130000+02	.239617-01	.188792+02	.192725+02	.000000
40.	.130000+02	.479233-01	.148477+02	.136677+02	.271199-01
41.	.130000+02	.479233-01	.144544+02	.134711+02	.271199-01
42.	.130000+02	.479233-01	.139627+02	.134711+02	.000000
43.	.130000+02	.718850-01	.114062+02	.107179+02	.362728-01
44.	.130000+02	.718850-01	.118978+02	.104229+02	.355948-01
45.	.130000+02	.718850-01	.118978+02	.104229+02	.000000
46.	.130000+02	.958466-01	.102262+02	.914459+01	.457648-01
47.	.130000+02	.958466-01	.100296+02	.875128+01	.457648-01
48.	.130000+02	.958466-01	.983289+01	.894793+01	.000000
49.	.130000+02	.119808+00	.904626+01	.757133+01	.576297-01
50.	.130000+02	.119808+00	.875128+01	.737467+01	.576297-01
51.	.130000+02	.119808+00	.845629+01	.737467+01	.000000
52.	.130000+02	.143770+00	.786632+01	.686637+01	.711896-01
53.	.130000+02	.143770+00	.766966+01	.658804+01	.694946-01
54.	.130000+02	.143770+00	.747300+01	.658804+01	.694946-01
55.	.112857+02	.279553-01	.117011+02	.165193+02	.238267-01

56.	.112857+02	.279553-01	.117011+02	.165193+02	.238267-01
57.	.112857+02	.279553-01	.114062+02	.165193+02	.238267-01
58.	.112857+02	.559105-01	.914459+01	.116028+02	.383552-01
59.	.112857+02	.559105-01	.875128+01	.117011+02	.383552-01
60.	.112857+02	.559105-01	.845629+01	.116028+02	.383552-01
61.	.112857+02	.838658-01	.737467+01	.914459+01	.493969-01
62.	.112857+02	.838658-01	.727634+01	.875128+01	.493969-01
63.	.112857+02	.838658-01	.707968+01	.865295+01	.493969-01
64.	.112857+02	.111821+00	.639138+01	.776799+01	.668311-01
65.	.112857+02	.111821+00	.629305+01	.747300+01	.668311-01
66.	.112857+02	.111821+00	.619472+01	.737467+01	.668311-01
67.	.112857+02	.139776+00	.560475+01	.668637+01	.770010-01
68.	.112857+02	.139776+00	.550642+01	.639138+01	.770010-01
69.	.112857+02	.139776+00	.550642+01	.639138+01	.770010-01
70.	.112857+02	.167732+00	.491645+01	.589974+01	.000000
71.	.112857+02	.167732+00	.491645+01	.589974+01	.000000
72.	.112857+02	.167732+00	.491645+01	.599807+01	.000000

END DATA.

@ERS
FURPUR 27R2 RL72R1 11/03/77 15:34:56
END ERS.

@ERS 15.
END ERS.

@ASG,T 10.,F14 . FILE WITH GAUSSIAN INTEGRATION CONSTANTS

@FOR,IS
FOR 00E3-11/03/77-15:42:08

MAIN PROGRAM

STORAGE USED: CODE(1) 000041; DATA(0) 000321; BLANK COMMON(2) 000000

EXTERNAL REFERENCES (BLOCK, NAME)

0003 LGAUSS
0004 NINTR\$
0005 NWDUS
0006 NIO2\$
0007 NIO1\$
0010 NSTOPS

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

0001	000012 1L	0001	000030 114G	0000	000312 2F	0000	000313 3F	0000 I 000311 I
0000	I 000310 N	0000	R 000144 W	0000	R 000000 X			

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00101	1*		DIMENSION X(100),W(100)	000000
00103	2*		N=90	000001
00104	3*		CALL LGAUSS(X,W,N,\$1)	000003
00105	4*	1	CONTINUE	000012
00106	5*		WRITE(10,2) N	000012
00111	6*	2	FORMAT(I4)	000021
00112	7*		WRITE(10,3) (X(I),W(I),I=1,N)	000021
00121	8*	3	FORMAT(2E18.8)	000034
00122	9*		STOP	000034
00123	10*		END	000040

END OF COMPILATION: NO DIAGNOSTICS.

@XQT
MAP2BR1 RL71-3 11/03/77 15:43:13

ADDRESS LIMITS	001000 010071	3642 IBANK WORDS DECIMAL
	040000 044220	2193 DBANK WORDS DECIMAL
STARTING ADDRESS	010031	

SEGMENT \$MAINS	001000 010071	040000 044220
NSWTC\$/FOR69	\$(1) 001000 001024	
NRBLK\$/FOR-E2	\$(1) 001025 001047	
NRWND\$/FOR-E3	\$(1) 001050 001133	\$(2) 040000 040011

NWEF\$/FOR-E2	\$(1)	001134 001341	\$(2)	040012 040031
NBDCV\$/FOR-E0	\$(1)	001342 001472	\$(2)	040032 040107
NFTV\$/FOR-E2	\$(1)	001473 001515		
NCNVT\$/FOR68	\$(1)	001516 001737	\$(2)	040110 040204
NCLOS\$/FOR-E2	\$(1)	001740 002175	\$(2)	040205 040232
NWBLK\$/FOR68	\$(1)	002176 002307		
NBSBL\$/FOR68	\$(1)	002310 002350		
NUPDAS\$/FOR68	\$(1)	002351 002404		
NBF00\$			\$(2)	040233 042460
NOTINS\$/FOR-E3	\$(1)	002405 002701	\$(2)	042461 042464
NOUT\$/FOR-E3	\$(1)	002702 004416	\$(2)	042465 042526
NFMT\$/FOR-E3	\$(1)	004417 005301	\$(2)	042527 042603
NIOER\$/FOR-E3	\$(1)	005302 005521	\$(2)	042604 042753
NFCHK\$/FOR-E3	\$(1)	005522 006513	\$(2)	042754 043124
	\$(3)	006514 006514	\$(4)	043125 043176
NTABS\$/FOR-TE3			\$(2)	043177 043235
FORCOM\$/FORFTN			\$(2)	043236 043243
ERU\$/SYS72-8				
NERCOM\$/FOR-TE3	\$(1)	006515 006574	\$(2)	043244 043257
FORVCOM\$/FOR-TE3			\$(2)	043260 043267
NERR\$/FOR-E3	\$(1)	006575 007136	\$(2)	043270 043447
NSTOP\$/FOR-TE3	\$(1)	007137 007201	\$(2)	043450 043457
NIER\$/FOR-E3	\$(1)	007202 007357	\$(2)	043460 043577
NOBUF\$/FOR68	\$(1)	007360 007420		
NINTR\$/FOR-E3	\$(1)	007421 007473	\$(2)	043600 043615
LGAUSS	\$(1)	007474 010030	\$(0)	043616 043677
			\$(2)	BLANK\$COMMON
BLANK\$COMMON(COMMONBLOCK)				
NAMES	\$(1)	010031 010071	\$(0)	043700 044220
			\$(2)	BLANK\$COMMON

SYS\$*RLIB\$. LEVEL 72-8
 END MAP

@DATA, L 10.
DATA T7 RL70-5 11/03-15:46:06

1.	90	
2.	-.99964698+00	.90525975-03
3.	-.99814039+00	.21074554-02
4.	-.99543183+00	.33086729-02
5.	-.99152394+00	.45059690-02
6.	-.98642138+00	.56979301-02
7.	-.98013026+00	.68829324-02
8.	-.97265817+00	.80596809-02
9.	-.96401411+00	.92266372-02
10.	-.95420849+00	.10382556-01
11.	-.94325311+00	.11525941-01
12.	-.93116120+00	.12655360-01
13.	-.91794731+00	.13769669-01
14.	-.90362736+00	.14867329-01
15.	-.88821861+00	.15947057-01
16.	-.87173963+00	.17007603-01
17.	-.85421026+00	.18047633-01
18.	-.83565165+00	.19065906-01
19.	-.81608614+00	.20061191-01
20.	-.79553731+00	.21032342-01
21.	-.77402992+00	.21978135-01
22.	-.75158988+00	.22897445-01
23.	-.72824423+00	.23789182-01
24.	-.70402111+00	.24652231-01
25.	-.67894970+00	.25485585-01
26.	-.65306021+00	.26288226-01
27.	-.62638382+00	.27059213-01
28.	-.59895270+00	.27797571-01
29.	-.57079988+00	.28502445-01
30.	-.54195929+00	.29172971-01
31.	-.51246569+00	.29808359-01
32.	-.48235460+00	.30407821-01
33.	-.45166232+00	.30970540-01
34.	-.42042581+00	.31496140-01
35.	-.38868273+00	.31983702-01
36.	-.35647131+00	.32432720-01
37.	-.32383037+00	.32842656-01
38.	-.29079925+00	.33213020-01
39.	-.25741773+00	.33543365-01
40.	-.22372605+00	.33833297-01
41.	-.18976479+00	.34082457-01
42.	-.15557488+00	.34290551-01
43.	-.12119751+00	.34457333-01
44.	-.86674112-01	.34582590-01
45.	-.52046277-01	.34666181-01
46.	-.17355731-01	.34707999-01
47.	.17355731-01	.34707999-01
48.	.52046277-01	.34666181-01
49.	.86674112-01	.34582590-01
50.	.12119751+00	.34457333-01
51.	.15557488+00	.34290551-01
52.	.18976479+00	.34082457-01
53.	.22372605+00	.33833297-01
54.	.25741773+00	.33543365-01
55.	.29079925+00	.33213020-01

56.	.32383037+00	.32842656-01
57.	.35647131+00	.32432720-01
58.	.38868273+00	.31983702-01
59.	.42042581+00	.31496140-01
60.	.45166232+00	.30970640-01
61.	.48235460+00	.30407821-01
62.	.51246569+00	.29808359-01
63.	.54195929+00	.29172971-01
64.	.57079988+00	.28502445-01
65.	.59895270+00	.27797571-01
66.	.62638382+00	.27059213-01
67.	.65306021+00	.26282226-01
68.	.67894970+00	.25485585-01
69.	.70402111+00	.24652231-01
70.	.72824423+00	.23789182-01
71.	.75158988+00	.22897445-01
72.	.77402992+00	.21978135-01
73.	.79553731+00	.21032342-01
74.	.81608614+00	.20061191-01
75.	.83565165+00	.19065906-01
76.	.85421026+00	.18047633-01
77.	.87173963+00	.17007603-01
78.	.88821861+00	.15947057-01
79.	.90362736+00	.14867329-01
80.	.91794731+00	.13769669-01
81.	.93116120+00	.12655380-01
82.	.94325511+00	.11525941-01
83.	.95420849+00	.10382556-01
84.	.96401411+00	.92266372-02
85.	.97265817+00	.80596809-02
86.	.98013026+00	.68829324-02
87.	.98642138+00	.56979301-02
88.	.99152394+00	.45059690-02
89.	.99543183+00	.33086729-02
90.	.99814039+00	.21074554-02
91.	.99964698+00	.90525975-03

END DATA.

@ERS
 FURPUR 27R2 RL72R1 11/03/77 15:46:15
 END ERS.

@ASG,T TP.,6C9,1964 . TAPE WITH ARCH ANALYSIS PROGRAMS

@MOVE TP,7
 FURPUR 27R2 RL72R1 11/03/77 15:46:37

@COPIN TP.,
 3 SYM

@FREE TP.

@FOR,S TPF\$.MAINARCH.M
FOR 00E3-11/03/77-15:57:21 (0.)

MAIN PROGRAM

STORAGE USED: CODE(1) 003227; DATA(0) 004616; BLANK COMMON(2) 001541

EXTERNAL REFERENCES (BLOCK, NAME)

0003 PLOTS
0004 NEWPEN
0005 DGJR
0006 CALCA
0007 CALPAR
0010 SCALE
0011 AXIS
0012 SYMBOL
0013 NUMBER
0014 PLOT
0015 FLINE
0016 LINE
0017 EXIT
0020 NINTR\$
0021 NRDC\$
0022 NIO2\$
0023 NRDU\$
0024 NIO3\$
0025 DSQRT
0026 NPRT\$
0027 DSIN
0030 DCOS
0031 NREW\$
0032 NIO1\$
0033 NWEF\$
0034 NSTOP\$

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

0001	000027	10L	0000	004274	1001F	0000	004300	1002F	0000	004316	1003F	0000	004324	1004F
0000	004335	1005F	0000	004346	1006F	0000	004220	1009F	0000	004216	1010F	0000	004352	1011F
0000	004204	1012F	0000	004373	1013F	0000	004430	1014F	0000	004450	1015F	0000	004457	1016F
0000	004464	1017F	0000	004471	1020F	0000	004175	1021F	0000	004200	1022F	0000	004160	1040F
0000	004153	1041F	0000	004147	1042F	0001	002062	1105G	0001	002104	1122G	0001	002112	1132G
0001	000125	20L	0000	004473	2001F	0001	001076	250L	0001	000411	251G	0001	001200	251L
0001	001054	252L	0001	000415	255G	0001	001036	300L	0000	004475	3001F	0000	004476	3002F
0000	004500	3003F	0000	004502	3004F	0000	004172	3005F	0000	004173	3006F	0001	001364	306L
0001	000535	322G	0001	000537	325G	0001	001266	328L	0001	001335	329L	0001	000542	331G
0001	000576	346G	0001	000605	353G	0001	000625	365G	0001	000626	370G	0001	001653	376L
0001	001676	377L	0001	001733	395L	0001	001734	396L	0001	000144	40L	0001	000650	401G
0001	002066	401L	0001	000651	404G	0001	000165	45L	0001	000755	460G	0001	000177	50L
0001	002067	500L	0001	001040	507G	0001	002200	510L	0001	002334	518L	0001	002342	520L
0001	002365	525L	0001	002375	530L	0001	002415	540L	0001	002417	550L	0001	002464	570L
0001	002660	580L	0001	002740	600L	0001	001204	605G	0001	001205	610G	0001	002743	610L
0001	001223	621G	0001	001224	624G	0001	001244	635G	0001	001245	640G	0001	003150	650L
0001	001273	656G	0001	001313	670G	0001	001324	674G	0001	001353	710G	0001	001576	763G

0001 001577 766G	0001 001610 776G	0001 003166 950L	0001 003161 960L	0001 003205 990L
0000 D 000032 A	0000 D 004050 AC	0000 D 004054 AE	0000 D 004035 ALPHA	0000 R 003307 AN
0000 R 003306 AR	0002 D 000007 ARR	0000 R 003310 AWI	0000 R 003311 AWO	0000 R 003312 AWRL
0000 D 000472 B	0000 D 004052 BC	0000 D 004056 BE	0002 D 000053 BETA	0002 D 000175 BLAM2
0002 D 000211 BLAM3	0000 D 004063 C	0000 R 001760 CN	0002 D 000111 CSA1	0002 D 000115 CSA3
0000 R 001612 CW	0000 R 002126 CWL	0002 D 000161 D	0002 D 000225 DA	0007 D 000005 E
0000 R 003140 ELN	0000 R 002624 EN	0000 R 002310 EWI	0000 R 002772 EWL	0000 R 002456 EWO
0000 D 004043 F	0002 D 000075 G	0002 D 000125 H	0002 D 000121 HCA2	0002 D 000123 HSA2
0000 I 004075 I	0002 I 001537 IBOUN	0002 I 000004 IC	0000 I 004102 ICL	0000 I 004034 IDUM
0000 I 004146 IEOF	0002 I 001540 IJUNC	0000 I 004033 ILOAD	0002 I 001535 INTEG	0000 I 004144 IP
0000 I 004032 IPLOT	0000 I 004141 ISAV	0002 I 001536 ITYP	0000 I 004077 J	0000 I 001576 JC
0000 I 004143 JP	0000 I 004076 K	0000 I 004106 KSET	0000 I 004103 LIN	0000 I 004145 NEXP
0000 I 004060 NIS	0000 I 004047 NMAX	0000 I 004142 NVAL	0000 D 004107 PA	0000 D 004111 PB
0000 D 004123 QCB	0000 D 004127 QCH	0000 D 004131 QG1	0000 D 004133 QG2	0000 D 004135 QG3
0000 D 004137 QG4	0000 D 000000 QIDEN	0000 D 004121 QSB	0000 D 004125 QSH	0002 D 000000 RHO
0000 D 004067 RHOSQ	0000 D 004071 RHOSQI	0000 D 003314 RLIM	0000 R 003313 RRHO	0000 D 004045 SMG
0002 D 000113 SNA1	0002 D 000117 SNA3	0002 D 000715 SOL	0000 D 001132 T	0000 D 003342 TARR
0000 D 004104 TEMPA	0000 D 004115 THEHAR	0000 D 004041 THEMAT	0000 D 004037 THETA	0000 D 004117 THETAR
0000 D 004113 THETR	0000 D 001572 V	0000 D 004100 WFA	0000 R 002304 WLSCAL	0000 R 002274 WSCAL
0000 D 003330 X	0000 D 004061 XC	0000 D 004065 XE	0002 D 000145 XI	0002 D 000002 XN
0000 D 003322 XNLIM	0000 R 002300 XNSCAL	0002 D 000153 XR	0002 D 000067 YLAM	0000 D 004073 YLAMSQ
0000 D 003334 Z				

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00100	1*	C		000000
00101	2*		IMPLICIT DOUBLE PRECISION(A-H,O-Z)	000000
00101	3*	C		000000
00101	4*	C	ELASTIC ANALYSIS OF PRESSURE STABILIZED ARCH	000000
00101	5*	C		000000
00101	6*	C	REQUESTED BY EARL C STEEVES, GEPL X2406	000000
00101	7*	C		000000
00101	8*	C	PURPOSE - SOLUTION OF SET OF SECOND ORDER DIFFERENTIAL EQUATIONS	000000
00101	9*	C	WITH CONSTANT COEFFICIENTS	000000
00101	10*	C		000000
00101	11*	C	C CHRETIEN	000000
00101	12*	C	OCTOBER 1973	000000
00101	13*	C	CHANGE FEB 1974	000000
00101	14*	C		000000
00101	15*	C		000000
00101	16*	C		000000
00101	17*	C	H=ARRAY CONTAINING CONSTANT COEFFICIENTS IN EQUATIONS	000000
00101	18*	C	E,RHO,C,XN - INPUT POSSIBLY VARYING OVER AN INTERVAL	000000
00101	19*	C	ARRAYS ELIM,RLIM,CLIM,XNLIM,ARE USED TO READ INIT,FINAL,DELTA	000000
00101	20*	C	OF EACH	000000
00101	21*	C	λINT=ARRAY OF 3 VARIABLES DEFINED IN TERMS OF INTEGRAL	000000
00101	22*	C	NUMERICALLY EVALUATED	000000
00103	23*		COMMON RHO,XN,IC,E	000001
00104	24*		COMMON ARR(3,6),BETA(6),YLAM(3),G(6),CSA1,SNA1,CSA3,SNA3	000001
00105	25*		COMMON HCA2,HSA2,H(8)	000001
00106	26*		COMMON XI(3),XR(3),D(6),BLAM2(6),BLAM3(6)	000001
00107	27*		COMMON DA(12,13),SOL(200),INTEG,ITYP,IBOUN,IJUNC	000001
00110	28*		DIMENSION QIDEN(13)	000001
00111	29*		DIMENSION A(12,12),B(12,12),T(12,12),V(2),JC(12)	000001
00112	30*		REAL CW(102),CN(102),CWL(102)	000001
00113	31*		REAL WSCAL(4),XNSCAL(4),WLSCAL(4)	000001

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00114 32*      REAL EWI(102),EWO(102),EN(102),EWL(102),ELN(102)      000001
00115 33*      REAL AR,AN,AWI,AWO,AWRL,RRHO      000001
00116 34*      DIMENSION RLIM(3),XNLIM(3),X(2),Z(3)      000001
00117 35*      DIMENSION TARR(12,13)      000001
00120 36*      READ 3001 IPLOT,ILOAD,INTEG,IBOUN      000001
00120 37*      C      IBOUN=0      CLAMPED ENDS      000001
00120 38*      C      IBOUN=1      SIMPLY SUPPORTED ENDS      000001
00120 39*      C      INTEG=0 IMPLIES NO INTEGRATION OF GREEN S FUNCTION      000001
00120 40*      C      INTEG=1 IMPLIES INTEGRATION OF GREEN S FUNCTION      000001
00120 41*      C      ITYP=0      CONCENTRATED LOAD AND INTEGRATION OF GREEN FUNCTION      000001
00120 42*      C      ITYP=1      UNIFORM LOAD      000001
00120 43*      C      ILOAD=0      IMPLIES NORMAL LOAD      000001
00120 44*      C      ILOAD=1      IMPLIES VERTICAL LOAD      000001
00126 45*      IF (IPLOT .EQ. 1) GO TO 10      000011
00130 46*      IDUM=100      000014
00131 47*      CALL PLOTS (IDUM,IDUM,20)      000016
00132 48*      CALL NEWPEN (1)      000023
00132 49*      C      CALL PLOT (0.0,-36.0,-3)      000023
00132 50*      C      CALL PLOT (0.0,2.0,-3)      000023
00133 51*      10 READ( 5,3002,END=990) RLIM,XNLIM      000027
00137 52*      READ 1001,ALPHA,THETA, THEHAT      000042
00144 53*      READ 2001, F,SMG,NMAX      000051
00151 54*      READ 3002 AC,BC,AE,BE      000060
00157 55*      NIS=0      000070
00160 56*      READ 1010,QIDEN      000071
00163 57*      X(1)=0.0      000100
00164 58*      X(2)=2.0*3.14159      000102
00165 59*      RHO=RLIM(1)      000104
00166 60*      XC=AC+XNLIM(1)+BC      000106
00167 61*      C=XC      000112
00170 62*      XE=AE+XNLIM(1)+BE      000113
00171 63*      E=XE      000117
00172 64*      XN=XNLIM(1)      000120
00173 65*      IC=0      000122
00174 66*      GO TO 50      000123
00175 67*      20 IF (RHO .GE. RLIM(2)) GO TO 10      000125
00177 68*      RHO=RHO+RLIM(3)      000130
00200 69*      C=XC      000133
00201 70*      E=XE      000135
00202 71*      XN=XNLIM(1)      000137
00203 72*      IC=0      000141
00204 73*      GO TO 50      000142
00205 74*      40 IF (XN .LT. XNLIM(2)) GO TO 45      000144
00207 75*      IF (SMG .EQ. 0.0 .OR. IPLOT .EQ. 1) GO TO 20      000147
00211 76*      GO TO 500      000163
00212 77*      45 XN=XN+XNLIM(3)      000165
00213 78*      C=AC+XN+BC      000167
00214 79*      E=AE+XN+BE      000172
00215 80*      50 RHOSQ=RHO+RHO      000177
00216 81*      RHOSQI=1.0/RHOSQ      000201
00217 82*      Z(1)=RHOSQ*RHOSQ*(2.0/(SQRT(1.0-RHOSQI))-2.0-RHOSQI)      000204
00220 83*      Z(2)=1.0+RHOSQI*Z(1)      000222
00221 84*      Z(3)=(1.0+RHOSQI*(1.0-Z(1))+RHOSQI*RHOSQI*Z(1))      000225
00222 85*      H(1)=2.0*E/RHO+E*Z(2)/(RHOSQ*RHO)      000236
00223 86*      H(2)=C*Z(3)/RHO+XN*Z(2)/RHO      000251
00224 87*      H(3)=E*Z(2)/RHOSQ      000261
00225 88*      H(4)=C*Z(3)+XN*Z(1)/RHOSQ      000264

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00226	89*	H(5)=H(1)+H(2)	000271
00227	90*	H(6)=RHO*H(3)	000274
00230	91*	H(7)=RHO*H(4)	000277
00231	92*	H(8)=H(3)+H(4)	000302
00232	93*	YLAMSQ=-(H(1)*H(4)*(H(4)-RHO*H(2)))/(H(2)*H(3)*(RHO*H(1)-H(3)))	000305
00233	94*	YLAM(1)=SQRT(YLAMSQ)	000323
00234	95*	YLAM(2)=0.0	000327
00235	96*	YLAM(3)=1.0	000331
00235	97*	C	000331
00235	98*	C CALCULATION OF BETA	000331
00235	99*	C	000331
00235	100*	C	000331
00235	101*	C	000331
00236	102*	A(1,1)=YLAMSQ*H(1)-H(2)	000333
00237	103*	A(2,1)=YLAMSQ*H(3)-H(4)	000337
00240	104*	A(1,2)=A(2,1)	000343
00241	105*	A(2,2)=YLAMSQ*H(6)-H(7)	000344
00242	106*	183 B(1,1)=-YLAM(1)*H(5)	000350
00243	107*	B(2,1)=-YLAM(1)*H(8)	000354
00244	108*	V(1)=1.0	000360
00245	109*	CALL DGJR(A,12,12,2,2,\$960,JC,V)	000361
00246	110*	IF (JC(1) .NE. 2) GO TO 950	000373
00250	111*	DO 190 I=1,2	000411
00253	112*	BETA(I)=0.0	000411
00254	113*	DO 185 K=1,2	000415
00257	114*	BETA(I)=BETA(I)+A(I,K)*B(K,1)	000415
00260	115*	185 CONTINUE	0.0421
00262	116*	BETA(I)=-BETA(I)	000421
00263	117*	190 CONTINUE	000430
00265	118*	A(1,1)=-H(1)-H(2)	000430
00266	119*	A(2,1)=-H(3)-H(4)	000432
00267	120*	A(3,1)=0.0	000434
00270	121*	A(4,1)=0.0	000436
00271	122*	A(1,2)=A(2,1)	000437
00272	123*	A(2,2)=-H(6)-H(7)	000441
00273	124*	A(3,2)=0.0	000445
00274	125*	A(4,2)=0.0	000446
00275	126*	A(1,3)=-2.0*H(1)	000447
00276	127*	A(2,3)=-2.0*H(3)	000453
00277	128*	A(3,3)=-H(1)-H(2)	000457
00300	129*	A(4,3)=-H(3)-H(4)	000460
00301	130*	A(1,4)=A(2,3)	000461
00302	131*	A(2,4)=-2.0*H(6)	000463
00303	132*	A(3,4)=A(2,1)	000467
00304	133*	A(4,4)=A(2,2)	000471
00305	134*	B(1,1)=H(5)	000473
00306	135*	B(2,1)=H(8)	000475
00307	136*	B(3,1)=0.0	000477
00310	137*	B(4,1)=0.0	000500
00311	138*	B(1,2)=-H(5)	000501
00311	139*	B(2,2)=-H(8)	000503
00313	140*	B(3,2)=-H(5)	000505
00314	141*	B(4,2)=-H(8)	000507
00315	142*	V(1)=1.0	000511
00316	143*	CALL DGJR(A,12,12,4,4,\$960,JC,V)	000513
00317	144*	IF (JC(1) .NE. 4) GO TO 950	000525
00321	145*	DO 200 I=1,4	000537

00324	146*	DO 200 J=1,2	000537
00327	147*	T(I,J)=0.0	000537
00330	148*	DO 200 K=1,4	000542
00333	149*	T(I,J)=T(I,J)+A(I,K)*B(K,J)	000542
00334	150*	200 CONTINUE	000561
00340	151*	BETA(3)=-T(1,1)	000561
00341	152*	BETA(4)=-T(2,1)	000563
00342	153*	BETA(5)=-T(1,2)	000565
00343	154*	BETA(6)=-T(2,2)	000567
00343	155*	C	000567
00343	156*	C UNIFORM LOAD	000567
00343	157*	C	000567
00344	158*	IJUNC=0	000571
00345	159*	DO 210 I=1,6	000576
00350	160*	BLAM2(I)=BETA(I)*YLAM(2)	000576
00351	161*	BLAM3(I)=BETA(I)*YLAM(3)	000600
00352	162*	DO 210 J=1,6	000605
00355	163*	A(I,J)=0.0	000605
00356	164*	210 CONTINUE	000614
00361	165*	IF (F.EQ. 0.0) GO TO 300	000614
00363	166*	CALL CALCA (ALPHA)	000616
00364	167*	DO 212 I=1,3	000626
00367	168*	DO 211 J=1,6	000626
00372	169*	TARR(I+3,J)=ARR(I,J)	000626
00373	170*	211 CONTINUE	000637
00375	171*	212 CONTINUE	000637
00377	172*	CALL CALCA (-ALPHA)	000637
00400	173*	DO 217 I=1,3	000651
00403	174*	DO 216 J=1,6	000651
00406	175*	TARR(I,J)=ARR(I,J)	000651
0040	176*	216 CONTINUE	000662
00411	177*	217 CONTINUE	000662
00413	178*	PRINT 1011	000662
00415	179*	IF (IBOUN.EQ.1) PRINT 1041	000666
00420	180*	IF (IBOUN.EQ.0) PRINT 1042	000675
00423	181*	1042 FORMAT(59X'CLAMPED ENDS')	000703
00424	182*	1041 FORMAT(56X'SIMPLY SUPPORTED ENDS')	000703
00425	183*	PRINT 1010 QIDEN	000703
00430	184*	PRINT 1040 AC,BC,AE,BE	000712
00436	185*	1040 FORMAT(/5X,'C=',F6.4,'*N+',F6.4/5X,'E=',F6.3,'*N+',F6.4)	000722
00437	186*	PRINT 1013, ALPHA,RHO,E,C,XN	000722
00446	187*	PRINT 1014	000733
00446	188*	C	000733
00446	189*	C SOLVE FOR G	000733
00446	190*	C	000733
00450	191*	G(1)=-F/H(1)	000737
00451	192*	TARR(1,7)=0.0	000743
00452	193*	TARR(2,7)=0.0	000745
00453	194*	TARR(3,7)=-G(1)	000746
00454	195*	TARR(4,7)=0.0	000747
00455	196*	TARR(5,7)=0.0	000750
00456	197*	TARR(6,7)=-G(1)	000751
00456	198*	C UNIFORM LOAD IS REDUCED TO A PROBLEM OF ORDER 3 BY STMMETRY	000751
00457	199*	DO 221 I=1,3	000755
00462	200*	TARR(I,2)=TARR(I,4)	000755
00463	201*	TARR(I,3)=TARR(I,5)	000756
00464	202*	221 TARR(I,4)=TARR(I,7)	000760

00466	203*	IF(IBOUN.EQ.1) TARR(2,4)= G(1)	000763
00470	204*	V(1)=4.0	000770
00471	205*	CALL DGJR(TARR,13,12,3,4,\$960,JC,V)	000772
00472	206*	D(1)=TARR(1,4)	001004
00473	207*	D(2)=0.0	001006
00474	208*	D(3)=0.0	001010
00475	209*	D(4)=TARR(2,4)	001011
00476	210*	D(5)=TARR(3,4)	001013
00477	211*	D(6)=0.0	001015
00500	212*	ITYP=1	001016
0050	213*	CALL CALPAR(-ALPHA,NMAX,THETA,WFA,0,0)	001020
00502	214*	IF (SMG .EQ. 0.0) GO TO 40	001032
00502	215*	C	001032
00502	216*	C GREEN'S FUNCTION	001032
00502	217*	C CONCENTRATED LOAD	001032
00502	218*	C	001032
00504	219*	300 CONTINUE	001040
00505	220*	3005 FORMAT(I4)	001040
00506	221*	DO 303 ICL=1,200	001040
00511	222*	303 SOL(ICL)=0.0	001040
00513	223*	LIN=0	001042
00514	224*	IF(INTEG.EQ.0) GO TO 250	001043
00516	225*	READ(10,3005) NIS	001045
00521	226*	252 LIN=LIN+1	001054
00522	227*	IJUNC=0	001056
00523	228*	READ(10,3006) THETA,WFA	001057
00527	229*	THETA=THETA*ALPHA	001066
00530	230*	WFA=0.01745*ALPHA*WFA	001071
00531	231*	3006 FORMAT (2E18.8)	001076
00532	232*	250 CONTINUE	001076
00533	233*	IF(INTEG.EQ.1) GOTO 251	001076
00535	234*	PRINT 1002	001100
00537	235*	IF(ILOAD.EQ.0)PRINT 1021	001104
00542	236*	IF(ILOAD.EQ.1)PRINT 1022	001112
00545	237*	1021 FORMAT(61X,8H(NORMAL))	001121
00546	238*	1022 FORMAT(60X,10H(VERTICAL))	001121
00547	239*	IF(IBOUN.EQ.1) PRINT 1041	001121
00552	240*	IF(IBOUN.EQ.0) PRINT 1042	001130
00555	241*	PRINT 1010 QIDEN	001136
00560	242*	PRINT 1040 AC,BC,AE,BE	001145
00566	243*	PRINT 1013, ALPHA,RHO,E,C,XN	001155
00575	244*	PRINT 1003, THETA	001166
00600	245*	PRINT 1014	001173
00602	246*	251 CONTINUE	001200
00603	247*	G(1)=0.0	001200
00604	248*	DO 310 I=1,3	001205
00607	249*	DO 310 J=7,12	001205
00612	250*	A(I,J)=0.0	001205
00613	251*	A(I+3,J-6)=0.0	001206
00614	252*	310 CONTINUE	001214
00617	253*	CALL CALCA(0.0)	001214
00620	254*	DO 320 I=1,3	001224
00623	255*	DO 315 J=1,6	001224
00626	256*	A(I,J)=ARR(I,J)	001224
00627	257*	315 CONTINUE	001235
00631	258*	320 CONTINUE	001235
00633	259*	CALL CALCA(0.0)	001235

00634	260*	DO 324 I=4,6	001245
00637	261*	DO 323 J=7,12	001245
00642	262*	A(I,J)=ARR(I-3,J-6)	001245
00643	263*	323 CONTINUE	001256
00645	264*	324 CONTINUE	001256
00647	265*	IJUNC=1	001256
00650	266*	TEMPA=THETA	001260
00651	267*	KSET=1	001262
00652	268*	IF(KSET.EQ.1) GO TO 329	001263
00654	269*	328 KSET=KSET+1	001266
00655	270*	DO 360 J=1,6	001273
00660	271*	A(10,J+6)=-A(10,J)	001273
00661	272*	A(11,J+6)=-A(11,J)	001274
00662	273*	A(12,J+6)=A(12,J)	001276
00663	274*	360 CONTINUE	001301
00665	275*	THETA=ALPHA+TEMPA	001301
00666	276*	CALL CALCA(THETA)	001304
00667	277*	DO 330 I=1,3	001313
00672	278*	K=I+6	001313
00673	279*	DO 325 J=1,6	001316
00676	280*	A(K,J)=ARR(I,J)	001324
00677	281*	325 CONTINUE	001333
00701	282*	330 CONTINUE	001333
00703	283*	GO TO 306	001333
00704	284*	329 CONTINUE	001335
00705	285*	THETA=ALPHA-THETA	001335
00706	286*	CALL CALCA(THETA)	001337
00707	287*	DO 305 J=1,6	001353
00712	288*	A(I,J+6)=-A(I,J)	001353
00713	289*	A(7,J+6)=ARR(1,J)	001354
00714	290*	A(8,J+6)=ARR(2,J)	001356
00715	291*	A(9,J+6)=-ARR(3,J)	001360
00716	292*	305 CONTINUE	001364
00720	293*	304 CONTINUE	001364
00721	294*	306 CONTINUE	001364
00722	295*	PA=H(1)*(BETA(1)*YLAM(1)-1.0)+H(3)*BETA(2)*YLAM(1)	001364
00723	296*	A(10,1)=PA*CSA1	001375
00724	297*	A(10,2)=PA*SNA1	001377
00725	298*	PA=BETA(1)*YLAM(1)-1.0+RHO*BETA(2)*YLAM(1)	001402
00726	299*	A(11,1)=PA*CSA1	001407
00727	300*	A(11,2)=PA*SNA1	001411
00730	301*	PA=H(2)*(YLAM(1)+BETA(1))+H(4)*BETA(2)	001414
00731	302*	A(12,1)=PA*SNA1	001423
00732	303*	A(12,2)=PA*CSA1	001425
00733	304*	PA=(BETA(3)-1.0)*H(1)+H(3)*BETA(4)	001430
00734	305*	PB=(BETA(5)-BETA(3))*H(1)+H(3)*(BETA(6)-BETA(4))	001440
00735	306*	THETR=THETA	001452
00736	307*	THETA=0.01745*THETA	001454
00737	308*	A(10,3)=PA*SNA3	001456
00740	309*	A(10,4)=PA*CSA3	001460
00741	310*	A(10,5)=PB*CSA3+THETA*A(10,3)	001463
00742	311*	A(10,6)=-PB*SNA3+THETA*A(10,4)	001467
00743	312*	PA=BETA(3)-1.0+RHO*BETA(4)	001475
00744	313*	PB=(BETA(5)-BETA(3))+RHO*(BETA(6)-BETA(4))	001501
00745	314*	A(11,3)=PA*SNA3	001505
00746	315*	A(11,4)=PA*CSA3	001507
00747	316*	A(11,5)=PB*CSA3+THETA*A(11,3)	001512

00750	317*	A(11,6)=-PB*SNA3+THETA*A(11,4)	001517
00751	318*	PA=H(2)*(1.0-BETA(3))-H(4)*BETA(4)	001525
00752	319*	PB=H(2)*(1.0+BETA(5))+H(4)*BETA(6)	001535
00753	320*	A(12,3)=PA*CSA3	001544
00754	321*	A(12,4)=-PA*SNA3	001547
00755	322*	A(12,5)=A(12,3)*THETA+PB*SNA3	001553
00756	323*	A(12,6)=A(12,4)*THETA+PB*CSA3	001560
00757	324*	IF(KSET.EQ.1) GO TO 328	001566
00761	325*	THETA=TEMPA	001571
00762	326*	DO 370 I=1,12	001577
00765	327*	DO 365 J=1,12	001577
00770	328*	DA(I,J)=A(I,J)	001577
00771	329*	365 CONTINUE	001610
00773	330*	370 CONTINUE	001610
00775	331*	DO 375 I=1,11	001610
01000	332*	DA(I,13)=0.0	001610
01001	333*	375 CONTINUE	001612
01003	334*	THEHAR=0.01745*THEHAT	001612
01004	335*	THETAR=0.01745*THETA	001615
01005	336*	QSB=SIN(THETAR)	001620
01006	337*	QCB=COS(THETAR)	001624
01007	338*	QSH=SIN(THETAR)	001630
01010	339*	QCH=COS(THETAR)	001634
01011	340*	IF(ILOAD.EQ.1) GO TO 376	001640
01013	341*	QG1=0.0	001643
01014	342*	QG2=0.0	001645
01015	343*	QG3=SMG	001646
01016	344*	QG4=0.0	001650
01017	345*	GO TO 377	001651
01020	346*	376 QG1=-SMG*QSH*QSH*QCB	001653
0102	347*	QG2=-SMG*QSB	001660
01022	348*	QG3=SMG*QCH*QCH*QCB	001664
01023	349*	QG4=SMG*QCH*QSB	001672
01024	350*	377 DA(10,13)=QG2	001676
01025	351*	DA(11,13)=-QG4/H(3)	001677
01026	352*	DA(12,13)=QG1-QG3	001703
01027	353*	V(1)=4.0	001706
01030	354*	CALL DGJR(DA,13,12,12,13,\$960,JC,V)	001710
01031	355*	G(1)=0.0	001722
01032	356*	IF (IPL0T -1) 394,395,394	001724
01035	357*	394 ISAV=1	001727
01036	358*	GO TO 396	001731
01037	359*	395 ISAV=0	001733
01040	360*	396 NVAL=0	001734
01041	361*	ITYP=0	001734
01042	362*	CALL CALPAR(-ALPHA,NMAX,THETA,WFA,ISAV,NVAL)	001735
01043	363*	IF((LIN.LT.NIS).AND.(INTEG.EQ.1)) GO TO 252	001747
01045	364*	IF(INTEG.EQ.0) GO TO 401	001764
01047	365*	REWIND 10	001766
01050	366*	PRINT 1012	001771
01052	367*	IF(IBOUN.EQ.1) PRINT 1041	001775
01055	368*	IF(IBOUN.EQ.0) PRINT 1042	002004
01060	369*	PRINT 1010,QIDEN	002012
01063	370*	PRINT 1040 AC,BC,AE,BE	002021
01071	371*	PRINT 1013,ALPHA,RHO,E,C,XN	002031
01100	372*	PRINT 1014	002042
01102	373*	JP=B*(NMAX+1)	002046

01103	374*	PRINT 1009,((SOL(IP)),IP=1,JP)	002052
01111	375*	1012 FORMAT('1',45X,'DEFORMATION OFPRESSURE STABILIZED ARCHES')	002066
01112	376*	1010 FORMAT(1X,13A6)	002066
01113	377*	401 CONTINUE	002066
01114	378*	1009 FORMAT(/OPF10.3,1P7E17.8)	002066
01115	379*	GO TO 40	002066
01116	380*	500 END FILE 15	002067
01117	381*	REWIND 15	002071
01120	382*	RRHO=RHO	002074
01121	383*	DO 503 I=1,4	002104
01121	384*	WSCAL(I)=0.0	002104
01125	385*	XNSCAL(I)=0.0	002104
01126	386*	WLSCAL(I)=0.0	002105
01127	387*	503 CONTINUE	002112
01131	388*	DO 508 J=1,IC	002112
01134	389*	READ (15,3003) CN(J),CW(J),CWL(J)	002112
01141	390*	IF (CN(J) .LT. XNSCAL(1)) XNSCAL(1)=CN(J)	002121
01143	391*	IF (CN(J) .GT. XNSCAL(2)) XNSCAL(2)=CN(J)	002127
01145	392*	IF (CW(J) .LT. WSCAL(1)) WSCAL(1)=CW(J)	002135
01147	393*	IF (CW(J) .GT. WSCAL(2)) WSCAL(2)=CW(J)	002143
01151	394*	IF (CWL(J) .LT. WLSCAL(1)) WLSCAL(1)=CWL(J)	002151
01153	395*	IF (CWL(J) .GT. WLSCAL(2)) WLSCAL(2)=CWL(J)	002157
01155	396*	508 CONTINUE	002167
01157	397*	REWIND 15	002167
01160	398*	NEXP=0	002172
01161	399*	IEOF=0	002173
01162	400*	REWIND 16	002174
01163	401*	510 READ (16,3004,END=530) AR,AN,AWI,AWO,AWRL	002200
01172	402*	IF (ABS(AR-RRHO) .GT. 0.005) GO TO 540	002212
01174	403*	NEXP=NEXP+1	002220
01175	404*	IF (AN .LT. XNSCAL(1)) XNSCAL(1)=AN	002223
01177	405*	IF (AN .GT. XNSCAL(2)) XNSCAL(2)=AN	002231
01201	406*	IF (AWI .LT. WSCAL(1) .AND. AWI .NE. 0.0) WSCAL(1)=AWI	002237
01203	407*	IF (AWO .LT. WSCAL(1) .AND. AWO .NE. 0.0) WSCAL(1)=AWO	002254
01205	408*	IF (AWI .GT. WSCAL(2) .AND. AWI .NE. 0.0) WSCAL(2)=AWI	002271
01207	409*	IF (AWO .GT. WSCAL(2) .AND. AWO .NE. 0.0) WSCAL(2)=AWO	002306
01211	410*	IF (AWRL .NE. 0.0) GO TO 520	002323
01213	411*	IF (NEXP .NE. 1) GO TO 518	002325
01215	412*	ELN(1)=0.0	002330
01216	413*	EWL(1)=0.0	002331
01217	414*	GO TO 525	002332
01220	415*	518 EWL(NEXP)=EWL(NEXP-1)	002334
01221	416*	ELN(NEXP)=ELN(NEXP-1)	002336
01222	417*	GO TO 525	002340
01223	418*	520 IF (AWRL .LT. WLSCAL(1)) WLSCAL(1)=AWRL	002342
01225	419*	IF (AWRL .GT. WLSCAL(2)) WLSCAL(2)=AWRL	002351
01227	420*	EWL(NEXP)=AWRL	002357
01230	421*	ELN(NEXP)=AN	002362
01231	422*	525 EN(NEXP)=AN	002365
01232	423*	EWO(NEXP)=AWO	002367
01233	424*	EWI(NEXP)=AWI	002371
01234	425*	GO TO 510	002373
01235	426*	530 IF (NEXP .NE. 0 .OR. IEOF .NE. 1) GO TO 550	002375
01237	427*	IEOF=1	002406
01240	428*	REWIND 16	002410
01241	429*	GO TO 510	002413
01242	430*	540 IF (NEXP .EQ. 0) GO TO 510	002415

01244	431*	550	CALL SCALE (XNSCAL,8.0,2,1)	002417
01245	432*		CALL SCALE (WLSCAL,8.0,2,1)	002424
01246	433*		CALL SCALE (WSCAL,8.0,2,1)	002432
01247	434*		CN(IC+1)=XNSCAL(3)	002440
01250	435*		CN(IC+2)=XNSCAL(4)	002443
01251	436*		CW(IC+1)=WSCAL(3)	002445
01252	437*		CW(IC+2)=WSCAL(4)	002447
01253	438*		CWL(IC+1)=WLSCAL(3)	002451
01254	439*		CWL(IC+2)=WLSCAL(4)	002453
01255	440*		IF (NEXP .EQ. 0) GO TO 570	002455
01257	441*		EN(NEXP+1)=CN(IC+1)	002457
01260	442*		EN(NEXP+2)=CN(IC+2)	002462
01261	443*	570	CALL AXIS (0.0,0.0,'NONDIMENSIONAL PRESSURE',-23,5.0,0.0,CN(IC+1),	002464
01261	444*	1	CN(IC+2))	002464
01262	445*		CALL AXIS (0.0,0.0,'NONDIMENSIONAL FLEXIBILITY',26,6.0,90.0,	002502
01262	446*	1	CW(IC+1),CW(IC+2))	002502
01263	447*		CALL SYMBOL (3.0,9.5,0.21,'RHO =' ,0.0,5)	002521
01264	448*		CALL NUMBER (4.5,9.5,0.21,RRHO,0.0,4)	002531
01265	449*		CALL NEWPEN (2)	002541
01266	450*		CALL PLOT (1.0,9.0,3)	002544
01267	451*		CALL PLOT (1.5,9.0,2)	002551
01270	452*		CALL SYMBOL (1.6,9.0,0.14,'CALC VAL',0.0,8)	002556
01271	453*		CALL FLINE (CN,CW,IC,1,0,0)	002566
01272	454*		IF (NEXP .EQ. 0) GO TO 600	002576
01274	455*		CALL SCALE (EWI,8.0,NEXP,1)	002600
01275	456*		IF (EWI(NEXP+1) .EQ. 0.0 .AND. EWI(NEXP+2) .EQ. 0.0) GO TO 580	002606
01277	457*		EWI(NEXP+1)=CW(IC+1)	002620
01300	458*		EWI(NEXP+2)=CW(IC+2)	002622
01301	459*		CALL NEWPEN (3)	002624
01302	460*		CALL LINE (EN,EWI,NEXP,1,-1,0)	002627
01303	461*		CALL SYMBOL (3.605,9.07,0.14,0.0,-1)	002637
01304	462*		CALL SYMBOL (3.8,9.0,0.14,'EXP IN',0.0,6)	002647
01305	463*	580	CALL SCALE (EWO,8.0,NEXP,1)	002660
01306	464*		IF (EWO(NEXP+1) .EQ. 0.0 .AND. EWO(NEXP+2) .EQ. 0.0) GO TO 600	002665
01310	465*		EWO(NEXP+1)=CW(IC+1)	002677
01311	466*		EWO(NEXP+2)=CW(IC+2)	002701
01312	467*		CALL NEWPEN (1)	002703
01313	468*		CALL SYMBOL (5.4,9.07,0.14,1,0.0,-1)	002706
01314	469*		CALL SYMBOL (5.595,9.0,0.14,'EXP OUT',0.0,7)	002716
01315	470*		CALL LINE (EN,EWO,NEXP,1,-1,2)	002726
01316	471*		GO TO 610	002736
01317	472*	600	CALL NEWPEN (1)	002740
01320	473*	610	CALL PLOT (10.0,0.0,-3)	002743
01321	474*		CALL AXIS (0.0,0.0,'NONDIMENSIONAL PRESSURE',-23,5.0,0.0,CN(IC+1),	002747
01321	475*	1	CN(IC+2))	002747
01322	476*		CALL AXIS (0.0,0.0,'NONDIMENSIONAL WRINKLING LOAD',29,6.0,90.0,	002766
01322	477*	1	CWL(IC+1),CWL(IC+2))	002766
01323	478*		CALL SYMBOL (3.0,9.5,0.21,'RHO =' ,0.0,5)	003005
01324	479*		CALL NUMBER (4.5,9.5,0.21,RRHO,0.0,4)	003015
01325	480*		CALL NEWPEN (2)	003025
01327	481*		CALL PLOT (1.0,9.0,3)	003030
01327	482*		CALL PLOT (1.5,9.0,2)	003035
01330	483*		CALL SYMBOL (1.6,9.0,0.14,'CALC VAL',0.0,8)	003042
01331	484*		CALL FLINE (CN,CWL,IC,1,0,0)	003052
01332	485*		IF (NEXP .EQ. 0) GO TO 650	003062
01334	486*		CALL SCALE (EWL,8.0,NEXP,1)	003064
01335	487*		IF (EWL(NEXP+1) .EQ. 0.0 .AND. EWL(NEXP+2) .EQ. 0.0) GO TO 650	003072

01337	488*	EWL(NEXP+1)=CWL(IC+1)	003104
01340	489*	EWL(NEXP+2)=CWL(IC+2)	003106
01341	490*	ELN(NEXP+1)=CN(IC+1)	003110
01342	491*	ELN(NEXP+2)=CN(IC+2)	003112
01343	492*	CALL NEWPEN (3)	003114
01344	493*	CALL LINE (ELN,EWL,NEXP,1,-1,5)	003117
01345	494*	CALL SYMBOL (3.605,9.07,0.14,14,0.0,-1)	003127
01346	495*	CALL SYMBOL (3.8,9.0,0.14,'EXP VAL',0.0,7)	003137
01347	496*	650 CALL NEWPEN (1)	003150
01350	497*	CALL PLOT (10.0,0.0,-3)	003152
01351	498*	GO TO 20	003157
01352	499*	960 PRINT 1016	003161
01354	500*	GO TO 40	003164
01355	501*	950 PRINT 1017	003166
01357	502*	GO TO 40	003171
01360	*DIAGNOSTIC*	CONTROL CAN NEVER REACH THE NEXT STATEMENT	
01360	503*	970 PRINT 1004	003172
01362	504*	GO TO 40	003176
01363	*DIAGNOSTIC*	CONTROL CAN NEVER REACH THE NEXT STATEMENT	
01363	505*	980 PRINT 1005	003177
01365	506*	GO TO 40	003203
01366	507*	990 PRINT 1006	003205
01370	508*	IF (IPL0T .EQ. 1) CALL EXIT	003210
01372	509*	CALL PLOT (4.0,0.0,999)	003215
01373	510*	CALL EXIT	003222
01374	511*	1001 FORMAT (3F10.0,10X,3F10.0)	003226
01375	512*	1002 FORMAT ('1',45X,'DEFORMATION OF PRESSURE STABILIZED ARCHES'//	003226
01375	513*	1 57X,'CONCENTRATED LOAD')	003226
01376	514*	1003 FORMAT (13X,'LOAD LOCATION =' ,F10.3)	003226
01377	515*	1004 FORMAT ('1 ROOTS DO NOT CONVERGE IN 100 ITERATIONS')	003226
0140	516*	1005 FORMAT ('1 INTEGRAL DOES NOT CONVERGE IN 100 ITERATIONS')	003226
01401	517*	1006 FORMAT ('1 END OF JOB')	003226
01402	518*	1011 FORMAT ('1',45X,'DEFORMATION OF PRESSURE STABILIZED ARCHES'//	003226
01402	519*	1 49X,'NORMAL UNIFORM LOAD,DIRECT SOLUTION')	003226
01403	520*	1013 FORMAT (//11X,'HALF SPAN ANGLE =' ,F10.3/14X'RADIUS RATIO =' ,F10.3/	003226
01403	521*	1 5X,'ELASTIC MODULUS RATIO =' ,F10.3/	003226
01403	522*	2 7X,'SHEAR MODULUS RATIO =' ,F10.3/	003226
01403	523*	3 8X,'PRESSURE PARAMETER =' ,F10.3)	003226
01404	524*	1014 FORMAT(///3X,'PSI',13X,'U',16X,'W',15X,'PHI',15X,'E(0)'	003226
01404	525*	112X,'E(PI)',11X,'N',17X,'M')	003226
01405	526*	1015 FORMAT (' ERROR IN LAMBDA-SQ ' ,6E18.8)	003226
01406	527*	1016 FORMAT (' OVERFLOW IN GJR ')	003226
01407	528*	1017 FORMAT (' SINGULARITY IN GJR ')	003226
01410	529*	1020 FORMAT (7F10.3,I5)	003226
01411	530*	2001 FORMAT (2F10.0,I5)	003226
01412	531*	3001 FORMAT(4I1)	003226
01413	532*	3002 FORMAT (7F10.0)	003226
01414	533*	3003 FORMAT (3E20.8)	003226
01415	534*	3004 FORMAT (5E15.6)	003226
01416	535*	END	003226

END OF COMPILATION:

2 DIAGNOSTICS.

@FOR,S TPF\$.ARCHRESULTS,R
FOR 00E3-11/03/77-16:01:36 (0,)

SUBROUTINE CALPAR ENTRY POINT 001046

STORAGE USED: CODE(1) 001075; DATA(0) 000222; BLANK COMMON(2) 001541

EXTERNAL REFERENCES (BLOCK, NAME)

0003 DCOS
0004 DSIN
0005 DCOSH
0006 DSINH
0007 NPRT\$
0010 NIO2\$
0011 NWDU\$
0012 NERR3\$

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

0001	000750	10L	0001	001025	100L	0000	000101	1001F	0000	000104	1002F	0001	000764	11L	
0001	000150	116G	0001	000174	125G	0001	000201	3L	0001	000203	4L	0001	000222	5L	
0001	000702	6L	0002	D	000007	ARR	0002	D	000053	BETA	0002	D	000175	BLAM2	
0000	D	000075	CINT	0000	D	000024	CS	0002	D	000111	CSA1	0002	D	000115	CSA3
0002	D	000161	D	0002	D	000225	DA	0000	D	000006	DELTH	0002	D	000005	E
0000	D	000050	EZERO	0000	D	000002	FL	0002	D	000075	G	0002	D	000125	H
0002	D	000123	HSA2	0002	I	001537	IBOUN	0002	I	000004	IC	0000	I	000015	ID
0000	000123	INJP\$		0002	I	001535	INTEG	0002	I	001536	ITYP	0000	I	000010	N
0000	D	000044	PA	0000	D	000046	PB	0000	D	000060	PC	0000	D	000062	PD
0000	D	000066	PF	0000	D	000070	PG	0000	D	000072	PH	0000	D	000040	PHI
0000	D	000013	PSIDEG	0000	D	000030	P1	0000	D	000022	P2	0000	D	000020	P3
0000	D	000056	QN	0000	D	000004	QNSTEP	0002	D	000000	RHO	0002	D	000002	SMN
0002	D	000113	SNA1	0002	D	000117	SNA3	0000	D	000034	SNP	0002	D	000715	SOL
0000	D	000042	W	0000	D	000077	WRL	0002	D	000145	XI	0000	D	000011	XN
0000	D	000000	XXTH	0002	D	000067	YLAM					0002	D	000153	XR

00101	1*	SUBROUTINE CALPAR (DEGREE,NSTEP,THETA,WFA,ISAV,IND)	000000
00103	2*	IMPLICIT DOUBLE PRECISION(A-H,O-Z)	000000
00104	3*	COMMON RHO,SMN,IC,E	000000
00105	4*	COMMON ARR(3,6),BETA(6),YLAM(3),G(6),CSA1,SNA1,CSA3,SNA3	000000
00106	5*	COMMON HCA2,HSA2,H(8)	000000
00107	6*	COMMON XI(3),XR(3),D(6),BLAM2(6),BLAM3(6)	000000
00110	7*	COMMON DA(12,13),SOL(200),INTEG,ITYP,IBOUN,IJUNC	000000
00111	8*	XXTH=.01745*THETA	000000
00112	9*	FL=.0326*RHO/(RHO-1.)*COS(XXTH)	000002
00112	10*	C FL CAN BE ENTERED AS A FUNCTION OF PSI	000002
00113	11*	QNSTEP=NSTEP	000016
00114	12*	DELTH=-2.0*DEGREE/QNSTEP	000024
00115	13*	DO 100 N=0,NSTEP	000150
00120	14*	XN=N	000150


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00121 15* PSIDEG= DEGREE+XN*DELTH 000156
00122 16* IF(ITYP.EQ.1)GO TO 5 000161
00124 17* DO 4 ID=1,6 000174
00127 18* IF(PSIDEG.GT.THETA)GO TO 3 000174
00131 19* D(ID)=DA(ID,13) 000175
00132 20* GO TO 4 000177
00133 21* 3 C(ID)=DA(ID+6,13) 000201
00134 22* 4 CONTINUE 000204
00136 23* PSI=(-DEGREE+PSIDEG)*0.01745 000204
00137 24* IF(PSIDEG.GT.THETA) PSI=(-DEGREE-PSIDEG)*0.01745 000210
00141 25* 5 CONTINUE 000222
00142 26* IF(ITYP.EQ.1) PSI=0.01745*PSIDEG 000222
00144 27* P3=PSI*YLAM(3) 000227
00145 28* P2=PSI*YLAM(2) 000232
00146 29* CS=COS(P3) 000235
00147 30* SN=SIN(P3) 000241
00150 31* P1=PSI*YLAM(1) 000245
00151 32* CSP=COSH(P1) 000250
00152 33* SNP=SINH(P1) 000254
00153 34* U=D(1)*BETA(1)*SNP+D(2)*BETA(1)*CSP 000260
00154 35* PHI=D(1)*BETA(2)*SNP+D(2)*BETA(2)*CSP 000270
00155 36* W=D(1)*CSP+D(2)*SNP 000300
00156 37* PA=BETA(1)*YLAM(1)-1.0 000306
00157 38* PB=BETA(2)*YLAM(1) 000310
00160 39* EZERO=(PA-PB)*CSP*D(1)+(PA-PB)*SNP*D(2) 000312
00161 40* EPI=(PA+PB)*CSP*D(1)+(PA+PB)*SNP*D(2) 000325
00162 41* QM=-RHO*H(3)*(PA+RHO*PB)*(D(1)*CSP+D(2)*SNP) 000336
00163 42* QN=(PA*RHO*H(1)+RHO*H(3)*PB)*(D(1)*CSP+D(2)*SNP) 000346
00164 43* U=U-D(3)*BETA(3)*CS+D(4)*BETA(3)*SN 000356
00164 44* 1 +D(5)*(BETA(5)*SN-BETA(3)*PSI*CS) 000356
00164 45* 2 +D(6)*(BETA(5)*CS+BETA(3)*PSI*SN) 000356
00165 46* PHI=PHI-D(3)*BETA(4)*CS+D(4)*BETA(4)*SN 000407
00165 47* 1 +D(5)*(BETA(6)*SN-BETA(4)*PSI*CS) 000407
00165 48* 2 +D(6)*(BETA(6)*CS+BETA(4)*PSI*SN) 000407
00166 49* W=W+D(3)*SN+D(4)*CS+D(5)*PSI*SN+D(6)*PSI*CS+G(1) 000440
00167 50* PA=BETA(3)-1.0-BETA(4) 000461
00170 51* PB=BETA(5)-BETA(3)-BETA(6)+BETA(4) 000463
00171 52* PC=BETA(3)-1.0+BETA(4) 000465
00172 53* PD=BETA(5)-BETA(3)+BETA(6)-BETA(4) 000467
00173 54* PE=(BETA(3)-1.0)*RHO*H(1)+RHO*H(3)*BETA(4) 000471
00174 55* PF=(BETA(5)-BETA(3))*RHO*H(1)+RHO*H(3)*(BETA(6)-BETA(4)) 000473
00175 56* PG=BETA(3)-1.0+RHO*BETA(4) 000475
00176 57* PH=BETA(5)-BETA(3)+RHO*(BETA(6)-BETA(4)) 000477
00177 58* EZERO=EZERO+D(3)*PA*SN+D(4)*PA*CS-G(1) 000501
00177 59* 1 +D(5)*(PB*CS+PA*PSI*SN)+D(6)*(-PB*SN+PA*PSI*CS) 000501
00200 60* EPI=EPI+D(3)*PC*SN+D(4)*PC*CS-G(1) 000533
00200 61* 1 +D(5)*(PD*CS+PC*PSI*SN)+D(6)*(-PD*SN+PC*PSI*CS) 000533
00201 62* EZERO=EZERO/(RHO+1.0) 000565
00202 63* EPI=EPI/(RHO-1.0) 000567
00203 64* QN=QN+D(3)*SN*PE+D(4)*PE*CS+D(5)*(PF*CS+PE*SN*PSI)+D(6)*(-PF 000571
00203 65* 1*SN+PE*CS*PSI) -RHO*H(1)*G(1) 000571
00204 66* QM=QM-RHO*H(3)*(D(3)*PG*SN+D(4)*PG*CS+D(5)*(PH*CS+PG*SN*PSI) 000621
00204 67* 1+D(6)*(-PH*SN+PG*CS*PSI)-G(1)) 000621
00205 68* QN=QN/RHO 000653
00206 69* QM=QM/RHO 000655
00207 70* IF((PSIDEG.LE.THETA).OR.(ITYP.EQ.1)) GO TO 6 000660
00211 71* U=-U 000675

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00212	72*	PHI=-PHI	000677
00213	73*	6 CONTINUE	000702
00214	74*	IF (INTEG.EQ.0) GO TO 10	000702
00216	75*	NI=8*N	000703
00217	76*	SOL(NI+1)=PSIDEG	000707
00220	77*	CINT=WFA*FL	000711
00221	78*	SOL(NI+2)=SOL(NI+2)+U*CINT	000713
00222	79*	SOL(NI+3)=SOL(NI+3)+W*CINT	000716
00223	80*	SOL(NI+4)=SOL(NI+4)+PHI*CINT	000722
00224	81*	SOL(NI+5)=SOL(NI+5)+EZERO*CINT	000726
00225	82*	SOL(NI+6)=SOL(NI+6)+EPI*CINT	000732
00226	83*	SOL(NI+7)=SOL(NI+7)+QN*CINT	000736
00227	84*	SOL(NI+8)=SOL(NI+8)+QM*CINT	000742
00230	85*	GO TO 11	000746
00231	86*	10 CONTINUE	000750
00232	87*	PRINT 1001, PSIDEG,U,W,PHI,EZERO,EPI,QN,QM	000750
00244	88*	11 CONTINUE	000764
00245	89*	IF (ISAV.EQ. 0) GO TO 100	000764
00247	90*	IF (ABS(PSIDEG) .GT. 0.5 .OR. IND .EQ. 1) GO TO 100	000765
00251	91*	WRL=ABS(SMN/EZERO)/E	001002
00252	92*	WRITE (15,1002) SMN,W,WRL	001007
00257	93*	IC=IC+1	001017
00260	94*	IND=1	001022
00261	95*	100 CONTINUE	001026
00263	96*	RETURN	001026
00264	97*	1001 FORMAT (/F10.3,1P7E17.8)	001074
00265	98*	1002 FORMAT (3E20.8)	001074
00266	99*	END	001074

END OF COMPILATION: NO DIAGNOSTICS.

@FOR,S TPF\$.BOUNDARYARCH,B
FOR 00E3-11/03/77-16:02:55 (0,)

SUBROUTINE CALCA ENTRY POINT 000250

STORAGE USED: CODE(1) 000255; DATA(0) 000034; BLANK COMMON(2) 001541

EXTERNAL REFERENCES (BLOCK, NAME)

0003 DCOS
0004 DSIN
0005 DSINH
0006 DCOSH
0007 NERR3\$

STORAGE ASSIGNMENT (BLOCK, TYPE, RELATIVE LOCATION, NAME)

0001	000056	10L	0001	000073	11L	0001	000166	20L	0001	000226	21L	0000	D	000000	ANGLE
0002	D	000007	ARR	0000	D	000004	A1	0000	D	000002	A3	0002	D	000053	BETA
0002	D	000211	BLAM3	0000	D	000010	CON1	0000	D	000012	CON2	0000	D	000006	CO1
0002	D	000115	CSA3	0002	D	000161	D	0002	D	000225	DA	0002	D	000005	E
0002	D	000125	H	0002	D	000121	HCA2	0002	D	000123	HSA2	0002	I	001537	IBOUN
0002	I	001540	IJUNC	0000	D	000020	INJP\$	0002	D	001535	INTEG	0002	D	001536	ITYP
0002	D	000113	SNA1	0002	D	000117	SNA3	0002	D	000715	SOL	0002	D	000145	XI
0002	D	000153	XR	0002	D	000067	YLAM					0002	D	000002	XN

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00101	1*	SUBROUTINE CALCA (DEGREE)	000000
00103	2*	IMPLICIT DOUBLE PRECISION(A-H,O-Z)	000000
00104	3*	COMMON RHO,XN,IC,E	000000
00105	4*	COMMON ARR(3,6),BETA(6),YLAM(3),G(6),CSA1,SNA1,CSA3,SNA3	000000
00106	5*	COMMON HCA2,HSA2,H(8)	000000
00107	6*	COMMON XI(3),XR(3),D(6),BLAM2(6),BLAM3(6)	000000
00110	7*	COMMON DA(12,13),SOL(200),INTEG,ITYP,IBOUN,IJUNC	000000
00111	8*	ANGLE=0.01745*DEGREE	000000
00112	9*	A3=YLAM(3)*ANGLE	000002
00113	10*	CSA3=COS(A3)	000004
00114	11*	SNA3=SIN(A3)	000010
00115	12*	A1=YLAM(1)*ANGLE	000014
00116	13*	SNA1=SINH(A1)	000017
00117	14*	CSA1=COSH(A1)	000023
00120	15*	ARR(1,1)=BETA(1)*SNA1	000027
00121	16*	ARR(1,2)=BETA(1)*CSA1	000032
00122	17*	IF((IBOUN.EQ.1).AND.(IJUNC.EQ.0)) GO TO 10	000034
00124	18*	ARR(2,1)=BETA(2)*SNA1	000046
00125	19*	ARR(2,2)=BETA(2)*CSA1	000051
00126	20*	GO TO 11	000054
00127	21*	10 CO1=BETA(1)*YLAM(1)-1.0+RHO*BETA(2)*YLAM(1)	000056
00130	22*	ARR(2,1)=CO1*CSA1	000065
00131	23*	ARR(2,2)=CO1*SNA1	000067
00132	24*	11 CONTINUE	000073

00133	25*	ARR(3,1)=CSA1	000073
00134	26*	ARR(3,2)=SNA1	000074
00135	27*	ARR(1,3)=-BETA(3)*CSA3	000076
00136	28*	ARR(1,4)=BETA(3)*SNA3	000102
00137	29*	ARR(1,5)=BETA(5)*SNA3-BETA(3)*ANGLE*CSA3	000105
00140	30*	ARR(1,6)=BETA(5)*CSA3+BETA(3)*ANGLE*SNA3	000116
00141	31*	IF((IBOUN.EQ.1).AND.(IJUNC.EQ.0)) GO TO 20	000124
00143	32*	ARR(2,3)=-BETA(4)*CSA3	000136
00144	33*	ARR(2,4)=BETA(4)*SNA3	000142
00145	34*	ARR(2,5)=BETA(6)*SNA3-BETA(4)*ANGLE*CSA3	000145
00146	35*	ARR(2,6)=BETA(6)*CSA3+BETA(4)*ANGLE*SNA3	000156
00147	36*	GO TO 21	000164
00150	37*	20 CON1=BETA(3)-1.0+RHO*BETA(4)	000166
00151	38*	CON2=BETA(5)-BETA(3)+RHO*(BETA(6)-BETA(4))	000173
00152	39*	ARR(2,3)=CON1*SNA3	000202
00153	40*	ARR(2,4)=CON1*CSA3	000204
00154	41*	ARR(2,5)=CON2*CSA3+CON1*ANGLE*SNA3	000207
00155	42*	ARR(2,6)=-CON2*SNA3+CON1*ANGLE*CSA3	000216
00156	43*	21 CONTINUE	000226
00157	44*	ARR(3,3)=SNA3	000226
00160	45*	ARR(3,4)=CSA3	000227
00161	46*	ARR(3,5)=ANGLE*SNA3	000231
00162	47*	ARR(3,6)=ANGLE*CSA3	000233
00163	48*	RETURN	000235
00164	49*	END	000254

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END OF COMPILATION: NO DIAGNOSTICS.

@MAP.IN A.B
MAP2BR1 RL71-3 11/03/77 16:03:39 (.0)
END MAP

@ASG.T 20.,6C9,0928W . PLOT TAPE WITH APPROPRIATE NO.

@XQT B

DEFORMATION OF PRESSURE STABILIZED ARCHES

CONCENTRATED LOAD
(NORMAL)
SIMPLY SUPPORTED ENDS

FINITE ELEMENT CHECK CASE

C= .0000*N+ .0500
E= .000*N+1.0000

HALF SPAN ANGLE = 90.000
RADIUS RATIO = 20.000
ELASTIC MODULUS RATIO = 1.000
SHEAR MODULUS RATIO = .050
PRESSURE PARAMETER = .057
LOAD LOCATION = .000

PSI	U	W	PHI	E(0)	E(PI)	N	M
-90.000	-2.03287907-20	0.00000000	1.58475030-04	-1.65779550-05	-1.65779550-05	-3.31559099-05	4.23516474-23
-72.000	-3.25139188-04	-1.20542675-03	8.97332786-05	8.00368673-07	-3.95025582-05	-3.76939858-05	2.01388530-05
-54.000	-8.60732065-04	-1.24301006-03	-5.05428694-05	4.60105860-06	-4.43697882-05	-3.85436923-05	2.44701009-05
-36.000	-1.20240372-03	-7.94067007-06	-1.81650596-04	-1.15403683-06	-3.53225971-05	-3.56218854-05	1.70735891-05
-18.000	-9.79840769-04	2.18096021-03	-2.18952714-04	-2.19261753-05	-6.91271813-06	-2.92144648-05	-7.50203102-06
.000	4.74338450-20	4.50843540-03	-2.26089141-20	-7.90181502-05	6.26127394-05	-1.99483988-05	-7.07711297-05
18.000	9.79840769-04	2.18096021-03	2.18952714-04	-2.19261753-05	-6.91271813-06	-2.92144648-05	-7.50203102-06
36.000	1.20240372-03	-7.94067007-06	1.81650596-04	-1.15403683-06	-3.53225971-05	-3.56218854-05	1.70735891-05
54.000	8.60732065-04	-1.24301006-03	5.05428694-05	4.60105860-06	-4.43697882-05	-3.85436923-05	2.44701009-05
72.000	3.25139188-04	-1.20542675-03	-8.97332786-05	8.00368673-07	-3.95025582-05	-3.76939858-05	2.01388530-05
90.000	0.00000000	0.00000000	-1.58475030-04	-1.65779550-05	-1.65779550-05	-3.31559099-05	8.47032947-23

DEFORMATION OF PRESSURE STABILIZED ARCHES

CONCENTRATED LOAD
(NORMAL)
SIMPLY SUPPORTED ENDS

FINITE ELEMENT CHECK CASE

C= .0000*N+ .0500
E= .000*N+1.0000

HALF SPAN ANGLE = 90.000
RADIUS RATIO = 20.000
ELASTIC MODULUS RATIO = 1.000
SHEAR MODULUS RATIO = .050
PRESSURE PARAMETER = .067
LOAD LOCATION = .000

PSI	U	W	PHI	E(0)	E(PI)	N	M
-90.000	-1.01643954-20	0.00000000	1.36283977-04	-1.65779255-05	-1.65779255-05	-3.31558510-05	-1.48230766-22
-72.000	-2.96422217-04	-1.03989002-03	7.63284971-05	-1.55356452-06	-3.69647999-05	-3.76325295-05	1.76945378-05
-54.000	-7.72215360-04	-1.05442386-03	-4.59015665-05	1.69830150-06	-4.11982382-05	-3.84.68521-05	2.14348479-05
-36.000	-1.07282052-03	3.92254658-05	-1.60391672-04	-3.00068467-06	-3.32162718-05	-3.54610941-05	1.50983394-05
-18.000	-8.73666662-04	1.97038106-03	-1.93859112-04	-2.06971344-05	-8.01096887-06	-2.90254559-05	-6.33911337-06
.000	-2.71050543-20	4.05357628-03	-2.41201731-20	-7.16352752-05	5.50548433-05	-1.97496669-05	-6.33054190-05
18.000	8.73666662-04	1.97038106-03	1.93859342-04	-2.06971344-05	-8.01096887-06	-2.90254559-05	-6.33911337-06
36.000	1.07282052-03	3.92254658-05	1.60391672-04	-3.00068467-06	-3.32162718-05	-3.54610941-05	1.50983394-05
54.000	7.72215360-04	-1.05442386-03	4.59015665-05	1.69830150-06	-4.11982382-05	-3.84268521-05	2.14348479-05
72.000	2.96422217-04	-1.03989002-03	-7.63284971-05	-1.55356452-06	-3.69647999-05	-3.76325295-05	1.76945378-05
90.000	0.00000000	0.00000000	-1.36283977-04	-1.65779255-05	-1.65779255-05	-3.31558510-05	1.05879118-22

DEFORMATION OF PRESSURE STABILIZED ARCHES

CONCENTRATED LOAD
(NORMAL)
SIMPLY SUPPORTED ENDS

FINITE ELEMENT CHECK CASE

C= .0000*N+.0500
E= .000*N+1.0000

HALF SPAN ANGLE = 90.000
RADIUS RATIO = 30.000
ELASTIC MODULUS RATIO = 1.000
SHEAR MODULUS RATIO = .050
PRESSURE PARAMETER = .057
LOAD LOCATION = .000

PSI	U	W	PHI	E(0)	E(PI)	N	M
-90.000	1.62630326-19	4.65868121-21	2.19743349-04	-1.65779550-05	-1.65779550-05	-3.31559099-05	1.41172158-22
-72.000	-5.26901584-04	-2.02705377-03	1.23351702-04	-1.57546747-06	-3.67041428-05	-3.76939696-05	1.75594560-05
-54.000	-1.41243755-03	-2.11982231-03	-5.65979756-05	9.73197916-07	-4.02033255-05	-3.85436615-05	2.05825396-05
-36.000	-1.98626875-03	-9.85614664-05	-2.30614024-04	-1.81803947-06	-3.43460883-05	-3.56218429-05	1.62595041-05
-18.000	-1.62621295-03	3.55609708-03	-3.08653672-04	-1.73204319-05	-1.18019832-05	-2.92144149-05	-2.75845749-06
0.000	2.57498016-19	7.38875194-03	-8.99441353-19	-8.85435716-05	7.12593476-05	-1.99483463-05	-7.98792524-05
18.000	1.62621295-03	3.55609708-03	3.08653672-04	-1.73204319-05	-1.18019832-05	-2.92144149-05	-2.75845749-06
36.000	1.98626875-03	-9.85614664-05	2.30614024-04	-1.81803947-06	-3.43460883-05	-3.56218429-05	1.62595041-05
54.000	1.41243755-03	-2.11982231-03	5.65979756-05	9.73197916-07	-4.02033255-05	-3.85436615-05	2.05825396-05
72.000	5.26901584-04	-2.02705377-03	-1.23351702-04	-1.57546747-06	-3.67041428-05	-3.76939696-05	1.75594560-05
90.000	0.00000000	0.00000000	-2.19743349-04	-1.65779550-05	-1.65779550-05	-3.31559099-05	2.82344316-23

DEFORMATION OF PRESSURE STABILIZED ARCHES

CONCENTRATED LOAD
(NORMAL)
SIMPLY SUPPORTED ENDS

FINITE ELEMENT CHECK CASE

C= .0000*N+ .0500
E= .000*N+1.0000

HALF SPAN ANGLE = 90.000
RADIUS RATIO = 30.000
ELASTIC MODULUS RATIO = 1.000
SHEAR MODULUS RATIO = .050
PRESSURE PARAMETER = .067
LOAD LOCATION = .000

PSI	U	W	PHI	E(0)	E(PI)	N	M
-90.000	-2.43945489-19	2.54109884-21	1.87444223-04	-1.65779255-05	-1.65779255-05	-3.31558510-05	-3.10578747-22
-72.000	-4.74621036-04	-1.72613997-03	1.04025766-04	-3.83076676-06	-3.43098749-05	-3.76325154-05	1.52353185-05
-54.000	-1.25093116-03	-1.77526265-03	-5.06792375-05	-1.74853405-06	-3.72704883-05	-3.84268252-05	1.77560408-05
-36.000	-1.74888422-03	-8.60272085-06	-2.00449914-04	-3.80151175-06	-3.21318488-05	-3.54610570-05	1.41612316-05
-18.000	-1.43089193-03	3.17093732-03	-2.69625203-04	-1.65029362-05	-1.24549916-05	-2.90254123-05	-2.02340980-06
.000	-1.34847645-18	6.56372347-03	2.65411643-18	-7.97383034-05	6.23576056-05	-1.97496211-05	-7.10282080-05
18.000	1.43089193-03	3.17093732-03	2.69625203-04	-1.65029362-05	-1.24549916-05	-2.90254123-05	-2.02340980-06
36.000	1.74888422-03	-8.60272085-06	2.00449914-04	-3.80151175-06	-3.21318488-05	-3.54610570-05	1.41612316-05
54.000	1.25093116-03	-1.77526265-03	5.06792375-05	-1.74853405-06	-3.72704883-05	-3.84268252-05	1.77560408-05
72.000	4.74621036-04	-1.72613997-03	-1.04025766-04	-3.83076676-06	-3.43098749-05	-3.76325154-05	1.52353185-05
90.000	-2.03287907-20	0.00000000	-1.87444223-04	-1.65779255-05	-1.65779255-05	-3.31558510-05	2.82344316-23

SYMBOLS

A_i, B_i, C_i	constants of integration
b	force vector
a	cross-section radius
C_{ij}	material stiffness parameters
C	vector whose elements are the integration constants C_i
c, d	nondimensional material stiffnesses
E	nondimensional form of e and the energy density function
e	axial strain
F_i	applied surface loading
F_a	applied force
f_i	generalized forces associated with F_i
\bar{f}_i	nondimensional form of f_i
G_i	applied line load intensity
g_i	generalized forces associated with G_i
\bar{g}_i	nondimensional form of g_i
g	magnitude of concentrated load
H_i	coefficients of the governing differential equations
J_i	constants used in writing the boundary condition matrix
L_i	constants defined in Appendix E
l_g	gage length
M_x, M_y, M_z	nondimensional form of m_x, m_y, m_z
m_x, m_y, m_z	internal moments

N_{ij}	stress resultants
N°_{ij}	stress resultants due to pressurization
N'_{ij}	first order stress resultants due to applied load
N''_{ij}	second order stress resultants due to applied load
n	nondimensional pressure parameter
P	pressure
Q_y, Q_z	nondimensional form of q_y, q_z
q_y, q_z	internal shear forces
R_1, R_2	principal radii of curvature
R	arch radius
S	coefficient matrix
s_{ij}	elements of matrix
s	arch length
T	nondimensional form of t
t	internal axial force
u_i	displacements due to applied load
U, V, W	cross-section displacements
U, V, W	nondimensional form of U, V, W
v_i	general displacements
w_i	displacements due to pressurization
Z, Z_i	constants resulting from integration w.r.t. θ_1
α	half span angle of arch

α_2	parameter defining arch length
β_i	constants used in the relocations among A_i , B_i , and C_i
Γ_Y, Γ_Z	nondimensional form of γ_Y, γ_Z
γ_Y, γ_Z	transverse shear strains
γ	nondimensional flexibility
ϵ_{ij}	strain components
ϵ^o_{ij}	strain components due to pressurization
ϵ'_{ij}	first order strain components due to applied load
ϵ''_{ij}	second order strain components due to applied load
θ_1, θ_2	coordinates locating position on arch
$\bar{\theta}_2$	location of applied line load
$\hat{\theta}_1$	location of concentrated load
K_X, K_Y, K_Z	nondimensional forms of $\kappa_X, \kappa_Y, \kappa_Z$
$\kappa_X, \kappa_Y, \kappa_Z$	curvatures
λ	parameter specifying the solution of the characteristic equation
ρ	radius ratio
ϕ_X, ϕ_Y, ϕ_Z	cross-section rotations
ω	angle defining region over which load acts and characteristic number

Subscript w denotes value parameter at wrinkling

()' denotes differentiation w.r.t. θ_2 except for ϵ_{ij} and N_{ij}

δ denotes variation